

# Duality in Nondifferentiable Multiobjective Programming with Cone Constraints

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## 1 Introduction

In study of duality under generalized convexity, Mond and Weir [5] proposed a number of different duals for nonlinear programming problems with nonnegative variables and established duality theorems under appropriate pseudo-convexity/quasi-convexity assumptions. Taking motivation from Bazaraa and Goode [1] and Kuk and Kim [3], Nanda and Das [6] attempted to extend the results of Mond and Weir [5] to cone domains with appropriate pseudo-invexity and quasi-invexity assumptions on objective and constraint functions. However, certain shortcomings were pointed out in the work of Nanda and Das [6] and appropriate modifications were suggested for studying duality under pseudo-invexity assumptions in Chandra and Abha [2]. Recently, Yang et al. [7] established various converse duality results for nonlinear programming with cone constraints and its four dual models introduced by Chandra and Abha [2].

In this paper, we construct nondifferentiable multiobjective dual problems with cone constraints over arbitrary closed convex cones, which are Mond-Weir type and Wolfe type. And we establish weak, strong duality theorems for a weakly efficient solution by using suitable generalized invexity conditions.

## 2 Preliminaries

Let  $\mathbb{R}^n$  be the  $n$ -dimensional Euclidean space and let  $\mathbb{R}_+^n$  be its non-negative orthant. The following convention for inequalities will be used in this talk.

If  $x, u \in \mathbb{R}^n$ , then

$$\begin{aligned} x < u &\iff u - x \in \text{int}\mathbb{R}_+^n ; \\ x \leq u &\iff u - x \in \mathbb{R}_+^n ; \\ x \leq u &\iff u - x \in \mathbb{R}_+^n \setminus \{0\} ; \\ x \not< u &\text{ is the negation of } x < u . \end{aligned}$$

**Definition 2.1** A nonempty set  $C$  in  $\mathbb{R}^n$  is said to be a cone with vertex zero, if  $x \in C$  implies that  $\lambda x \in C$  for all  $\lambda \geq 0$ . If, in addition,  $C$  is convex, then  $C$  is called a convex cone.

**Definition 2.2** The polar cone  $C^*$  of  $C$  is defined by

$$C^* = \{z \in \mathbb{R}^n \mid x^T z \leq 0 \text{ for all } x \in C\}.$$

**Definition 2.3** Let  $S \subseteq \mathbb{R}^n$  be open and  $f : S \rightarrow \mathbb{R}$  be a differentiable function.

(1) The function  $f$  is said to be invex at  $u \in S$ , if there exists a function  $\eta : S \times S \rightarrow \mathbb{R}^n$  such that

$$f(x) - f(u) \geq \eta(x, u)^T \nabla f(u).$$

(2) The function  $f$  is said to be pseudoinvex at  $u \in S$ , if there exists a function  $\eta : S \times S \rightarrow \mathbb{R}^n$  such that

$$\eta(x, u)^T \nabla f(u) \geq 0 \Rightarrow f(x) - f(u) \geq 0.$$

(3) The function  $f$  is said to be *quasiconvex* at  $u \in S$ , if there exists a function  $\eta : S \times S \rightarrow \mathbb{R}^n$  such that

$$f(x) - f(u) \leq 0 \Rightarrow \eta(x, u)^T \nabla f(u) \leq 0.$$

**Definition 2.4** [4] The support function  $s(x|B)$ , being convex and everywhere finite, has a subdifferential, that is, there exists  $z$  such that

$$s(y|B) \geq s(x|B) + z^T(y - x) \text{ for all } y \in B.$$

Equivalently,

$$z^T x = s(x|B).$$

The subdifferential of  $s(x|B)$  is given by

$$\partial s(x|B) := \{z \in B : z^T x = s(x|B)\}.$$

For any set  $S \subset \mathbb{R}^n$ , the normal cone to  $S$  at a point  $x \in S$  is defined by

$$N_S(x) := \{y \in \mathbb{R}^n : y^T(z - x) \leq 0 \text{ for all } z \in S\}.$$

It is readily verified that for a compact convex set  $B$ ,  $y$  is in  $N_B(x)$  if and only if  $s(y|B) = x^T y$ , or equivalently,  $x$  is in the subdifferential of  $s$  at  $y$ .

### 3 Mond-Weir Type Duality

We consider the following multiobjective programming problem:

$$\begin{aligned}
 \text{(MP)} \quad & \text{Minimize} && f(x) + s(x|D) \\
 & && = (f_1(x) + x^T w_1, \dots, f_k(x) + x^T w_k) \\
 & \text{subject to} && -g(x) \in C_2^*, \quad x \in C_1,
 \end{aligned}$$

and its Mond Weir type dual programming problem (MWD):

(MWD)

$$\begin{aligned}
 & \text{Maximize} && f(u) + u^T w \\
 & \text{subject to} && \lambda^T [\nabla f(u) + w] = \nabla y^T g(u), \tag{1}
 \end{aligned}$$

$$g(u) \in C_2^*, \tag{2}$$

$$w_i \in D_i, \quad i = 1, \dots, k,$$

$$y \in C_2, \quad \lambda \geq 0, \quad \lambda^T e = 1,$$

where

(i)  $f : S \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^k$  and  $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$  are differentiable functions,

(ii)  $C_1$  and  $C_2$  are closed convex cones in  $\mathbb{R}^n$  and  $\mathbb{R}^m$  with nonempty interiors, respectively,

(iii)  $C_1^*$  and  $C_2^*$  are polar cones of  $C_1$  and  $C_2$ , respectively,

(iv)  $e = (1, \dots, 1)^T$  is vector in  $\mathbb{R}^k$ ,

(v)  $w_i (i = 1, \dots, k)$  is vector in  $\mathbb{R}^n$  and  $D_i (i = 1, \dots, k)$  is compact convex set in  $\mathbb{R}^n$ , respectively,

(vi)  $u^T w = (u^T w_1, \dots, u^T w_k)^T$ .

Now we establish the duality theorems of (MP) and (MWD).

**Theorem 3.1 (Weak Duality)** *Let  $x$  and  $(u, y, \lambda, w)$  be feasible solutions of (MP) and (MWD), respectively. Assume that*

(a)  $f_i(\cdot) + (\cdot)^T w_i, i = 1, \dots, k$ , is invex at  $u$  and  $-y^T g(\cdot)$  is invex at  $u$  or  
(b)  $\lambda^T [f(\cdot) + (\cdot)^T w]$  is pseudoinvex at  $u$  and  $-y^T g(\cdot)$  is quasinvex at  $u$ .

Then

$$f(x) + s(x|D) \not\leq f(u) + u^T w.$$

*Proof.* Assume to the contrary that

$$f(x) + s(x|D) < f(u) + u^T w.$$

Since  $\lambda \geq 0$ , we have

$$\lambda^T [f(x) + s(x|D)] < \lambda^T [f(u) + u^T w]. \quad (3)$$

(a) From the assumption (a), we get

$$\lambda^T [f(x) + x^T w] - \lambda^T [f(u) + u^T w] \geq \eta(x, u)^T [\lambda^T (\nabla f(u) + w)] \quad (4)$$

and

$$-y^T g(x) + y^T g(u) \geq -\eta(x, u)^T \nabla y^T g(u). \quad (5)$$

Adding (4) and (5), we obtain

$$\begin{aligned} & \lambda^T [f(x) + x^T w] - y^T g(x) - \lambda^T [f(u) + u^T w] + y^T g(u) \\ & \geq \eta(x, u)^T [\lambda^T (\nabla f(u) + w) - \nabla y^T g(u)]. \end{aligned}$$

Also, by  $-y^T g(x) \leq 0, y^T g(u) \leq 0$  and the dual constraint (1), it follows that

$$\lambda^T [f(x) + x^T w] - \lambda^T [f(u) + u^T w] \geq 0.$$

Using the fact that  $s(x|D) \geq x^T w$ , the above inequality becomes

$$\lambda^T [f(x) + s(x|D)] - \lambda^T [f(u) + u^T w] \geq 0,$$

which contradicts (3). Hence,

$$f(x) + s(x|D) \not\leq f(u) + u^T w.$$

(b) From the assumption (b), (3) implies that

$$\eta(x, u)^T [\lambda^T (\nabla f(u) + w)] < 0.$$

From the dual constraint (1), it yields

$$\eta(x, u)^T \nabla y^T g(u) < 0.$$

By the quasiinvexity of  $-y^T g(\cdot)$ , the above inequality becomes

$$-y^T g(x) > -y^T g(u). \quad (6)$$

Since  $-y^T g(x) \leq 0$  and  $y^T g(u) \leq 0$ , we get  $-y^T g(x) \leq -y^T g(u)$ , which contradicts (6). Thus,

$$f(x) + s(x|D) \not\leq f(u) + u^T w.$$

□

By using the necessary optimality condition due to Bazaraa and Goode [1], we can obtain the following lemma.

**Lemma 3.1** *If  $\bar{x}$  is a weakly efficient solution of (MP) at which constraint qualification be satisfied. Then there exist  $\bar{w}_i \in D_i (i = 1, \dots, k)$ ,  $\bar{\lambda} \geq 0$  and  $\bar{y} \in C_2$  with  $(\bar{\lambda}, \bar{y}) \neq 0$  such that*

$$[\bar{\lambda}^T (\nabla f(\bar{x}) + \bar{w}) - \bar{y}^T \nabla g(\bar{x})]^T (x - \bar{x}) \geq 0, \quad \text{for all } x \in C_1,$$

$$\bar{y}^T g(\bar{x}) = 0,$$

$$\bar{w}_i \in D_i, \quad s(\bar{x}|D_i) = \bar{x}^T \bar{w}_i, \quad i = 1, \dots, k.$$

**Theorem 3.2 (Strong Duality)** *If  $\bar{x}$  is a weakly efficient solution of (MP) at which constraint qualification be satisfied. Then there exist  $\bar{\lambda} \geq 0$ ,  $\bar{y} \in C_2$  and  $\bar{w}_i \in D_i (i = 1, \dots, k)$  such that  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is feasible for (MWD) and the corresponding values of (MP) and (MWD) are equal. If the assumption of Theorem 3.1 are satisfied, then  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is weakly efficient for (MWD).*

*Proof.* Since  $\bar{x}$  is a weakly efficient solution of (MP), then there exist  $w_i \in D_i, i = 1, \dots, k, \bar{\lambda} \geq 0$  and  $\bar{y} \in C_2$  with  $(\bar{\lambda}, \bar{y}) \neq 0$  such that

$$[\bar{\lambda}^T (\nabla f(\bar{x}) + w) - \bar{y}^T \nabla g(\bar{x})]^T (x - \bar{x}) \geq 0, \quad \text{for all } x \in C_1, \quad (7)$$

$$\bar{y}^T g(\bar{x}) = 0, \quad (8)$$

$$w_i \in D_i, \quad s(\bar{x}|D_i) = \bar{x}^T w_i, \quad i = 1, \dots, k. \quad (9)$$

Since  $x \in C_1, \bar{x} \in C_1$  and  $C_1$  is a closed convex cone, we have  $x + \bar{x} \in C_1$  and thus the inequality (7) implies

$$[\bar{\lambda}^T (\nabla f(\bar{x}) + w) - \bar{y}^T \nabla g(\bar{x})]^T x \geq 0, \quad \text{for all } x \in C_1,$$

i.e.,

$$\bar{\lambda}^T (\nabla f(\bar{x}) + w) - \bar{y}^T \nabla g(\bar{x}) = 0.$$

And (8) implies  $\bar{y}^T g(\bar{x}) \leq 0$ , then  $g(\bar{x}) \in C_2^*$ . Taking  $\bar{w}_i = w_i \in D_i, i = 1, \dots, k$ , we find that  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is feasible for (MWD) and corresponding values of (MP) and (MWD) are equal, by (9). If the assumptions of Theorem 3.1 are satisfied, then  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is a weakly efficient solution of (MWD).  $\square$

## 4 Wolfe Type Duality

We propose the following Wolfe Type multiobjective dual problem to the primal problem (MP):

(WD)

$$\begin{aligned}
 & \text{Maximize} && f(u) + u^T w - y^T g(u)e \\
 & \text{subject to} && \lambda^T [\nabla f(u) + w] = \nabla y^T g(u), \\
 & && w_i \in D_i, \quad i = 1, \dots, k, \\
 & && y \in C_2, \quad \lambda \geq 0, \quad \lambda^T e = 1,
 \end{aligned} \tag{10}$$

where

- (i)  $f : S \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^k$  and  $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$  are differentiable functions,
- (ii)  $C_1$  and  $C_2$  are closed convex cones in  $\mathbb{R}^n$  and  $\mathbb{R}^m$  with nonempty interiors, respectively,
- (iii)  $C_1^*$  and  $C_2^*$  are polar cones of  $C_1$  and  $C_2$ , respectively,
- (iv)  $e = (1, \dots, 1)^T$  is vector in  $\mathbb{R}^k$ ,
- (v)  $w_i (i = 1, \dots, k)$  is vector in  $\mathbb{R}^n$  and  $D_i (i = 1, \dots, k)$  is compact convex set in  $\mathbb{R}^n$ , respectively,
- (vi)  $u^T w = (u^T w_1, \dots, u^T w_k)^T$ .

Now we establish the duality theorems of (MP) and (WD).



**Theorem 4.1 (Weak Duality)** *Let  $x$  and  $(u, y, \lambda, w)$  be feasible solutions of (MP) and (WD), respectively. Assume that*

- (a)  $f_i(\cdot) + (\cdot)^T w_i, i = 1, \dots, k$ , is invex at  $u$  and  $-y^T g(\cdot)$  is invex at  $u$  or  
 (b)  $\lambda^T [f(\cdot) + (\cdot)^T w] - y^T g(\cdot)$  is pseudoinvex at  $u$ .

Then

$$f(x) + s(x|D) \not\leq f(u) + u^T w - y^T g(u)e.$$

*Proof.* Assume to the contrary that

$$f(x) + s(x|D) < f(u) + u^T w - y^T g(u)e.$$

Since  $\lambda \geq 0$ , we have

$$\lambda^T [f(x) + s(x|D)] < \lambda^T [f(u) + u^T w - y^T g(u)e]. \quad (11)$$

(a) By the assumption (a), we obtain

$$\lambda^T [f(x) + x^T w] - \lambda^T [f(u) + u^T w] \geq \eta(x, u)^T [\lambda^T (\nabla f(u) + w)]$$

and

$$-y^T g(x) + y^T g(u) \geq -\eta(x, u)^T \nabla y^T g(u).$$

So, we get

$$\begin{aligned} & \lambda^T [f(x) + x^T w] - y^T g(x) - \lambda^T [f(u) + u^T w] + y^T g(u) \\ & \geq \eta(x, u)^T [\lambda^T (\nabla f(u) + w) - \nabla y^T g(u)]. \end{aligned}$$

Also, by  $-y^T g(x) \leq 0$  and the dual constraint (10), it follows that

$$\lambda^T [f(x) + x^T w] - \lambda^T [f(u) + u^T w] + y^T g(u) \geq 0.$$

Using the fact that  $s(x|D) \geq x^T w$ , the above inequality becomes

$$\lambda^T [f(x) + s(x|D)] - \lambda^T [f(u) + u^T w] + y^T g(u) \geq 0,$$

which contradicts (11). Hence,

$$f(x) + s(x|D) \not\leq f(u) + u^T w - y^T g(u)e.$$

(b) Since  $-y^T g(x) \leq 0$ , (11) implies that

$$\lambda^T [f(x) + s(x|D)] - y^T g(x) < \lambda^T [f(u) + u^T w] - y^T g(u).$$

By the assumption (b), it yields

$$\eta(x, u)^T [\nabla f(u) + w - \nabla y^T g(u)] < 0,$$

which contradicts (10). Thus,

$$f(x) + s(x|D) \not\leq f(u) + u^T w - y^T g(u)e.$$

□

**Theorem 4.2 (Strong Duality)** *If  $\bar{x}$  is a weakly efficient solution of (MP) at which constraint qualification be satisfied. Then there exist  $\bar{\lambda} \geq 0$ ,  $\bar{y} \in C_2$  and  $\bar{w}_i \in D_i (i = 1, \dots, k)$  such that  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is feasible for (WD) and the corresponding values of (MP) and (WD) are equal. If the assumption of Theorem 4.1 are satisfied, then  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is weakly efficient for (WD).*

*Proof.* Since  $\bar{x}$  is a weakly efficient solution of (MP), then there exist  $w_i \in D_i, i = 1, \dots, k, \bar{\lambda} \geq 0$  and  $\bar{y} \in C_2$  with  $(\bar{\lambda}, \bar{y}) \neq 0$  such that

$$[\bar{\lambda}^T (\nabla f(\bar{x}) + w) - \bar{y}^T \nabla g(\bar{x})]^T (x - \bar{x}) \geq 0, \quad \text{for all } x \in C_1, \quad (12)$$

$$\bar{y}^T g(\bar{x}) = 0, \quad (13)$$

$$w_i \in D_i, \quad s(\bar{x}|D_i) = \bar{x}^T w_i, \quad i = 1, \dots, k. \quad (14)$$

Since  $x \in C_1$ ,  $\bar{x} \in C_1$  and  $C_1$  is a closed convex cone, we have  $x + \bar{x} \in C_1$  and thus the inequality (12) implies

$$[\bar{\lambda}^T (\nabla f(\bar{x}) + w) - \bar{y}^T \nabla g(\bar{x})]^T x \geq 0, \quad \text{for all } x \in C_1,$$

i.e.,

$$\bar{\lambda}^T (\nabla f(\bar{x}) + w) - \bar{y}^T \nabla g(\bar{x}) = 0.$$

Taking  $\bar{w}_i = w_i \in D_i, i = 1, \dots, k$ , we find that  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is feasible for (WD) and corresponding values of (MP) and (WD) are equal, by (13) and (14). If the assumptions of Theorem 4.1 are satisfied, then  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{w})$  is a weakly efficient solution of (WD).  $\square$

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