Hyperfunctions and Čech-Dolbeault cohomology in the microlocal point of view

By

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Abstract

In this note, we explain how to construct the boundary value map $b_{\Omega} : \mathscr{O}(\Omega) \to \mathscr{B}(M)$ of Sato's hyperfunction in the framework of Čech-Dolbeault cohomology.

§1. Introduction

The boudnary value map b_{Ω} is the most important morphism in the hyperfunction theory, by which we can understand a hyperfunction to be the sum of boundary values of holomorphic functions defined on wedges along a real analytic manifold. As was explained in [2] of this volume, the theory of Čech-Dolbeault cohomology brings several benefits to the treatment of a hyperfunction, and as such an important example, we here explain how to construct the boundary value morphism in our framework. For an application to the theory of Laplace hyperfunctions, see [3] in this volume.

This is a joint work with Takashi Izawa and Tatsuo Suwa.

§2. Boundary value morphism

Let M be a real analytic manifold assumed to be orientable and countable at infinity, and let X be its complexification. Note that, through the note, we use the same notations as those in [2] of this volume.

Let Ω be an open subset in X, for which we introduce the following two conditions: (B₁) $\overline{\Omega} \supset M$.

(B₂) The inclusion $(X \setminus \Omega) \setminus M \hookrightarrow X \setminus \Omega$ gives a homotopy equivalence.

²⁰¹⁰ Mathematics Subject Classification(s): Primary 32A45; Secondary 32C35. Supported by JSPS Grant 18K03316

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For example, a usual convex wedge Ω along M like a left shape in Fig. 1 satisfies the condition (B₂). However, the right shape in the same figure that is a wedge along M in which the smaller one is removed violates (B₂) because $(X \setminus \Omega) \setminus M$ consists of two connected components while $X \setminus \Omega$ is connected.

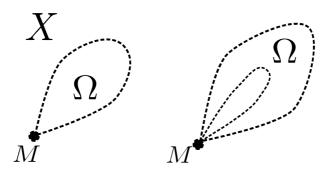


Figure 1. A good case (left) and bad case (right).

Set $\mathcal{W} = \{V_0 = X \setminus M, V_1 = X\}$ and $\mathcal{W}' = \{V_0\}$. We also set $V_{01} = V_0 \cap V_1$ as usual. In what follows, we always assume that Ω satisfies the above two conditions. Then we will define the following boundary value map

$$b_{\Omega}: \mathscr{O}(\Omega) \longrightarrow \mathscr{B}(M) = H^n_M(X; \mathscr{O}) \otimes_{\mathbb{Z}_M(M)} or_{M/X}(M)$$
$$\simeq H^{\mathfrak{g}, \mathfrak{n}}_{\mathfrak{G}, \mathfrak{n}}(\mathcal{W}, \mathcal{W}') \otimes_{\mathbb{Z}_M(M)} or_{M/X}(M)$$

using Čech-Dolbeault cohomology.

As M is orientable, we can take a global section $\mathbb{1}$ in $or_{M/X}(M)$ which generates each stalk of the sheaf $or_{M/X}$ over \mathbb{Z} . We fix such a section $\mathbb{1}$ hereafter.

The canonical sheaf morphism $\mathbb{Z}_X \to \mathbb{C}_X$ induces the morphism of \mathbb{Z} -modules

$$or_{M/X}(M) = H^n_M(X; \mathbb{Z}_X) \hookrightarrow H^n_M(X; \mathbb{C}_X) = H^n_D(\mathcal{W}, \mathcal{W}'),$$

which is clearly injective. The image in $H^n_M(X; \mathbb{C}_X)$ of 1 by this morphism is still denoted by the same symbol in what follows. The following lemma is crucial to our construction of b_{Ω} .

Lemma 2.1. Under the conditions (B₁) and (B₂), the $\mathbb{1} \in H^n_D(\mathcal{W}, \mathcal{W}')$ has a representative

$$(\nu_1,\nu_{01})\in\mathscr{E}^{(n)}(V_1)\oplus\mathscr{E}^{(n-1)}(V_{01})=\mathscr{E}^{(n)}(\mathcal{W},\mathcal{W}')$$

which satisfies $\operatorname{Supp}_{V_1}(\nu_1) \subset \Omega$ and $\operatorname{Supp}_{V_{01}}(\nu_{01}) \subset \Omega$ (see Fig. 2 also).

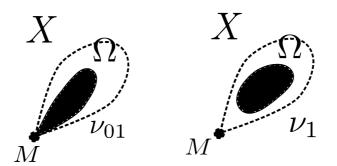


Figure 2. The support of ν_{01} and ν_1 indicated by black regions.

The canonical sheaf morphism $\iota : \mathbb{C}_X \to \mathscr{O}$ induces the canonical morphisms of \mathbb{C} -vector spaces :

$$H^k(\iota): H^k_M(X; \mathbb{C}_X) \longrightarrow H^k_M(X; \mathscr{O}).$$

Its counterpart in the relative de Rham and relative Dolbeault cohomologies is, as was explained in Section 5 in [2], given by

$$\rho^k: \mathscr{E}^{(k)}(\mathcal{W}, \mathcal{W}') \to \mathscr{E}^{(0,k)}(\mathcal{W}, \mathcal{W}') \qquad \text{given by } (\omega_1, \omega_{01}) \mapsto (\omega_1^{(0,k)}, \omega_{01}^{(0,k-1)}).$$

Hereafter we often write ρ instead of ρ^n . We give an example of a ν in the above lemma for a typical case.

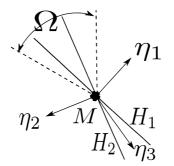


Figure 3. The typical picture of n = 2.

Example 2.2. Let $M = \mathbb{R}^n$, $X = \mathbb{C}^n$ and $\Omega = M \times \sqrt{-1}\Gamma$, where Γ is an open proper convex cone in \mathbb{R}^n . We first take *n* linearly independent unit vectors η_1, \ldots, η_n in \mathbb{R}^n_y so that

$$\bigcap_{1 \le k \le n} H_k \subset \mathbf{I}$$

holds, where we set $H_k = \{ y \in \mathbb{R}^n_y \mid \langle y, \eta_k \rangle > 0 \}$. We also set

$$\eta_{n+1} = -(\eta_1 + \dots + \eta_n).$$

Then, let φ_k , $k = 1, \ldots, n + 1$, be C^{∞} -functions on $X \smallsetminus M$ which satisfy

(1) $\operatorname{Supp}_{X \setminus M}(\varphi_k) \subset M \times \sqrt{-1}H_k$ for any $k = 1, \dots, n+1$. (2) $\sum_{k=1}^{n+1} \varphi_k = 1$ on $X \setminus M$. Set

$$\nu_{01} = (-1)^n (n-1)! \,\hat{\chi}_{H_{n+1}} \, d\varphi_1 \wedge \cdots \wedge d\varphi_{n-1},$$

where $\hat{\chi}_{H_{n+1}}$ is the anti-characteristic function of the set H_{n+1} , that is,

$$\hat{\chi}_{H_{n+1}}(z) = \begin{cases} 0 & z \in H_{n+1}, \\ 1 & \text{otherwise.} \end{cases}$$

Then we can easily confirm that $\nu_{01} \in \mathscr{E}^{(n-1)}(X \smallsetminus M)$ and

$$\operatorname{Supp}_{X \setminus M}(\nu_{01}) \subset M \times \sqrt{-1} \bigcap_{1 \leq k \leq n} H_k \subset \Omega.$$

Furthermore,

$$\nu = (0, \nu_{01}) \in \mathscr{E}^{(n)}(V_1) \oplus \mathscr{E}^{(n-1)}(V_{01}) = \mathscr{E}^{(n)}(\mathcal{W}, \mathcal{W}')$$

gives the image of a positively oriented generator of $or_{M/X}(M)$ under the standard orientations on M and X. Note that, by the definition of ρ , we have

$$\rho(\nu) = (0, (-1)^n (n-1)! \hat{\chi}_{H_{n+1}} \bar{\partial} \varphi_1 \wedge \dots \wedge \bar{\partial} \varphi_{n-1}) \in \mathscr{E}^{(0,n)}(\mathcal{W}, \mathcal{W}')$$

Let us construct the boundary value map. We first take, thanks to Lemma 2.1, $\nu = (\nu_1, \nu_{01}) \in \mathscr{E}^n(\mathcal{W}, \mathcal{W}')$ which is a representative of $\mathbb{1} \in or_{M/X}(M)$ and satisfies

$$\operatorname{Supp}_{X}(\nu_{1}) \subset \Omega, \qquad \operatorname{Supp}_{X \setminus M}(\nu_{01}) \subset \Omega$$

By tracing the image of 1 in the diagram below, we obtain $\rho(\nu)$ in $H^{0, n}_{\bar{\vartheta}}(\mathcal{W}, \mathcal{W}')$.

Then, using $\rho(\nu)$, we define the boundary map

(2.1)
$$b_{\Omega}: \mathscr{O}(\Omega) \to H^{0,n}_{\bar{\vartheta}}(\mathcal{W}, \mathcal{W}') \underset{\mathbb{Z}(M)}{\otimes} or_{M/X}(M) = \mathscr{B}(M)$$

by, for $f \in \mathscr{O}(\Omega)$,

(2.2)
$$b_{\Omega}(f) := [f\rho(\nu)] \otimes 1 \in H^{0,n}_{\bar{\vartheta}}(\mathcal{W}, \mathcal{W}') \underset{\mathbb{Z}(M)}{\otimes} or_{M/X}(M).$$

Lemma 2.3. The above b_{Ω} is well-defined. That is, b_{Ω} does not depend on the choice of 1 and ν .

Remark. Thus constructed $b_{\Omega}(\bullet)$ coincides with the original boundary value map by Sato-Kawai-Kashiwara [1].

The proposition below immediately comes from the definition:

Proposition 2.4. Let $\Omega' \subset \Omega$ be an open subset in X. Assume that Ω' also satisfies the conditions (B_1) and (B_2) . Then we have

$$b_{\Omega'}(f|_{\Omega'}) = b_{\Omega}(f), \qquad f \in \mathscr{O}(\Omega).$$

We can easily estimate the microlocal analyticity of the hyperfunction $b_{\Omega}(f)$. Before stating the estimate, we give the characterization of microlocal analyticity of a hyperfunction in our framework. For an open subset V in X, we set

$$\mathcal{W}_V = \{ V_0 = V \smallsetminus M, V_1 = V \} \text{ and } \mathcal{W}'_V = \{ V_0 \}.$$

Proposition 2.5. Let u be a hyperfunction at $x_0 \in M$. Then u is microlocally analytic at $p_0 = (x_0, \sqrt{-1}\xi_0) \in \sqrt{-1}T^*M$ if and only if there exist a closed cone $G \subset \mathbb{R}^n$ with the condition

$$G \setminus \{0\} \subset \{ y \in \mathbb{R}^n \mid \operatorname{Re} \langle \sqrt{-1}y, \sqrt{-1}\xi_0 \rangle > 0 \} = \{ y \in \mathbb{R}^n \mid \langle y, \xi_0 \rangle < 0 \},\$$

an open neighborhood V of x_0 and a representative

$$(\tau_1, \tau_{01}) \in \mathscr{E}^{(0,n)}(V_1) \oplus \mathscr{E}^{(0,n-1)}(V_{01}) = \mathscr{E}^{(0,n)}(\mathcal{W}_V, \mathcal{W}_V')$$

of u near x_0 which satisfies $\tau_1 = 0$ and $\operatorname{Supp}_{V \setminus M}(\tau_{01}) \subset \mathbb{R}^n_x \times \sqrt{-1}G$.

Then it follows from the above two propositions that we have:

Theorem 2.6. Let M be an open subset in \mathbb{R}^n_x and $X = M \times \sqrt{-1}\mathbb{R}^n_y$. Assume that $\Omega \cap (\{x_0\} \times \sqrt{-1}\mathbb{R}^n_y)$ is a non-empty convex cone for any $x_0 \in M$. Then we have

$$\mathrm{SS}(b_{\Omega}(f)) \subset \Omega^{\circ}, \qquad f \in \mathscr{O}(\Omega),$$

where Ω° is the polar set of Ω defined by

$$\bigsqcup_{x \in M} \left\{ \sqrt{-1}\xi \in (T^*_M X)_x \mid \langle \xi, y \rangle \ge 0 \text{ for any } y \text{ with } (x, \sqrt{-1}y) \in \Omega \right\} \subset T^*_M X.$$

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