

# Concentration and Stability of standing waves of nonlinear Schrödinger equation with inhomogeneous nonlinearity

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## 1 Introduction

In this paper, we consider the following nonlinear Schrödinger equation with inhomogeneous nonlinearity.

$$iu_t = -\Delta u - b(x)|u|^{p-1}u, \quad (x, t) \in \mathbb{R}^{N+1}, \quad (1.1)$$

where  $N \geq 1$ ,  $u : \mathbb{R}^{N+1} \rightarrow \mathbb{C}$  is an unknown function,  $p \in (1, 1 + 4/N)$  and  $b(x)$  is a smooth function which satisfies

$$0 < \inf_{x \in \mathbb{R}^N} b(x) = \lim_{|x| \rightarrow \infty} b(x) \leq \sup_{x \in \mathbb{R}^N} b(x) = 1.$$

A standing wave is a solution of equation (1.1) with the form  $u(x, t) = e^{i\omega t} \phi(x)$ . In this case,  $\phi$  satisfies the following partial differential equation.

$$-\Delta \phi + \omega \phi - b(x)|\phi|^{p-1} \phi = 0, \quad x \in \mathbb{R}^N. \quad (1.2)$$

The flow of equation (1.1) conserves the  $L^2$ -norm and the following functional, which we call the energy.

$$\mathcal{E}(u) := \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 dx - \frac{1}{p+1} \int_{\mathbb{R}^N} b(x)|u|^{p+1} dx.$$

The well-posedness of equation (1.1) is well known. See for example [2].

**Proposition 1.** *For every  $u_0 \in H^1(\mathbb{R}^N)$ , there exists a solution  $u \in C(\mathbb{R}; H^1(\mathbb{R}^N))$  of (1.1) such that*

- (a)  $u(x, 0) = u_0(x)$  for  $x \in \mathbb{R}^N$ .
- (b)  $\mathcal{E}(u(t)) = \mathcal{E}(u_0)$ ,  $\|u(t)\|_{L^2} = \|u_0\|_{L^2}$  for  $t \in \mathbb{R}$ .

Equation (1.1) appears in various regions of physics such as nonlinear optics, plasma physics and Bose-Einstein condensation (BEC). In the context of BEC, the ground states are considered to describe the physical properties of Bose gas in low temperature. Here, a ground state is a standing wave which minimizes the energy functional  $\mathcal{E}$  under the constraint of the  $L^2$ -norm. Note that by the

Lagrange multiplier method, the ground state satisfies (1.2) for some  $\omega \in \mathbb{R}$ . For the case  $b \equiv 1$ , it is known that the ground state is unique ([5, 9]), and if  $1 < p < 1 + 4/N$ , it is stable ([1]). For the case  $b = |x|^{-\beta}$ ,  $\beta \in (0, 2)$ ,  $N \geq 3$ , it is proved that the ground state is stable ([4]).

We now state prepare the notations.

**Definition 1.** *Set*

$$\mathcal{G}_\alpha := \{u \in H^1(\mathbb{R}^N) \mid \|u\|_{L^2} = \alpha, \mathcal{E}(u) = E_\alpha\},$$

where

$$E_\alpha = \inf \{\mathcal{E}(v) \mid v \in H^1(\mathbb{R}^N), \|v\|_{L^2} = \alpha\}.$$

In this paper, we call the elements of  $\mathcal{G}_\alpha$ , the ground states.

For the case,  $b$  is a radial symmetric function, we can consider a minimizer of  $\mathcal{E}$  under the constraint  $u \in H_r^1(\mathbb{R}^N)$  and  $\|u\|_{L^2} = \alpha$ , where

$$H_r^1(\mathbb{R}^N) := \{u \in H^1(\mathbb{R}^N) \mid u \text{ is radially symmetric}\}.$$

**Definition 2.** *Set*

$$\mathcal{G}_{\alpha,r} := \{u \in H_r^1(\mathbb{R}^N) \mid \|u\|_{L^2} = \alpha, \mathcal{E}(u) = E_{\alpha,r}\},$$

where

$$E_{\alpha,r} = \inf \{\mathcal{E}(v) \mid v \in H_r^1(\mathbb{R}^N), \|v\|_{L^2} = \alpha\}.$$

In this paper, we call the elements of  $\mathcal{G}_{\alpha,r}$ , the radial minimizers.

We investigate the concentration and stability of ground states and radial minimizers.

**Definition 3.** *We say that the  $\mathcal{G}_\alpha$  (resp.  $\mathcal{G}_{\alpha,r}$ ) concentrates for sufficiently large  $\alpha$  if the elements of  $\mathcal{G}_\alpha$  ( $\mathcal{G}_{\alpha,r}$ ) satisfies the following: For arbitrary  $\varepsilon > 0$ , there exists an  $\alpha_\varepsilon > 0$  such that for every  $\alpha > \alpha_\varepsilon$  and every  $\phi \in \mathcal{G}_\alpha$  ( $\mathcal{G}_{\alpha,r}$ ), there exists  $y_{\alpha,\phi} \in \mathbb{R}^N$  such that*

$$\int_{|x-y_{\alpha,\phi}|>\varepsilon} |\phi|^2 dx < \varepsilon \int_{\mathbb{R}^N} |\phi|^2 dx = \varepsilon \alpha^2.$$

We call  $y_{\alpha,\phi} \in \mathbb{R}^N$ , the concentration center.

**Definition 4.** *We say that  $\mathcal{G}_\alpha$  (resp.  $\mathcal{G}_{\alpha,r}$ ) is stable if the following property is satisfied: For arbitrary  $\varepsilon > 0$ , there exists an  $\delta_\varepsilon > 0$  such that for every  $u_0 \in H^1$  with*

$$\inf_{v \in \mathcal{G}_\alpha(\mathcal{G}_{\alpha,r})} \|u_0 - v\|_{H^1} < \delta_\varepsilon,$$

the solution of equation (1.1) with  $u(0) = u_0$  satisfies

$$\sup_{t>0} \inf_{v \in \mathcal{G}_\alpha(\mathcal{G}_{\alpha,r})} \|u(t) - v\|_{H^1} < \varepsilon.$$

If  $\mathcal{G}_\alpha$  ( $\mathcal{G}_{\alpha,r}$ ) is not stable, we say  $\mathcal{G}_\alpha$  ( $\mathcal{G}_{\alpha,r}$ ) is unstable.

The existence, concentration and stability of  $\mathcal{G}_\alpha$  is well known.

**Proposition 2.** *For  $\alpha > 0$ ,  $\mathcal{G}_\alpha \neq \emptyset$  and  $\mathcal{G}_\alpha$  is stable. Further,  $\mathcal{G}_\alpha$  concentrates for sufficiently large  $\alpha$  and the concentration center converges to some maximum point of  $b$ .*

**Remark 1.** For the existence of ground states, see Proposition 8.3.6 of [2]. For the stability result, see [1] and for the concentration result, see [13].

The purpose of this paper is to investigate the stability and concentration for the elements of  $\mathcal{G}_{\alpha,r}$ .

**Proposition 3.** *Let  $b$  radially symmetric. Then for  $\alpha > 0$ , we have  $\mathcal{G}_\alpha \neq \emptyset$ .*

**Remark 2.** Proposition 3 can be proved as the existence of ground states.

We first study the case  $N \geq 2$ .

**Theorem 1.** *Let  $N \geq 2$ . Then  $\mathcal{G}_\alpha$  concentrates for sufficiently large  $\alpha$  and the concentration center is 0. Further, if 0 is a nondegenerate minimum point (resp. maximum point), then for sufficiently large  $\alpha > 0$ ,  $\mathcal{G}_{\alpha,r}$  is stable (unstable).*

Thus, we see that the concentration result holds but the stability result some times fails for the case of radial minimizers. For the case  $N = 1$ , we see that also the concentration result sometimes fails.

**Theorem 2.** *Let  $N = 1$ .*

- (i) *If  $1 \geq b(0) > 2^{-(p-1)/2}$ , then  $\mathcal{G}_{\alpha,r}$  concentrates for sufficiently large  $\alpha$  and the concentration center is 0. Further, if 0 is a nondegenerate minimum point (resp. maximum point), then for sufficiently large  $\alpha > 0$ ,  $\mathcal{G}_{\alpha,r}$  is stable (unstable).*
- (ii) *If  $0 < b(0) < 2^{-(p-1)/2}$ , then  $\mathcal{G}_\alpha$  is unstable and does not concentrate for sufficiently large  $\alpha$ .*

The plan of this paper is as follows. In section 2, we rescale our problem. In section 3 and 4, we prove Theorems 1 and 2 respectively. The proof of the concentration result of Theorem 1 relies on the radial lemma due to Strauss [14]. For the proof of the concentration result of Theorem 2, we use the concentration compactness method due to Lions [10, 11]. For the stability result, we use the abstract theory developed by Grillakis, Shatah and Strauss [7] and for the instability result, we use the result of [12] for  $N \geq 2$  and [6] for the case  $N = 1$ .

## 2 Preliminary

We rescale our problem. Take  $\phi \in H^1_r(\mathbb{R}^N)$  with  $\|\phi\|_{L^2} = 1$ . Then, we have

$$\mathcal{E}(\alpha\phi) = \alpha^2 \left( \frac{1}{2} \int_{\mathbb{R}} |\nabla\phi|^2 dx - \frac{\alpha^{p-1}}{p+1} \int_{\mathbb{R}} b(x)|\phi|^{p+1} dx \right).$$

Next, set  $\phi_\alpha(x) = \alpha^{AN/2} \phi(\alpha^A x)$ , where  $A = \frac{2(p-1)}{4-N(p-1)}$ . Then, we have

$$\mathcal{E}_\alpha(\alpha\phi_\alpha) = \alpha^{2+2A} \left( \frac{1}{2} \int_{\mathbb{R}} |\nabla\phi|^2 dx - \frac{1}{p+1} \int_{\mathbb{R}} b(\alpha^{-A}x)|\phi|^{p+1} dx \right).$$

Therefore, we set

$$I_\alpha(\phi) := \frac{1}{2} \int_{\mathbb{R}} |\nabla \phi|^2 dx - \frac{1}{p+1} \int_{\mathbb{R}} b(\alpha^{-A}x) |\phi|^{p+1} dx,$$

and

$$\mathcal{I}_{\alpha,r} := \left\{ \phi \in H_r^1(\mathbb{R}^N) \mid \|\phi\|_{L^2} = 1, I_\alpha(\phi) = \inf_{\|\psi\|_{L^2}=1, \psi \in H_r^1(\mathbb{R}^N)} I_\alpha(\psi) \right\}.$$

Thus, we obtain

$$\mathcal{G}_{\alpha,r} = \{ \alpha \phi_\alpha \mid \phi \in \mathcal{I}_{\alpha,r} \}.$$

We also define the following functional:

$$I_{\infty,b}(\phi) := \frac{1}{2} \int_{\mathbb{R}} |\nabla \phi|^2 dx - \frac{b}{p+1} \int_{\mathbb{R}} |\phi|^{p+1} dx.$$

Then, it is well known that there exists a unique positive radial minimizer  $\psi_{b,\beta}$  of  $I_{\infty,b}$  under the constraint  $\|\phi\|_{L^2}^2 = \beta$ . That is

$$\begin{aligned} \mathcal{I}_{\infty,r,b,\beta} &:= \left\{ \phi \in H_r^1(\mathbb{R}^N) \mid \|\phi\|_{L^2}^2 = \beta, I_{\infty,b}(\phi) = \inf_{\|\varphi\|_{L^2}^2 = \beta, \varphi \in H_r^1} I_{\infty,b}(\varphi) \right\} \\ &= \{ c \psi_{b,\beta} \mid c \in \mathbb{C}, |c| = 1 \}. \end{aligned}$$

**Remark 3.** The uniqueness of positive radial solution of equation (1.2) in the case  $b(x) \equiv b > 0$  is proved by Kwong [9]. Further, letting  $\phi_{b,\omega}$  be the unique positive radial solution of equation (1.2) in the case  $b(x) \equiv b > 0$ , we have  $\phi_{b,\omega}(x) = \omega^{\frac{1}{p-1}} \phi_b(\omega^{1/2}x)$ , where  $\phi_b$  is the unique positive radial solution of

$$-\Delta \phi_b + \phi_b - b \phi_b^p = 0, \quad x \in \mathbb{R}^N.$$

Therefore, we see  $\frac{d}{d\omega} \|\phi_{b,\omega}\|_{L^2}^2 > 0$  for  $1 < p < 1 + 4/N$ . This implies the uniqueness of the radial minimizer up to constant phase.

We now calculate the value

$$I_{\infty,b}(\psi_{b,\beta}) = \inf \{ I_{\infty,b}(\phi) \mid \phi \in H_r^1(\mathbb{R}^N), \|\phi\|_{L^2}^2 = \beta \}.$$

**Lemma 1.** *Let*

$$J_\infty = \inf_{\|u\|_{L^2}=1} I_{\infty,1}(u) = I_{\infty,1}(\psi_{1,1}) < 0.$$

*Then*

$$I_{\infty,b}(\psi_{b,\beta}) = b^{\frac{2A}{p-1}} \beta^{1+A} J_\infty,$$

where  $A = \frac{2(p-1)}{4-N(p-1)} > 0$ .

*Proof.*

$$\begin{aligned} I_{\infty,b}(\psi_{b,\beta}) &= \inf_{\phi \in H_r^1, \|\phi\|_{L^2}^2 = \beta} \left( \frac{1}{2} \int_{\mathbb{R}} |\nabla \phi|^2 dx - \frac{b}{p+1} \int_{\mathbb{R}} |\phi|^{p+1} dx \right) \\ &= \beta \inf_{\|\phi\|_{L^2} = 1} \left( \frac{1}{2} \int_{\mathbb{R}} |\nabla \phi|^2 dx - \frac{b\beta^{\frac{p-1}{2}}}{p+1} \int_{\mathbb{R}} |\phi|^{p+1} dx \right). \end{aligned}$$

Now, setting  $\phi(x) = (b\beta^{\frac{p-1}{2}})^{\frac{N}{4-N(p-1)}} \varphi((b\beta^{\frac{p-1}{2}})^{\frac{2}{4-N(p-1)}} x)$ , we have  $\|\varphi\|_{L^2} = \|\phi\|_{L^2}$  and

$$\frac{1}{2} \int_{\mathbb{R}} |\nabla \phi|^2 dx - \frac{b\beta^{\frac{p-1}{2}}}{p+1} \int_{\mathbb{R}} |\phi|^{p+1} dx = (b\beta^{\frac{p-1}{2}})^{\frac{4}{4-N(p-1)}} I_{\infty,1}(\varphi).$$

Thus, we have

$$\inf_{\|u\|_{L^2}^2 = \beta} I_{\infty,b}(u) = b^{\frac{4}{4-N(p-1)}} \beta^{1 + \frac{2(p-1)}{4-N(p-1)}} J_{\infty}.$$

□

We further prepare some compactness results. To show the concentration result of Theorem 1, we use the following lemma due to Strauss [14].

**Lemma 2.** *Let  $N \geq 2$ . Then every  $u \in H_r^1$  is almost everywhere equal to a function  $U$ , continuous for  $x \neq 0$ , such that*

$$|U(x)| \leq C_N |x|^{-\frac{(N-1)}{2}} \|u\|_{H^1} \text{ for } |x| \geq C_N,$$

where  $C_N$  depends only on the dimension  $N$ .

To show Theorem 2, we prepare two concentration compactness lemmas, which are slight modifications of the concentration compactness lemma due to Lions [10, 11] (See also [2]).

**Lemma 3.** *Let  $\{u_n\} \subset H_r^1(\mathbb{R})$  be such that*

$$\|u_n\|_{L^2} = 1, \sup_{n \in \mathbb{N}} \|\nabla u_n\|_{L^2} < \infty. \quad (2.1)$$

Set

$$\tilde{\mu} = \lim_{t \rightarrow \infty} \liminf_{n \rightarrow \infty} \int_{|x| < t} |u_n|^2 dx. \quad (2.2)$$

Then, there exists a subsequence  $\{u_{n_k}\}$  that satisfies the following.

- (i) If  $\tilde{\mu} = 1$ , then there exists a  $u \in H_r^1(\mathbb{R})$  such that  $u_{n_k} \rightarrow u$  in  $L^p(\mathbb{R})$  for  $p \in [2, \infty]$ .

(ii) There exist  $\{v_k\}$ ,  $\{w_{k,+}\}$  and  $\{w_{k,-}\} \subset H_r^1(\mathbb{R})$  such that

$$\begin{aligned} & \text{supp} w_{k,+} \subset (0, \infty), \quad \text{supp} w_{k,-} \subset (-\infty, 0), \\ & \text{supp} v_k \cap \text{supp} w_{k,+} = \text{supp} v_k \cap \text{supp} w_{k,-} = \emptyset, \\ & |v_k| + |w_{k,+}| + |w_{k,-}| \leq |u_{n_k}| \\ & \|v_k\|_{H^1} + \|w_{k,+}\|_{H^1} + \|w_{k,-}\|_{H^1} \leq \|u_{n_k}\|_{H^1} \\ & \|v_k\|_{L^2}^2 \rightarrow \tilde{\mu}, \quad \|w_{k,+}\|_{L^2}^2 \rightarrow \frac{1}{2}(1 - \tilde{\mu}), \quad \|w_{k,-}\|_{L^2}^2 \rightarrow \frac{1}{2}(1 - \tilde{\mu}) \\ & \liminf_{k \rightarrow \infty} \int (|\nabla u_{n_k}|^2 - |\nabla v_k|^2 - |\nabla w_{k,+}|^2 - |\nabla w_{k,-}|^2) \geq 0 \\ & \left| \int (|u_{n_k}|^p - |v_k|^p - |w_{k,+}|^p - |w_{k,-}|^p) \right| \rightarrow 0, \quad (k \rightarrow \infty) \end{aligned}$$

for all  $2 \leq p \leq \infty$ .

**Lemma 4.** Let  $\{u_n\}$  satisfy (2.1). Define  $\tilde{\mu}$  as (2.2) and

$$\mu := \lim_{t \rightarrow \infty} \liminf_{n \rightarrow \infty} \sup_{y \in \mathbb{R}} \int_{|x-y|<t} |u_n|^2 dx.$$

Assume  $\tilde{\mu} = 0$ . Then,  $0 \leq \mu \leq 1/2$  and there exists a subsequence  $\{u_{n_k}\}$  that satisfies the following.

- (i) If  $\mu = 1/2$ , then there exist  $u \in H_r^1(\mathbb{R})$  and  $y_k > 0$  such that  $y_k \rightarrow \infty$  and  $\chi_+(\cdot - y_k)u_{n_k}(\cdot - y_k) \rightarrow u$  in  $L^p(\mathbb{R})$  for  $p \in [2, \infty]$ , where  $\chi_+ \in C^\infty$  satisfies  $0 \leq \chi_+ \leq 1$ ,  $\text{supp} \chi_+ \subset [0, \infty)$  and  $\chi_+(x) = 1$  for  $x \geq 1$ .
- (ii) If  $\mu = 0$ , then  $u_{n_k} \rightarrow 0$  in  $L^p$  for  $p \in (2, \infty]$ .
- (iii) There exist  $\{v_{k,+}\}$ ,  $\{v_{k,-}\}$ ,  $\{w_{k,+}\}$  and  $\{w_{k,-}\} \subset H_r^1(\mathbb{R})$  such that

$$\begin{aligned} & \text{supp} v_{k,+}, \text{supp} w_{k,+} \subset (0, \infty), \quad \text{supp} v_{k,-}, \text{supp} w_{k,-} \subset (-\infty, 0), \\ & \text{supp} v_{k,+} \cap \text{supp} w_{k,+} = \text{supp} v_{k,-} \cap \text{supp} w_{k,-} = \emptyset, \\ & |v_{k,+}| + |v_{k,-}| + |w_{k,+}| + |w_{k,-}| \leq |u_{n_k}| \\ & \|v_{k,+}\|_{H^1} + \|v_{k,-}\|_{H^1} + \|w_{k,+}\|_{H^1} + \|w_{k,-}\|_{H^1} \leq \|u_{n_k}\|_{H^1} \\ & \|v_{k,\pm}\|_{L^2}^2 \rightarrow \tilde{\mu}, \quad \|w_{k,\pm}\|_{L^2}^2 \rightarrow \frac{1}{2}(1 - \tilde{\mu}) \\ & \liminf_{k \rightarrow \infty} \int (|\nabla u_{n_k}|^2 - |\nabla v_{k,+}|^2 - |\nabla v_{k,-}|^2 - |\nabla w_{k,+}|^2 - |\nabla w_{k,-}|^2) \geq 0 \\ & \left| \int (|u_{n_k}|^p - |v_{k,+}|^p - |v_{k,-}|^p - |w_{k,+}|^p - |w_{k,-}|^p) \right| \rightarrow 0, \quad (k \rightarrow \infty) \end{aligned}$$

for all  $2 \leq p \leq \infty$ .

### 3 Proof of Theorem 1

Let  $\psi_{b(0),1} \in \mathcal{I}_{\infty,r,b(0),1}$ ,  $\psi_{b(0),1} > 0$ . We show that the rescaled radial minimizers converge to  $\psi_{b(0),1}$ .

**Lemma 5.** Let  $N \geq 2$  and  $b$  radially symmetric. Let  $\phi_n \in \mathcal{I}_{\alpha_n}$  with  $\phi_n > 0$ , where  $\alpha_n \rightarrow \infty$  as  $n \rightarrow \infty$ . Then  $\{\phi_n\}$  is a minimizing sequence of  $I_{\infty, b(0)}$  under the constraint  $\|\phi\|_{L^2} = 1$ . In particular,  $\phi_n \rightarrow \psi_{b(0), 1}$ .

*Proof.* We calculate  $I_{\infty, b(0)}(\phi_n)$ .

$$\begin{aligned} I_{\infty, b(0)}(\phi_n) &= \frac{1}{2} \int_{\mathbb{R}} |\nabla \phi_n|^2 dx - \frac{b(0)}{p+1} \int_{\mathbb{R}} |\phi_n|^{p+1} dx \\ &\leq I_{\alpha_n}(\phi_n) + \frac{1}{p+1} \int_{\mathbb{R}} |b(\alpha_n^{-A}x) - b(0)| |\phi_n|^{p+1} dx \\ &\leq I_{\alpha_n}(\psi_{b(0), 1}) + \frac{1}{p+1} \int_{\mathbb{R}} |b(\alpha_n^{-A}x) - b(0)| |\phi_n|^{p+1} dx \\ &\leq I_{\infty, b(0)}(\psi_{b(0), 1}) \\ &\quad + \frac{1}{p+1} \int_{\mathbb{R}} |b(\alpha_n^{-A}x) - b(0)| (|\phi_n|^{p+1} + |\psi_{b(0), 1}|^{p+1}) dx, \end{aligned}$$

where  $A = \frac{2(p-1)}{4-N(p-1)} > 0$ . Now, for arbitrary  $\varepsilon > 0$ , there exists  $R_\varepsilon > 0$  such that  $|b(x) - b(0)| < \varepsilon$  for  $|x| < R_\varepsilon$ . Therefore, we have

$$\int_{\mathbb{R}} |b(\alpha_n^{-A}x) - b(0)| |\psi_{b(0), 1}|^{p+1} dx \leq \varepsilon \int_{\mathbb{R}} |\psi_{b(0), 1}|^{p+1} dx + \int_{|x| > \alpha_n^A R_\varepsilon} |\psi_{b(0), 1}|^{p+1} dx.$$

Further, for sufficiently large  $\alpha_n$ , we have

$$\frac{1}{p+1} \int_{|x| > \alpha_n^A R_\varepsilon} |\psi_{b(0), 1}|^{p+1} dx \leq \varepsilon.$$

Thus, we obtain

$$\frac{1}{p+1} \int_{\mathbb{R}} |b(\alpha_n^{-A}x) - b(0)| |\psi_{b(0), 1}|^{p+1} dx \rightarrow 0, \quad n \rightarrow \infty$$

Next, using the fact that  $\phi_n$  is a radial minimizer of  $I_{\alpha_n}$ , we see that  $I_{\alpha_n}(\phi_n) < 0$ . Combining this to Gagliardo-Nirenberg's inequality, we see that  $\|\phi_n\|_{H^1}$  is uniformly bounded. Therefore, by Lemma 2, we have

$$\begin{aligned} \int_{\mathbb{R}} |b(\alpha_n^{-A}x) - b(0)| |\phi_n|^{p+1} dx &\leq \varepsilon \int_{\mathbb{R}} |\phi_n|^{p+1} dx + C \int_{|x| > \alpha_n^A R_\varepsilon} |x|^{-\frac{(N-1)(p+1)}{2}} dx \\ &\leq C\varepsilon + C(\alpha_n R_\varepsilon)^{1 - \frac{(N-1)(p+1)}{2}}. \end{aligned}$$

Since  $1 - \frac{(N-1)(p+1)}{2} < 0$ , we see that

$$\frac{1}{p+1} \int_{\mathbb{R}} |b(\alpha_n^{-A}x) - b(0)| |\phi_n|^{p+1} dx \rightarrow 0, \quad n \rightarrow \infty.$$

Therefore, we see that  $\phi_n$  is a minimizing sequence of  $I_{\infty, b(0)}$ .  $\square$

We now prove Theorem 1.

*Proof of Theorem 1.* Let  $u_n \in \mathcal{G}_{\alpha_n}$  with  $\alpha_n \rightarrow \infty$  as  $n \rightarrow \infty$ . Then, there exists  $\phi_n \in \mathcal{I}_{\alpha_n}$  such that

$$\alpha_n^{1+N.A/2} \phi_n(\alpha^A x) = u_n(x),$$

where  $A = \frac{2(p-1)}{4-N(p-1)}$ . We compute  $\left(\int_{|x|>\varepsilon} |u_n|^2 dx\right)^{1/2}$ .

$$\begin{aligned} \left(\int_{|x|>\varepsilon} |u_n|^2 dx\right)^{\frac{1}{2}} &= \alpha \left(\int_{|x|>\varepsilon\alpha^A} |\phi_n|^2 dx\right)^{\frac{1}{2}} \\ &\leq \alpha \left(\int_{\mathbb{R}^N} |\psi_{b(0),1} - \phi_n|^2 dx\right)^{\frac{1}{2}} + \alpha \left(\int_{|x|>\varepsilon\alpha^A} |\psi_{b(0),1}|^2 dx\right)^{\frac{1}{2}}, \end{aligned}$$

where  $\psi_{b(0),1}$  is the positive radial minimizer of  $I_{\infty,b(0)}$  under the constraint  $\|\phi\|_{L^2} = 1$ . Since  $\phi_n \rightarrow \psi_{b(0),1}$  in  $L^2(\mathbb{R}^N)$ , we have

$$\left(\int_{\mathbb{R}} |\psi - \phi_n|^2 dx\right)^{1/2} < \frac{1}{2}\varepsilon^{1/2}$$

for sufficiently large  $n$ . Further, since  $\frac{2(p-1)}{4-N(p-1)} > 0$  and  $\alpha_n \rightarrow \infty$ , we see

$$\left(\int_{|x|>\varepsilon\alpha_n^A} |\psi|^2 dx\right)^{1/2} < \frac{1}{2}\varepsilon^{1/2},$$

for sufficiently large  $n$ . Therefore, we have the concentration result.

We next show the stability for the case 0 is a nondegenerate minimum point of  $b$ . For this case, modifying the result of Grossi [8], we see that for large  $\alpha > 0$ , the radial minimizer is unique up to constant phase. Therefore, the radial minimizer must correspond to the ground state with a penalizer which was introduced in [3]. Since this ground state is stable, we see that also the radial minimizer is stable.

Finally for the proof of the instability for the case 0 is a nondegenerate maximum point of  $b$ , see [12].  $\square$

## 4 Proof of Theorem 2

*Proof of Theorem 2 (i).* Let  $u_n \in \mathcal{G}_{\alpha_n}$  with  $u_n > 0$  and  $\alpha_n \rightarrow \infty$  as  $n \rightarrow \infty$ . Then, there exists  $\phi_n \in \mathcal{I}_{\alpha_n}$  such that

$$\alpha_n^{1+\frac{p-1}{5-p}} \phi_n(\alpha_n^{\frac{2(p-1)}{5-p}} x) = u_n(x).$$

Since  $\|\phi_n\|_{L^2} = 1$  and  $\sup_n \|\nabla\phi_n\|_{L^2} < \infty$ , we apply Lemma 3 to  $\{\phi_n\}$ . As in the proof of Theorem 1, if we can show  $\phi_n \rightarrow \psi_{b(0),1}$  in  $H^1(\mathbb{R})$ , where  $\psi_{b(0),1}$  is the minimizer of  $I_{\infty,b(0)} = I_{\infty}$  under the constraint  $\|u\|_{L^2} = 1$ , we have the concentration result. Further, the stability and instability follows as in the proof of Theorem 1.

Therefore, it suffices to show  $\phi_n \rightarrow \psi_{b(0),1}$  in  $H^1(\mathbb{R})$ . Now, let

$$\tilde{\mu} = \lim_{t \rightarrow \infty} \liminf_{n \rightarrow \infty} \int_{|x|<t} |\phi_n|^2 dx.$$



We show  $\tilde{\mu} = 1$ . If  $\tilde{\mu} = 1$ , we have a subsequence  $\phi_{n_k}$  and  $\phi$  such that  $\phi_{n_k} \rightarrow \phi$  in  $L^p$ ,  $p \in [2, \infty]$ . Thus, we have  $\|\phi\|_{L^2} = 1$  and

$$\begin{aligned} I_{\infty, b(0)}(\phi) &\leq \liminf_{k \rightarrow \infty} I_{\infty, b(0)}(\phi_{n_k}) \\ &\leq \liminf_{k \rightarrow \infty} \left( I_{\alpha_{n_k}}(\phi_{n_k}) + \int |b(0) - b(\alpha_{n_k}^{-A}x)| |\phi_{n_k}|^{p+1} dx \right) \\ &\leq \liminf_{k \rightarrow \infty} \left( I_{\alpha_n}(\psi_{b(0),1}) + \int |b(0) - b(\alpha_n^{-A}x)| |\phi_{n_k}|^{p+1} dx \right) \\ &\leq I_{\infty, b(0)}(\psi_{b(0),1}) + \liminf_{k \rightarrow \infty} \int |b(0) - b(\alpha_n^{-A}x)| (|\phi_{n_k}|^{p+1} + |\psi_{b(0),1}|^{p+1}) dx \\ &= I_{\infty, b(0)}(\psi_{b(0),1}), \end{aligned}$$

where  $A = \frac{2(p-1)}{5-p}$ . Therefore, from the definition of  $\psi_{b(0),1}$  and the uniqueness of the radial minimizer of  $I_{\infty, b(0)}$ , we see that  $\phi_{n_k} \rightarrow \psi_{b(0),1}$  in  $H^1(\mathbb{R})$ .

Therefore, it suffices to show  $\tilde{\mu} = 1$ . Suppose  $\tilde{\mu} < 1$ . Then, by Lemma 3, there exist  $\{v_k\}$ ,  $\{w_{k,+}\}$  and  $\{w_{k,-}\}$  and we have

$$\liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) \geq \limsup_{k \rightarrow \infty} \left( I_{\alpha_{n_k}}(v_k) + I_{\infty,1}(w_{k,+}) + I_{\infty,1}(w_{k,-}) \right).$$

We claim  $\limsup_{k \rightarrow \infty} I_{\alpha_{n_k}}(v_k) \geq b(0)^{\frac{2A}{p-1}} \tilde{\mu}^{1+A} J_{\infty}$ , where  $A = \frac{2(p-1)}{5-p}$ . Indeed, since  $|v_k| \leq |u_{n_k}|$ , taking arbitrary  $\varepsilon > 0$ , there exists  $R_{\varepsilon} > 0$  such that

$$\limsup_{k \rightarrow \infty} \int_{|x| > R_{\varepsilon}} |v_k|^2 dx < \varepsilon.$$

Therefore, we have

$$\begin{aligned} \limsup_{k \rightarrow \infty} I_{\alpha_{n_k}}(v_k) &\geq \limsup_{k \rightarrow \infty} \left( I_{\infty, b(0)}(v_k) - \int_{|x| < R_{\varepsilon}} |b(\alpha_{n_k}^{-A}x) - b(0)| |v_k|^{p+1} dx \right. \\ &\quad \left. - \int_{|x| > R_{\varepsilon}} |b(\alpha_{n_k}^{-A}x) - b(0)| |v_k|^{p+1} dx \right). \end{aligned}$$

Further, since  $\sup_k \|v_k\|_{L^{\infty}} \leq C_1 \sup_k \|v_k\|_{H^1} \leq C_2 \sup_k \|\phi_{n_k}\|_{H^1} < C_3$ , we have

$$\int_{|x| > R_{\varepsilon}} |b(\alpha_{n_k}^{-A}x) - b(0)| |v_k|^{p+1} dx \leq 2C_3^{p-1} \varepsilon,$$

and taking  $\alpha_{n_k}$  sufficiently large, we have

$$\int_{|x| < R_{\varepsilon}} |b(\alpha_{n_k}^{-A}x) - b(0)| |v_k|^{p+1} dx \leq \varepsilon \int_{\mathbb{R}} |v_k|^{p+1} dx \leq C \varepsilon.$$

Therefore, we obtain

$$\liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) \geq \left( b(0)^{\frac{2A}{p-1}} \tilde{\mu}^{1+A} + 2 \left( \frac{1 - \tilde{\mu}}{2} \right)^{1+A} \right) J_{\infty}.$$

On the other hand, we have

$$\liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) \leq \liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\psi_{b(0)}) = b(0)^{\frac{2A}{p-1}} J_{\infty}.$$

Therefore, since  $J_{\infty} < 0$ , we have

$$b(0)^{\frac{2A}{p-1}} \leq \frac{(1 - \tilde{\mu})^{1+A}}{2^A(1 - \tilde{\mu}^{1+A})}.$$

Since,  $\frac{(1 - \tilde{\mu})^{1+A}}{1 - \tilde{\mu}^{1+A}} \leq 1$ , we obtain

$$b(0) \leq 2^{-\frac{p-1}{2}}.$$

However we have assumed  $b(0) > 2^{-\frac{p-1}{2}}$ . Therefore, this is a contradiction.  $\square$

*Proof of Theorem 2 (ii).* Let  $u_n \in \mathcal{G}_{\alpha_n}$  with  $u_n > 0$  and  $\alpha_n \rightarrow \infty$  as  $n \rightarrow \infty$ . Then, there exists  $\phi_n \in \mathcal{I}_{\alpha_n, r}$  such that

$$\alpha_n^{1 + \frac{p-1}{5-p}} \phi_n(\alpha_n^{\frac{2(p-1)}{5-p}} x) = u_n(x).$$

We first show  $\tilde{\mu} = 0$ . Suppose  $\tilde{\mu} > 0$ . Then as in the proof of Theorem 2 (i), using Lemma 3, we have

$$\lim_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_n) \geq \left( b(0)^{\frac{2A}{p-1}} \tilde{\mu}^{1+A} + 2 \left( \frac{1 - \tilde{\mu}}{2} \right)^{1+A} \right) J_{\infty},$$

where  $A = \frac{2(p-1)}{5-p}$ . On the other hand, take  $x_0 > 0$  to satisfy  $b(x_0) = 1$  and set

$$\varphi_k(x) = t_k (\psi_{1,1/2}(x - \alpha_{n_k}^A x_0) + \psi_{1,1/2}(x + \alpha_{n_k}^A x_0)),$$

where  $\psi$  is the minimizer of  $I_{\infty,1}$  under the constraint  $\|u\|_{L^2}^2 = 1/2$  and  $t_k > 1$ ,  $t_k \rightarrow 1$  as  $k \rightarrow \infty$  is taken so that  $\|\varphi_k\|_{L^2} = 1$ . By a simple calculation, we have

$$\lim_{k \rightarrow \infty} I_{\alpha_{n_k}}(\varphi_k) = 2^{-A} J_{\infty}. \quad (4.1)$$

Since  $I_{\alpha_{n_k}}(\phi_{n_k}) \leq I_{\alpha_{n_k}}(\varphi_k)$  and  $J_{\infty} < 0$ , we have

$$b(0)^{\frac{2A}{p-1}} \tilde{\mu}^{1+A} + 2 \left( \frac{1 - \tilde{\mu}}{2} \right)^{1+A} \geq 2^{-A}. \quad (4.2)$$

However, (4.2) implies

$$b(0) \geq 2^{-\frac{p-1}{2}}.$$

Thus, we have contradiction since we are assuming  $b(0) < 2^{-\frac{p-1}{2}}$ .

Therefore, we have  $\tilde{\mu} = 0$ . We use Lemma 4. Suppose,  $\mu = 0$ . Then, by Lemma 4 (ii), we have  $\liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) \geq 0$ , so it contradicts to

$$\liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) \leq \liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\varphi_k) < 0.$$

Suppose  $0 < \mu < 1/2$ . Then calculating as the proof of Theorem 2 (i) and using Lemma 4 instead of Lemma 3, we obtain

$$\liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) \geq \left( 2\mu^{1+A} + 2 \left( \frac{1-2\mu}{2} \right)^{1+A} \right) J_{\infty}.$$

However, this implies  $\liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) > \lim_{k \rightarrow \infty} I_{\alpha_{n_k}}(\varphi_k)$  and we have a contradiction. Therefore, we have  $\mu = 1/2$ .

By Lemma 4, there exist  $\phi$  and  $y_k > 0$  such that  $\chi_+(\cdot - y_k)\phi_{n_k}(\cdot - y_k) \rightarrow \phi$  in  $L^p(\mathbb{R})$  for  $p \in [2, \infty]$ . Thus, we see that  $\|\chi_+(\cdot - y_k)\phi_{n_k}(\cdot - y_k)\|_{L^2}^2 \rightarrow 1/2$ . We claim  $\chi_+(\cdot - y_k)\phi_{n_k}(\cdot - y_k) \rightarrow \psi_{1,1/2}$  in  $H^1(\mathbb{R})$ , where  $\psi_{1,1/2}$  is the positive radial minimizer of  $I_{\infty,1}$  under the constraint  $\|\phi\|_{L^2}^2 = 1/2$ . To show this, it suffices to show

$$I_{\infty,1}(\chi_+(\cdot - y_k)\phi_{n_k}(\cdot - y_k)) \rightarrow I_{\infty,1}(\psi_{1,1/2}) = 2^{-(1+A)} J_{\infty}.$$

Now, suppose there exists  $\varepsilon_0 > 0$  such that

$$\frac{1}{p+1} \int_{\mathbb{R}} (1 - b(\alpha_{n_k}^{-A}x))\phi_{n_k}^{p+1} dx \geq \varepsilon_0.$$

Then, we have

$$\begin{aligned} \lim_{k \rightarrow \infty} I_{\infty,1}(\varphi_k) &= \lim_{k \rightarrow \infty} I_{\alpha_{n_k}}(\varphi_k) \\ &\geq \liminf_{k \rightarrow \infty} I_{\alpha_{n_k}}(\phi_{n_k}) \\ &= \liminf_{k \rightarrow \infty} \left( I_{\infty,1}(\phi_{n_k}) + \frac{1}{p+1} \int_{\mathbb{R}} (1 - b(x/\alpha_{n_k}^A))\phi_{n_k} dx \right) \\ &\geq 2I_{\infty,1}(\psi_{1,1/2}) + \varepsilon_0 \\ &= \lim_{k \rightarrow \infty} I_{\infty,1}(\varphi_k) + \varepsilon_0. \end{aligned}$$

Therefore, we have

$$\lim_{k \rightarrow \infty} \frac{1}{p+1} \int_{\mathbb{R}} (1 - b(x/\alpha_{n_k}^A))\phi_{n_k}^{p+1} dx = 0.$$

Thus, since  $\tilde{\mu} = 0$ , we have

$$\begin{aligned} \liminf_{k \rightarrow \infty} I_{\infty,1}(\chi_+(\cdot - y_k)\phi_{n_k}(\cdot - y_k)) &= \liminf_{k \rightarrow \infty} I_{\infty,1}(\chi_+\phi_{n_k}) \\ &= \liminf_{k \rightarrow \infty} \frac{1}{2} I_{\infty,1}(\phi_{n_k}) \\ &= \liminf_{k \rightarrow \infty} \frac{1}{2} \left( I_{\alpha_{n_k}}(\phi_{n_k}) + \frac{1}{p+1} \int_{\mathbb{R}} (1 - b(x/\alpha_{n_k}^A))\phi_{n_k}^{p+1} dx \right) \\ &\leq \lim_{k \rightarrow \infty} \frac{1}{2} I_{\alpha_{n_k}}(\varphi_k) \\ &= I_{\infty,1}(\psi_{1,1/2}) \end{aligned}$$

Therefore, we see that  $\chi_+(\cdot - y_k)\phi_{n_k}(\cdot - y_k) \rightarrow \phi$  in  $H^1$ . Since  $y_k \rightarrow \infty$ , we see that  $\phi_{n_k}$  cannot concentrate around some point.

The instability follows from the fact that  $\phi_{n_k} \sim \psi_{1,1/2}(\cdot - y_k) + \psi_{1,1/2}(\cdot + y_k)$ . We see that there exists two directions which is tangent to the hypersurface  $\{\phi \in H^1(\mathbb{R}) \mid \|\phi\|_{L^2} = \alpha\}$  and decreases the energy. Using this fact, by [6], we can show the linear instability of  $u_n$  and the instability follows from the linear instability.  $\square$

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