

## REMARKS ON BOUNDARIES OF CAT(0) SPACES FROM SHAPE THEORY

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### 1. INTRODUCTION AND PRELIMINARIES

In this paper, we follow notations and terminologies of [2]. A metric space  $(X, d)$  is said to be *proper* if all closed, bounded sets in  $(X, d)$  are compact. A metric space  $(X, d)$  is said to be a *geodesic space* if for any  $x, y \in X$ , there exists an isometric embedding  $\xi : [0, d(x, y)] \rightarrow X$  such that  $\xi(0) = x$  and  $\xi(d(x, y)) = y$  (such a  $\xi$  is called a *geodesic*). Let  $(X, d)$  be a geodesic space and let  $T$  be a geodesic triangle in  $X$ . A *comparison triangle* for  $T$  is a geodesic triangle  $\bar{T}$  in the Euclidean plane  $\mathbb{R}^2$  with same edge lengths as  $T$ . Choose two points  $x$  and  $y$  in  $T$ . Let  $\bar{x}$  and  $\bar{y}$  denote the corresponding points in  $\bar{T}$ . Then the inequality

$$d(x, y) \leq d_{\mathbb{R}^2}(\bar{x}, \bar{y})$$

is called the *CAT(0)-inequality*, where  $d_{\mathbb{R}^2}$  is the usual metric on  $\mathbb{R}^2$ . A geodesic space  $X$  is called a *CAT(0) space* if the CAT(0)-inequality holds for all geodesic triangles  $T$  and for all choices of two points  $x$  and  $y$  in  $T$ . See for details of CAT(0) spaces in [2, p.158].

Let  $(X, d)$  be a proper CAT(0) space. Fix  $x_0 \in X$ . Set  $\bar{B}(x_0, r) = \{x \in X : d(x_0, x) \leq r\}$  and  $S(x_0, r) = \{x \in X : d(x_0, x) = r\}$ . Denote the geodesic segment from  $x$  and  $x'$  in  $X$  by  $[x, x']$ . There exists the projection  $p_r : X \rightarrow \bar{B}(x_0, r)$  such that  $p_r|_{\bar{B}(x_0, r)} = id$  and  $p_r(x) = x'$  if  $x \notin \bar{B}(x_0, r)$ , where  $\{x'\} = S(x_0, r) \cap [x_0, x]$ . Let  $\bar{X} = \varprojlim(\bar{B}(x_0, n), p_n|_{\bar{B}(x_0, n+1)})$  and  $\partial X = \varprojlim(S(x_0, n), r_n)$ , said to be the *boundary of  $X$*  where  $r_n = p_n|_{S(x_0, n+1)} : S(x_0, n+1) \rightarrow S(x_0, n)$  for each  $n \in \mathbb{N}$ . It is clear that  $\bar{X} = X \cup \partial X$  is a compactification of  $X$  with a remainder  $\partial X$  which is AR (see [12, Lemma 1.1]). It is known that the boundary  $\partial X$  of  $X$  is independent on the choice of  $x_0 \in X$ . See for details in [2, pp.263-265].

**Definition 1.1** ([4]). Let  $X$  and  $Y$  be ANR proper metric spaces. A homotopy equivalence  $f : X \rightarrow Y$  is said to be a *simple homotopy equivalence* if there exist an ANR proper metric space  $Z$  and proper cell-like maps  $\alpha : Z \rightarrow X, \alpha' : Z \rightarrow Y$  such that  $f \circ \alpha$  is proper homotopic to  $\alpha'$ , written  $f \circ \alpha \simeq_p \alpha'$ .

Let  $(X_i, d_i)$  be a proper CAT(0) space for  $i = 0, 1$ . First, we show that there exists a simple homotopy equivalence from  $X_0$  to  $X_1$  if and only if  $\partial X_0$  and  $\partial X_1$  are shape equivalent (see Proposition 2.3 below).

**Definition 1.2.** An *action* of a group  $\Gamma$  on a space  $X$ , written  $\Gamma \curvearrowright X$ , is a homomorphism from  $\Gamma$  to the group of self-homeomorphism of  $X$ .

A group  $\Gamma$  is said to *act geometrically* on a metric space  $(X, d)$ , written  $\Gamma \curvearrowright_{\text{geo.}} X$ , if  $\Gamma \curvearrowright X$  satisfies the following:

- (1) (isometry) We have  $d(x, x') = d(\gamma x, \gamma x')$  for any  $x, x' \in X$  and each  $\gamma \in \Gamma$ , written  $\Gamma \curvearrowright_{\text{iso.}} X$ ;
- (2) (cocompact) There exists a compact subset  $C$  of  $X$  such that  $X = \bigcup_{\gamma \in \Gamma} \gamma C$ , written  $\Gamma \curvearrowright_{\text{coc.}} X$ ;
- (3) (proper) For every  $x \in X$  there exists  $\epsilon > 0$  such that  $\{\gamma \in \Gamma : \overline{B}(x, \epsilon) \cap \gamma \overline{B}(x, \epsilon) \neq \emptyset\}$  is finite, written  $\Gamma \curvearrowright_{\text{pro.}} X$ .

Let  $\Gamma$  be a group and let  $X$  and  $Y$  be spaces with  $\Gamma \curvearrowright X$  and  $\Gamma \curvearrowright Y$ . A map  $f : X \rightarrow Y$  is said to be  $\Gamma$ -map if  $f(\gamma x) = \gamma f(x)$  for each  $x \in X$  and each  $\gamma \in \Gamma$ . Two maps  $f_0 : X \rightarrow Y$  and  $f_1 : X \rightarrow Y$  is said to be  $\Gamma$ -homotopic if there exists a  $\Gamma$ -map  $H : X \times [0, 1] \rightarrow Y$  which is a homotopy from  $f_0$  to  $f_1$ .

Gromov [10, Chapter 6] asks whether the visual boundary  $\partial X_0$  of  $X_0$  is  $\Gamma$ -equivariantly homeomorphic to the visual boundary  $\partial X_1$  of  $X_1$  whenever a group  $\Gamma$  acts geometrically on a CAT(0) space  $X_i$ . Recall that  $\Gamma$  acts on  $\partial X_i$  (see Remark 2.1 below). But, in general, C. B. Croke and B. Kleiner [7] showed that  $\partial X_0$  is not homeomorphic to  $\partial X_1$ . By use of a polyhedral resolution of boundaries, P. Ontaneda [12] proved that there exists a proper  $\Gamma$ -homotopy equivalence map  $f : X_0 \rightarrow X_1$  and  $\partial X_0$  and  $\partial X_1$  are shape equivalent. Then, the map  $f$  induces a shape isomorphism  $\mathbf{f}$  from  $\partial X_0$  to  $\partial X_1$  and every  $\gamma \in \Gamma$  induces a shape isomorphism  $\gamma_{X_i}$  from  $\partial X_i$  to  $\partial X_i$  (see Remark 2.2 below). In particular, Bestvina posed the following: Are  $\partial X_0$  and  $\partial X_1$  cell-like equivalent? Recall that  $\partial X_0$  and  $\partial X_1$  is said to be *cell-like equivalent* if there exist a compact metric space  $Z$  and two cell-like maps  $f_i : Z \rightarrow \partial X_i$  ( $i = 0, 1$ ). It is clear that if two compact ANR metric spaces are simple homotopy equivalent, they are cell-like equivalent. By Proposition 2.3 below, we see that  $f : X_0 \rightarrow X_1$  is a simple homotopy equivalence. In this paper, we state the following result.

**Proposition 1.3.** *Let  $\Gamma$  be a group and for  $i = 0, 1$  let  $(X_i, d_i)$  be a proper CAT(0) space with  $\Gamma \curvearrowright_{\text{geo.}} X_i$ . Then there exists a  $\Gamma$ -homotopy equivalence  $f : X_0 \rightarrow X_1$  with a proper  $\Gamma$ -homotopy inverse  $g : X_1 \rightarrow X_0$  such that  $f$  is a simple homotopy equivalence,  $f|_{X_0^G} : X_0^G \rightarrow X_1^G$  is a proper homotopy equivalence with a proper homotopy inverse  $g|_{X_1^G} : X_1^G \rightarrow X_0^G$  for each subgroup  $G$  of  $\Gamma$ , and,  $\mathbf{f}\gamma_{X_0} = \gamma_{X_1}\mathbf{f}$  for each  $\gamma \in \Gamma$ .*

Here,  $X^G = \{x \in X : \gamma x = x \text{ for all } \gamma \in G\}$  for a subgroup  $G$  of  $\Gamma$ .

## 2. SHAPE EQUIVALENCES

*Remark 2.1.* Let  $(X, d)$  be a proper CAT(0) space. Let  $\Gamma$  be a group with  $\Gamma \overset{iso}{\curvearrowright} X$ . Since  $\gamma : X \rightarrow X : x \mapsto \gamma x$  is an isometry for each  $\gamma \in \Gamma$ , there exists the extension  $\bar{\gamma} : \bar{X} \rightarrow \bar{X}$  of  $\gamma$  which is a homeomorphism (see [2, Corollary 8.9]). Thus, we have a homeomorphism  $\gamma = \bar{\gamma}|_{\partial X} : \partial X \rightarrow \partial X$  for each  $\gamma \in \Gamma$ . Fix  $x_0 \in X$ . The map  $\gamma$  induces a shape morphism  $\gamma_X = (\gamma_{X,n}, \phi) : (S(x_0, n), r_n) \rightarrow (S(x_0, n), r_n)$  such that  $\bar{\gamma}(X_{\phi(n)}) \subset X_n$  for each  $n \in \mathbb{N}$  and  $\gamma(\bar{x}) = \lim_{n \rightarrow \infty} \gamma_{X,n}(\bar{p}_{\phi(n)}(\bar{x}))$  for each  $\bar{x} \in \partial X$ , where  $X_n = \{x \in X : d(x_0, x) \geq n\}$ ,  $\gamma_{X,n} = p_n \circ \bar{\gamma}|_{S(x_0, \phi(n))} : S(x_0, \phi(n)) \rightarrow S(x_0, n)$  and  $\bar{p}_n : \bar{X} \rightarrow \bar{B}(x_0, n)$  is the extension of  $p_n$  for each  $n \in \mathbb{N}$ . See [11].

*Remark 2.2.* Let  $(X_i, d_i)$  be a proper CAT(0) space. Fix  $x_i \in X_i$  for  $i = 0, 1$ . By Remark 2.1, we have  $\partial X_i = \varprojlim (S(x_i, n), r_{i,n})$ , where  $r_{i,n} = p_{i,n}|_{S(x_i, n+1)} : S(x_i, n+1) \rightarrow S(x_i, n)$  for each  $n \in \mathbb{N}$ . By [1], we have that  $\partial X_0$  and  $\partial X_1$  are shape equivalent if and only if there exist two functions  $\psi, \psi' : \mathbb{N} \rightarrow \mathbb{N}$ , maps  $f_n : S(x_0, \psi^n(1)) \rightarrow S(x_0, \psi'^n(1))$ , and,  $g_n : S(x_0, \psi'^{n+1}(1)) \rightarrow S(x_0, \psi^n(1))$  satisfying the following homotopy commutative diagram:

$$\begin{array}{ccccccc}
 S(x_0, \psi(1)) & \xleftarrow{\pi_1} & S(x_0, \psi^2(1)) & \xleftarrow{\pi_2} & S(x_0, \psi^3(1)) & \xleftarrow{\pi_3} & \dots \\
 f_0 \downarrow & \swarrow g_1 & \downarrow f_1 & \swarrow g_2 & \downarrow f_2 & \swarrow g_3 & \dots \\
 S(x_1, \psi'(1)) & \xleftarrow{\pi'_1} & S(x_1, \psi'^2(1)) & \xleftarrow{\pi'_2} & S(x_1, \psi'^3(1)) & \xleftarrow{\pi'_3} & \dots
 \end{array}$$

where  $\pi_k = r_{0, \psi^k(1)} \circ \dots \circ r_{0, \psi^{k+1}(1)-1}$  and  $\pi'_k = r_{1, \psi'^k(1)} \circ \dots \circ r_{1, \psi'^{k+1}(1)-1}$ .

Let  $f : X_0 \rightarrow X_1$  be a proper homotopy equivalence with a proper homotopy inverse  $g : X_1 \rightarrow X_0$ . Then it is easy to construct shape morphisms  $\mathbf{f} = (f_n, \psi) : (S(x_0, \psi^n(1)), r_{0,n}, \mathbb{N}) \rightarrow (S(x_0, \psi'^n(1)), r_{1,n}, \mathbb{N})$  and  $\mathbf{g} = (g_n, \psi') : (S(x_0, \psi'^n(1)), r_{1,n}, \mathbb{N}) \rightarrow (S(x_0, \psi^n(1)), r_{0,n}, \mathbb{N})$ , induced by  $f$  and  $g$ , respectively which satisfy the above. In particular, if  $f : X_0 \rightarrow X_1$  is a proper  $\Gamma$ -map,  $\mathbf{f}\gamma_{X_0} = \gamma_{X_1}\mathbf{f}$  for each  $\gamma \in \Gamma$ .

Let  $Q$  be the Hilbert cube, i.e.,  $[-1, 1]^\infty$ .

**Proposition 2.3.** *Let  $(X_i, d_i)$  be a proper CAT(0) space for  $i = 0, 1$ . The following are equivalent:*

- (1) *There exists a proper homotopy equivalence map  $f : X_0 \rightarrow X_1$ ;*
- (2)  *$\partial X_0$  and  $\partial X_1$  are shape equivalent;*
- (3)  *$X_0 \times Q$  and  $X_1 \times Q$  are homeomorphic;*
- (4) *There exists a simple homotopy equivalence map  $f' : X_0 \rightarrow X_1$ .*

*In particular, every proper homotopy equivalence map from  $X_0$  to  $X_1$  is a simple homotopy equivalence.*

*Proof.* Let  $incl_i : X_i = X_i \times \{0\} \hookrightarrow X_i \times Q$  be the inclusion and let  $\alpha_i : X_i \times Q \rightarrow X_i$  be the projection.

(1)  $\implies$  (2): See Remark 2.2.

(3)  $\implies$  (1): Let  $h : X_0 \times Q \rightarrow X_1 \times Q$  be a homeomorphism. Thus, we have two proper maps  $f = \alpha_2 \circ h \circ incl_1 : X_0 \rightarrow X_1$  and  $g = \alpha_1 \circ h^{-1} \circ incl_2 : X_1 \rightarrow X_0$  such that  $g \circ f$  is proper homotopic to the identity map  $id_{X_0}$  and  $f \circ g$  is proper homotopic to the identity map  $id_{X_1}$ .

(2)  $\implies$  (3): Let  $\overline{X}_i = X \cup \partial X_i$  which is AR for  $i = 0, 1$ . By [4],  $\overline{X}_i \times Q$  is homeomorphic to  $Q$ . Since  $\partial X_i \times Q$  is a Z-set in  $\overline{X}_i \times Q$  for  $i = 0, 1$ , by [4, Theorem 25.2],  $X_0 \times Q$  is homeomorphic to  $X_1 \times Q$ .

(1)  $\iff$  (4): It suffices to show (1)  $\implies$  (4). Let  $f$  be a proper homotopy equivalence. By [6, Theorem 7], there exists a homeomorphism  $h : X_0 \times Q \rightarrow X_1 \times Q$  which is proper homotopic to  $f \times id_Q : X_0 \times Q \rightarrow X_1 \times Q$ . Let  $\alpha_i : X_i \times Q \rightarrow X_i$  be the projection for  $i = 0, 1$ . By a proper homotopy commutative diagram

$$\begin{array}{ccc}
 X_0 \times Q & \xrightarrow{h} & X_1 \times Q \\
 \text{id}_{X_0 \times Q} \downarrow & & \downarrow \text{id}_{X_1 \times Q} \\
 X_0 \times Q & \xrightarrow{f \times \text{id}_Q} & X_1 \times Q \\
 \alpha_0 \downarrow & & \downarrow \alpha_1 \\
 X_0 & \xrightarrow{f} & X_0
 \end{array}$$

we have  $f \circ \alpha_0 \simeq_p \alpha_1 \circ h$ , thus  $f$  is a simple homotopy equivalence.  $\square$

**Example 2.4.** For  $i = 0, 1$  let  $Z_i$  be a continuum such that  $Z_0$  and  $Z_1$  are shape equivalent. By [3] or [9], for  $i = 0, 1$  there exists a proper CAT(0) space  $(X_i, d_i)$  such that  $\partial X_i$  is homeomorphic to  $Z_i$ . By Proposition 2.3,  $X_0$  and  $X_1$  are simple homotopy equivalent.

### 3. THE EXISTENCE OF PROPER MAP

Let  $\Gamma$  be a group and for  $i = 0, 1$  let  $(X_i, d_i)$  be a proper CAT(0) space with  $\Gamma \overset{geo.}{\curvearrowright} X_i$ . In [12, Theorem C], it was proved that there exists a proper  $\Gamma$ -homotopy equivalence  $f : X_0 \rightarrow X_1$ . But, in this section we give a more direct proof by no use of a polyhedral resolution of boundaries.

**Lemma 3.1.** *Let  $\Gamma$  be a group, let  $(X, d)$  be a proper CAT(0) space with  $\Gamma \overset{geo.}{\curvearrowright} X$ , and, let  $f : X \rightarrow X$  be a proper  $\Gamma$ -map. Then there exists a proper  $\Gamma$ -homotopy  $H : X \times [0, 1] \rightarrow X$  from  $f$  to the identity map  $id_X$ . In particular, for every subgroup  $G$  of  $\Gamma$ ,  $H|_{X^G} : X^G \times [0, 1] \rightarrow X^G$  is a proper homotopy from  $f|_{X^G} : X^G \rightarrow X^G$  to the identity map  $id_{X^G}$ .*

*Sketch of proof.* Since  $\Gamma \overset{\text{geo.}}{\curvearrowright} X$  and  $f$  is a  $\Gamma$ -map, there exists  $r > 0$  such that  $d(f, \text{id}_X) < r$ . For every  $x \in X$  Let  $c_x : [0, d(f(x), x)] \rightarrow X$  be a geodesic connecting from  $f(x)$  to  $x$ . Define  $H : X \times [0, 1] \rightarrow X$  by  $H(x, t) = c_x(td(f(x), x))$  for each  $x \in X$  and each  $t \in [0, 1]$ . It is clear that  $H$  is a proper homotopy from  $f$  to  $\text{id}_X$ . In particular, if  $f : X \rightarrow X$  is a  $\Gamma$ -map, so is  $H$ .  $\square$

**Definition 3.2.** [2, p. 179] Let  $(X, d)$  be a metric space, let  $Y$  be a bounded set of  $X$  and let  $Z$  be a closed subset of  $X$ . The *radius* of  $Y$  at  $Z$ , is defined by

$$r_Z(Y) = \inf\{r > 0 : x \in Z, Y \subset \overline{B}(x, r)\}.$$

For simplicity of notation, if  $X = Z$ , we write  $r(Y)$  instead of  $r_X(Y)$ .

**Proposition 3.3.** [2, Proposition II 2.7] Let  $(X, d)$  be a complete CAT(0) space, let  $Y$  be a bounded set of  $X$  and let  $Z$  be a closed convex subset of  $X$ . Then there exists a unique point  $c_Z(Y) \in Z$ , called the *centre* of  $Y$  at  $Z$ , such that  $Y \subset \overline{B}(c_Z(Y), r_Z(Y))$ .

*Sketch of proof.* There exist a sequence  $\{z_n\}_{n \in \mathbb{N}}$  of  $Z$  and  $\{r_n\}_{n \in \mathbb{N}}$  of  $\mathbb{R}_+$  such that  $r_Z(Y) = \lim_{n \rightarrow \infty} r_n$  and  $Y \subset \overline{B}(z_n, r_n)$  for all  $n \in \mathbb{N}$ . We can show that for every  $\epsilon > 0$  there exist  $R, R' > 0$  with  $R > r_Z(Y) > R' > 0$  such that  $\text{diam}[z_n, z_{n'}] < 2\epsilon$  for any  $n, n' \in \mathbb{N}$  with  $r_n, r_{n'} < R$ . This shows that  $\{z_n\}_{n \in \mathbb{N}}$  is a Cauchy sequence, so  $c_Z(Y) = \lim_{n \rightarrow \infty} z_n$ , and establishes the uniqueness of  $c_Z(Y)$ .  $\square$

**Lemma 3.4.** Let  $\Gamma$  be a group and let  $(X, d)$  be a complete CAT(0) space with  $\Gamma \overset{\text{iso.}}{\curvearrowright} X$ . Then  $X^G = \{x \in X : \gamma x = x \text{ for all } \gamma \in G\}$  is a convex set for each subgroup  $G$  of  $\Gamma$ . In particular,  $X^G$  is a nonempty convex set for each finite subgroup  $G$  of  $\Gamma$ .

*Sketch of proof.* Fix  $x, x' \in X^G$ . Let  $\xi : [0, d(x, x')] \rightarrow X$  be a geodesic from  $x$  to  $x'$ . Since  $\xi(2^{-1}d(x, x')) \in X^G$ , we have  $\{\xi(2^{-n}kd(x, x')) : n, k \in \mathbb{N}, 0 \leq k \leq 2^n\} \subset X^G$ , thus,  $\xi([0, d(x, x')]) \subset X^G$ . Let  $G$  be a finite subgroup of  $\Gamma$  and fix  $x_0 \in X$ . By Proposition 3.4,  $c(Gx_0) \in X^G$ , thus it is nonempty.  $\square$

**Definition 3.5.** Let  $\Gamma$  be a group and let  $K = |\mathcal{K}|$  be a simplicial complex with  $\Gamma \curvearrowright K$ . Set  $\Gamma^x = \{\gamma \in \Gamma : \gamma x = x\}$  for  $x \in K$  and  $\Gamma^A = \bigcap_{y \in A} \Gamma^y$  for  $A \subset K$ .  $\Gamma \curvearrowright K$  is *simplicial* if it is satisfied the following;

- (1)  $\gamma : K \rightarrow K$  is a simplicial map for each  $\gamma \in \Gamma$ ;
- (2)  $\Gamma^\sigma = \{\gamma \in \Gamma : \gamma\sigma = \sigma\}$  for each  $\sigma \in \mathcal{K}$ .

The proof of the following result is based on the proof of [8, p.286, Theorem A.2].

**Lemma 3.6.** *Let  $\Gamma$  be a group, let  $(X, d)$  be a proper CAT(0) space with  $\Gamma \overset{\text{geo.}}{\curvearrowright} X$ , and, let  $K$  be a locally finite simplicial complex with  $\Gamma \overset{\text{coc.,pro.}}{\curvearrowright} K$  such that  $\Gamma \overset{\text{geo.}}{\curvearrowright} X$  is simplicial. Then, for every  $\Gamma$ -invariant subcomplex  $L$  of  $K$  and every proper  $\Gamma$ -map  $f : L \rightarrow X$ , there exists a proper  $\Gamma$ -map  $\tilde{f} : K \rightarrow X$  such that  $\tilde{f}|_L = f$ .*

*Proof.* Let  $\mathcal{K}$  be a subdivision of  $K$  and let  $\mathcal{K}^{(n)}$  be the  $n$ -skeleton of  $\mathcal{K}$ . We show by induction on  $n$  that for every proper  $\Gamma$ -map  $f_n : L \cup |\mathcal{K}^{(n)}| \rightarrow X$ , there exists a proper  $\Gamma$ -map  $f_{n+1} : L \cup |\mathcal{K}^{(n+1)}| \rightarrow X$  such that  $f_{n+1}|_{L \cup |\mathcal{K}^{(n)}|} = f_n$ .

By assumption, there exists a finite subset  $S_0$  of  $|\mathcal{K}^{(0)}| \setminus L$  such that  $\Gamma S_0 = |\mathcal{K}^{(0)}| \setminus L$ , and,  $\Gamma v \cap S_0 = \{v\}$  for each  $v \in S_0$ . Since  $\Gamma \overset{\text{pro.}}{\curvearrowright} K$ ,  $\Gamma^v = \{\gamma \in \Gamma :$

$\gamma v = v\}$  is a finite subgroup of  $\Gamma$  for each  $v \in S_0$ . By Lemma 3.5,  $X^{\Gamma^v} = \{x \in X : \gamma x = x \text{ for all } \gamma \in \Gamma^v\}$  is nonempty for each  $v \in S_0$ . Choose  $\tilde{v} \in X^{\Gamma^v}$ . Let us define  $f_0 : L \cup |\mathcal{K}^{(0)}| \rightarrow X$  by  $f_0|_L = f$  and  $f_0(\gamma v) = \gamma \tilde{v}$  for each  $v \in S_0$  and each  $\gamma \in \Gamma$ . Let  $\gamma, \gamma' \in \Gamma$  and  $v, v' \in S_0$  with  $\gamma v = \gamma' v'$ . We show that  $\gamma \tilde{v} = \gamma' \tilde{v}'$ . Since  $\Gamma v \cap S_0 = \{v\}$  for each  $v \in S_0$ , we have  $v = v'$ , thus,  $\gamma^{-1} \gamma' \in \Gamma^v$ . Hence,  $\gamma^{-1} \gamma' \tilde{v} = \tilde{v}$ , and finally that  $\gamma \tilde{v} = \gamma' \tilde{v}'$ . Therefore,  $f_0$  is well-defined and a  $\Gamma$ -map. We show that  $f_0$  is a proper map, i.e.,  $f_0^{-1}(Z)$  is compact for each compact set  $Z \subset X$ . Let  $\Gamma_Z(v) = \{\gamma \in \Gamma : \gamma f_0(v) \in Z\}$  for each  $v \in S_0$ . Since  $\Gamma \overset{\text{pro.}}{\curvearrowright} X$ ,  $\Gamma_Z(v)$

is finite. Since  $f_0^{-1}(Z) \subset f^{-1}(Z) \cup \bigcup \{\gamma v : v \in S_0, \gamma \in \Gamma_Z(v)\}$ ,  $f_0^{-1}(Z)$  is compact.

Let  $f_n : L \cup |\mathcal{K}^{(n)}| \rightarrow X$  be a proper  $\Gamma$ -map for  $n \geq 0$ . By assumption, there exists a finite subset  $S_{n+1}$  of  $\mathcal{K}^{(n+1)} \setminus \mathcal{K}^{(n)}$  such that  $\Gamma(\bigcup_{\sigma \in S_{n+1}} \text{int}\sigma) = |\mathcal{K}^{(n+1)}| \setminus (L \cup |\mathcal{K}^{(n)}|)$ , and,  $\Gamma(\text{int}\sigma) \cap \bigcup_{\sigma \in S_{n+1}} \sigma = \text{int}\sigma$  for each  $\sigma \in S_{n+1}$ , where  $\partial\sigma = \bigcup \{\tau : \tau \text{ is a proper face of } \sigma\}$  and  $\text{int}\sigma = \sigma \setminus \partial\sigma$ . Let  $\sigma \in S_{n+1}$ . Recall  $\Gamma^\sigma = \{\gamma \in \Gamma : \gamma z = z \text{ for each } z \in \sigma\}$ . Since  $\Gamma^z$  is finite and  $\Gamma^\sigma \subset \Gamma^z$  for each  $z \in \sigma$ ,  $\Gamma^\sigma$  is a finite subgroup of  $\Gamma$ . It is clear that  $f(\partial\sigma) \subset X^{\Gamma^\sigma} = \{x \in X : \gamma x = x \text{ for all } \gamma \in \Gamma^\sigma\}$ . By Proposition 3.4, we have the centre  $c(f(\partial\sigma))$  of  $f(\partial\sigma)$  in  $X$ . Since  $\Gamma \overset{\text{iso.}}{\curvearrowright} X$ , by Proposition 3.4, we see that  $c(f(\partial\sigma)) \in X^{\Gamma^\sigma}$ . Set  $c(f(\partial\sigma)) * f(\partial\sigma) = \bigcup \{[c(f(\partial\sigma)), x] : x \in f(\partial\sigma)\}$ . Let  $c(\sigma)$  be the barycenter of  $\sigma$  and let  $f_{n+1,\sigma} : \sigma = c(\sigma) * \partial\sigma \rightarrow c(f(\partial\sigma)) * f(\partial\sigma) \subset X$  be the cone on  $f_n|_{\partial\sigma}$ . By Lemma 3.5,  $X^{\Gamma^\sigma}$  is a convex subset of  $X$ , so  $f_{n+1,\sigma}(\sigma) \subset X^{\Gamma^\sigma}$ . Define a map  $f_{n+1} : L \cup |\mathcal{K}^{(n+1)}| \rightarrow X$  satisfying  $f_{n+1}|_{L \cup |\mathcal{K}^{(n)}|} = f_n$  by  $f_{n+1}(\gamma z) = \gamma f_{n+1,\sigma}(z)$  for each  $\sigma \in S_{n+1}$ , each  $z \in \text{int}\sigma$ , and, each  $\gamma \in \Gamma$ . Let  $\gamma, \gamma' \in \Gamma$ ,  $\sigma, \sigma' \in S_{n+1}$ , and,  $z \in \text{int}\sigma, z' \in \text{int}\sigma'$  with  $\gamma z = \gamma' z'$ . We show that  $f_{n+1}(\gamma z) = f_{n+1}(\gamma' z')$ . By the definition of  $S_{n+1}$ , we see  $\sigma = \sigma'$ . Since  $\Gamma \overset{\text{iso.}}{\curvearrowright} X$  is simplicial, we have  $\gamma^{-1} \gamma' \in \Gamma^\sigma$ , hence,  $z = z'$ . Since  $f_{n+1,\sigma}(\sigma) \subset X^{\Gamma^\sigma}$ , we have  $\gamma^{-1} \gamma' f_{n+1,\sigma}(z) = f_{n+1,\sigma}(z)$ , hence,  $f_{n+1}(\gamma z) = f_{n+1}(\gamma' z')$ . Therefore,  $f_{n+1}$  is well-defined and a  $\Gamma$ -map.

We show that  $f_{n+1}$  is a proper map, i.e.,  $f_{n+1}^{-1}(Z)$  is compact for each compact set  $Z \subset X$ . Let  $\Gamma_Z(\sigma) = \{\gamma \in \Gamma : \gamma f_{n+1}(\sigma) \in Z\}$  for each  $\sigma \in S_{n+1}$ . Since  $\Gamma \overset{\text{pro.}}{\curvearrowright} X$ ,  $\Gamma_Z(\sigma)$  is finite. Since  $f_{n+1}^{-1}(Z) \subset f^{-1}(Z) \cup \bigcup \{\gamma v : \sigma \in S_{n+1}, \gamma \in \Gamma_Z(\sigma)\}$ ,  $f_{n+1}^{-1}(Z)$  is compact.  $\square$

We show the following lemma, and it directly follows from [12, Proposition A], but we give a more direct proof based on the proof of it.

**Lemma 3.7.** *Let  $\Gamma$  be a group and for  $i = 0, 1$  let  $(X_i, d_i)$  be a proper CAT(0) space with  $\Gamma \overset{geo.}{\curvearrowright} X_i$ . Then there exists a proper  $\Gamma$ -map  $f : X_0 \rightarrow X_1$*

*Proof.* By  $\Gamma \overset{coc.}{\curvearrowright} X_0$ , there exist a compact set  $C$  of  $X_0$  such that  $\Gamma C = X_0$ . By [2, Proposition I.8.5(1)], for every  $x \in C$  there exists  $\epsilon_x > 0$  such that every  $\gamma \in \Gamma$ ,

$$\gamma x = x \text{ or } \overline{B}(x, \epsilon_x) \cap \gamma \overline{B}(x, \epsilon_x) = \emptyset. \quad (1)$$

Thus, there exist a finite subset  $X'_0 = \{x_0, \dots, x_l\}$  of  $C$  such that  $\Gamma \mathcal{V}$  is a locally finite open cover of  $X_0$  and  $U \not\subset \bigcup \{U' \in \Gamma \mathcal{V} : U \neq U'\}$  for each  $U \in \Gamma \mathcal{V}$ , where  $\mathcal{V} = \{B(x_i, \epsilon_{x_i}) : i = 0, \dots, l\}$ .

Let  $\mathcal{L}$  be the nerve of  $\Gamma \mathcal{V}$ , i.e.,  $\mathcal{L}^{(0)} = \mathcal{U}$ , and,  $\langle U_0, \dots, U_k \rangle \in \mathcal{L}$  if and only if  $U_0 \cap \dots \cap U_k \neq \emptyset$ . Set  $L = |\mathcal{L}|$ . For every  $\gamma \in \Gamma$ , define a simplicial map  $\gamma : L \rightarrow L$  by  $\gamma(\langle U_0, \dots, U_k \rangle) = \langle \gamma U_0, \dots, \gamma U_k \rangle$  for each  $\langle U_0, \dots, U_k \rangle \in \mathcal{L}$ . Since  $U = \gamma U$  whenever  $U \cap \gamma U \neq \emptyset$ , we have  $\Gamma \curvearrowright L$ .

Let  $\gamma \in \Gamma$  and  $\langle U_0, \dots, U_k \rangle \in \mathcal{L}$  such that  $\gamma(\langle U_0, \dots, U_k \rangle) = \langle U_0, \dots, U_k \rangle$ , i.e.,  $\{U_0, \dots, U_k\} = \{\gamma U_0, \dots, \gamma U_k\}$ . Since  $\bigcap_{i=0}^k U_i = \bigcap_{i=0}^k \gamma U_i \neq \emptyset$ , we have  $U_i \cap \gamma U_i \neq \emptyset$ , hence,  $U_i = \gamma U_i$  for each  $i = 0, \dots, k$ . Therefore,  $\Gamma \curvearrowright L$  is simplicial.

We show that  $\Gamma \overset{coc.}{\curvearrowright} L$ . Let  $\mathcal{J} = \{\langle V_0, \dots, V_k \rangle \in \mathcal{L} : V_i \in \mathcal{V} \text{ for each } i\}$  such that  $|\mathcal{J}|$  is a finite subcomplex of  $L$ . It suffices to show that  $L = \Gamma |St(\mathcal{J}, \mathcal{L})|$ , where  $St(\mathcal{J}, \mathcal{L}) = \{\sigma \in \mathcal{L} : \sigma \cap |\mathcal{J}| \neq \emptyset\}$  is the close star of  $\mathcal{J}$  in  $\mathcal{L}$ . Let  $\langle \gamma_0 V_0, \dots, \gamma_k V_k \rangle \in \mathcal{L}$  such that  $\gamma_i \in \Gamma$  and  $V_i \in \mathcal{V}$  for each  $i = 0, \dots, k$ . Since  $\gamma_0 V_0 \cap \dots \cap \gamma_k V_k \neq \emptyset$ , we have  $V_0 \cap \gamma_0^{-1} \gamma_1 V_1 \cap \dots \cap \gamma_0^{-1} \gamma_k V_k \neq \emptyset$ . Since  $V_0 \in \mathcal{J}^{(0)}$ , we have  $\langle V_0, \gamma_0^{-1} \gamma_1 V_1, \dots, \gamma_0^{-1} \gamma_k V_k \rangle \in St(\mathcal{J}, \mathcal{L})$ . Since  $\langle \gamma_0 V_0, \dots, \gamma_k V_k \rangle = \gamma_0 \langle V_0, \gamma_0^{-1} \gamma_1 V_1, \dots, \gamma_0^{-1} \gamma_k V_k \rangle \in \gamma_0 St(\mathcal{J}, \mathcal{L})$ , we have  $|\langle \gamma_0 V_0, \dots, \gamma_k V_k \rangle| \in \Gamma |St(\mathcal{J}, \mathcal{L})|$ , thus,  $L = \Gamma |St(\mathcal{J}, \mathcal{L})|$ . By the above, we see that  $\dim L = \dim |St(\mathcal{J}, \mathcal{L})| < \infty$ .

We show that  $\Gamma \overset{pro.}{\curvearrowright} L$ . Since  $\mathcal{L}^{(0)} = \Gamma \mathcal{J}^{(0)}$ , it suffices to show that for any  $V \in \mathcal{V}$ ,  $\{\gamma \in \Gamma : |St(V, \mathcal{L})| \cap \gamma |St(V, \mathcal{L})| \neq \emptyset\}$  is finite. This follows that  $\{\gamma \in \Gamma : V \cap \gamma V' \neq \emptyset\}$  is finite for each  $V' \in \mathcal{V}$  with  $\gamma' \in \Gamma$  and  $V \cap \gamma' V' \neq \emptyset$ .

We construct the canonical map  $f_0 : X_0 \rightarrow L$ . Let  $x \in X_0$ . Set  $\{U \in \Gamma \mathcal{V} : x \in U\} = \{U_0, \dots, U_k\}$ . Define

$$\lambda_i(x) = \frac{d(x, X_0 \setminus U_i)}{\sum_{j=0}^k d(x, X_0 \setminus U_j)} \text{ and } f_0(x) = \sum_{i=0}^k \lambda_i(x) U_i \in \langle U_0, \dots, U_k \rangle.$$

Since  $f_0^{-1}(\langle U_0, \dots, U_k \rangle) \subset U_0 \cup \dots \cup U_k$ , we see that  $f_0$  is a proper map. Since  $\gamma : X_0 \rightarrow X_0$  is an isometry, for every  $\gamma \in \Gamma$  we have

$$\lambda_i(\gamma x) = \frac{d(\gamma x, X_0 \setminus \gamma U_i)}{\sum_{j=0}^k d(\gamma x, X_0 \setminus \gamma U_j)} = \frac{d(x, X_0 \setminus U_i)}{\sum_{j=0}^k d(x, X_0 \setminus U_j)} = \lambda_i(x),$$

thus, since  $\gamma : L \rightarrow L$  is a simplicial map,

$$f_0(\gamma x) = \sum_{i=0}^k \lambda_i(\gamma x) \gamma U_i = \sum_{i=0}^k \lambda_i(x) \gamma U_i = \gamma \left( \sum_{i=0}^k \lambda_i(x) U_i \right) = \gamma f_0(x),$$

thus,  $f_0$  is a  $\Gamma$ -map.

By Lemma 3.7, there exists a proper  $\Gamma$ -map  $f_1 : L \rightarrow X_1$ , therefore, we have a proper  $\Gamma$ -map  $f = f_1 \circ f_0 : X_0 \rightarrow X_1$ , which completes the proof.  $\square$

Let  $L$  be as in the proof of Lemma 3.8. We can think of  $L$  as a piecewise Euclidean complex, a locally finite simplicial complex with the intrinsic pseudo-metric  $\rho$  (see [2, pp.98-99]) such that a length of every 1-simplex in  $\mathcal{L}$  is one. Since  $\text{Shape}(L)$  is finite (see [2, p.98]),  $(L, \rho)$  is a complete geodesic space ([2, Theorem I.7.19, p.105]). In particular, by the construction of  $(L, \rho)$ ,  $\gamma : (L, \rho) \rightarrow (L, \rho)$  is an isometry for each  $\gamma \in \Gamma$ , i.e.,  $\Gamma \overset{iso.}{\curvearrowright} L$ .

*The proof of Proposition 1.3.* By Lemma 3.8, for  $i = 0, 1$  there exist proper  $\Gamma$ -maps  $f : X_0 \rightarrow X_1$  and  $g : X_1 \rightarrow X_0$ . By Remark 2.2, Proposition 2.3 and Lemma 3.1,  $f$  and  $g$  satisfy the conditions in Proposition 1.3, which completes the proof.  $\square$

#### 4. QUESTIONS

**Question 4.1.** Let  $\Gamma$  be a group, let  $(X_i, d)$  be a proper CAT(0) space with  $\Gamma \overset{geo.}{\curvearrowright} X_i$ , and let  $f : X_0 \rightarrow X_1$  be a proper  $\Gamma$ -map. Does there exist an ANR proper metric space  $Z$  with  $\Gamma \overset{geo.}{\curvearrowright} Z$  and proper cell-like  $\Gamma$ -maps  $\alpha : Z \rightarrow X_0$ ,  $\alpha' : Z \rightarrow X_1$  such that  $f \circ \alpha$  is proper  $\Gamma$ -homotopic to  $\alpha'$ ?, i.e., is  $f : X_0 \rightarrow X_1$  a simple  $\Gamma$ -homotopy equivalence?

**Question 4.2.** Let  $\Gamma$  be a group and let  $(X, d)$  be a proper CAT(0) space with  $\Gamma \overset{geo.}{\curvearrowright} X$ . If there exists a compact ANR metric space  $Z$  which is shape  $(\Gamma)$ -equivalent to  $\partial X$ , is  $\partial X$  ANR?

**Question 4.3.** Let  $\Gamma$  be a group and let  $(X_i, d)$  be a proper CAT(0) space with  $\Gamma \overset{geo.}{\curvearrowright} X_i$  such that  $\partial X_i$  is ANR for  $i = 0, 1$ .

- (1) Does there exist a  $\Gamma$ -homotopy equivalence map from  $\partial X_0$  and  $\partial X_1$ ?
- (2) Are  $\partial X_0$  and  $\partial X_1$  simple homotopy equivalent?



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