

On space efficiency of Krivine's abstract machine and Hyland-Ong games

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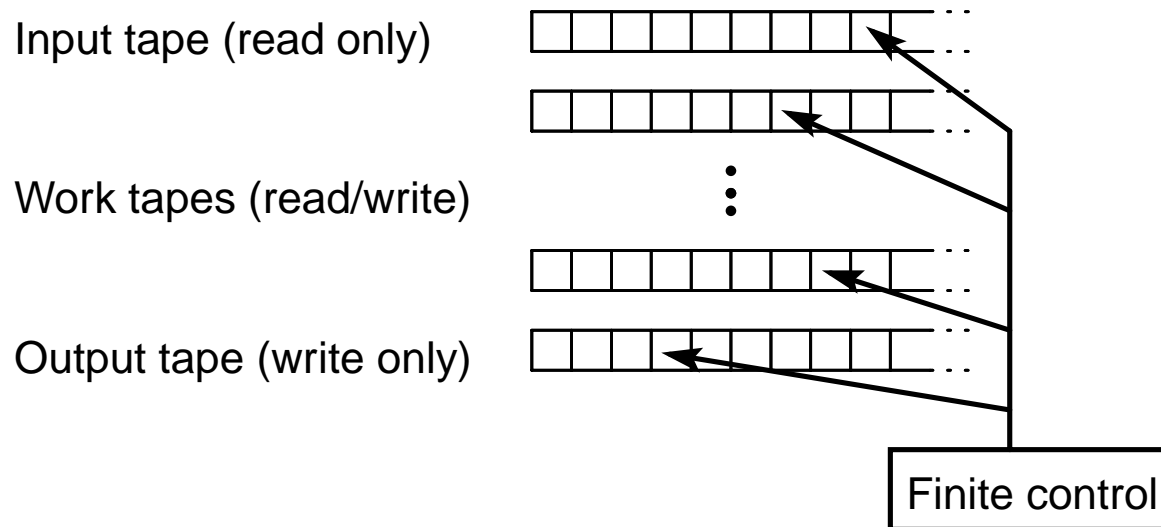
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ICC

- Intensional Computational Complexity (ICC)
 - algorithms (eg. λ terms)
 - evaluation mechanisms (eg. β -reduction)

Space sensitive Turing machines



- **Space** = the num of cells used on **worktapes**.
- The input and output can be significantly larger than the space:
If M works in space $f(n)$ then the output is of size $O(2^{f(n)})$.
- Given two Turing machines M , N , we want to **compose** them.
How?

Space sensitive Turing machines

- **Functional** composition is not good:
If M, N work in space $f(n), g(n)$, then $M; N$ works in space $O(f(n) + g(2^{f(n)}) + 2^{f(n)})$.
- In particular, logspace functions **do not** compose.
- Composition must be **interactive**: $M \rightleftharpoons N$ works in $O(f(n) + g(2^{f(n)}))$.
- **From functional to interactive computation!**

Towards a logical theory of computational complexity

- Shortcomings of Turing Machines:
 - Poor data structures (only tapes)
 - Poor control mechanisms (only transitions)
 - Ad hoc constructions: no canonical way of composition
 - Results in lack of beautiful mathematical theory
- Logic and lambda calculus
 - Rich data structures and controls
 - Canonical composition $T \circ U = \lambda x.T(U(x))$
 - Hope to make complexity theory more mathematical

Space in lambda calculus

- Composition does not preserve good space bounds when using β -reduction, because β -reduction is **not** interactive!
- **Interactive** evaluation mechanisms
 - Geometry of Interaction
 - Krivine's abstract machine (KAM)
 - Game semantics

KAM

- KAM implements **weak head linear reduction**:

$$(\lambda \cdots \lambda x \cdots .x\vec{U}) \cdots T \cdots \implies (\lambda \cdots \lambda x \cdots .T\vec{U}) \cdots T \cdots$$

- Gol with “jumps” under $A \Rightarrow B \equiv !(A \multimap B)$ (Danos-Regnier 94)
- Syntax:

Terms $t ::= x \mid \lambda x.t_1 \mid t_1 t_2$

Environments $\rho ::= [x_1 \mapsto t_1 \rho_1, \dots, x_n \mapsto t_n \rho_n]$

Closures $t\rho$

Stacks $\pi ::= t_1 \rho_1 : \cdots : t_n \rho_n$

States $S ::= (t\rho, \pi)$

KAM

- Initial state: $(t[], \text{nil})$

- Transitions

$$(x\rho, \pi) \longrightarrow (\rho(x), \pi) \quad \text{if } x \in \text{Dom}(\rho)$$

$$((tu)\rho, \pi) \longrightarrow (t\rho, u\rho : \pi)$$

$$((\lambda x.t)\rho, u\rho' : \pi) \longrightarrow (t\rho[x \mapsto u\rho'], \pi)$$

- Terminations

$(x\rho, \pi)$ with $x \notin \text{Dom}(\rho)$ — Success with output x

$((\lambda x.t)\rho, \text{nil})$ — Failure

- Not space efficient: ρ contains a lot of redundant bindings.

Optimized KAM

● Optimized transitions

$$(x\rho, \pi) \longrightarrow (\rho(x), \pi) \quad \text{if } x \in \text{Dom}(\rho)$$

$$((tx)\rho, \pi) \longrightarrow (t(\rho|_t), \rho(x) : \pi) \quad \text{if } x \in \text{Dom}(\rho)$$

$$((tu)\rho, \pi) \longrightarrow (t(\rho|_t), u(\rho|_u) : \pi) \quad \text{otherwise}$$

$$((\lambda x.t)\rho, u\rho' : \pi) \longrightarrow (t\rho[x \mapsto u\rho'], \pi)$$

● $\rho|_t$ is a **restriction** of ρ to the free variables of t .

Example

Suppose $(K[], \text{nil}) \longrightarrow^* (\lambda z.z, \text{nil})$, $\bar{2} = \lambda f x.f(fx)$.

$(\bar{2}Kc, \text{nil})$

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$(f[f \mapsto K], c)$

(K, c)

Size of a state

- **Subterm property:** if $(t[], \text{nil}) \longrightarrow^* S$, all terms occurring in S are subterms of t .
- Allows us to think of each state as made of **pointers** rather than actual terms.
- $\#S$ = the number of pointers in S :

$$\#\rho = \#\rho_1 + \dots + \#\rho_n + n \quad \text{if } \rho = [x_1 \mapsto t_1\rho_1, \dots, x_n \mapsto t_n\rho_n]$$

$$\#\pi = \#\rho_1 + \dots + \#\rho_n + n \quad \text{if } t_1\rho_1 : \dots : t_n\rho_n$$

$$\#(t\rho, \pi) = \#\rho + \#\pi + 1$$

- In particular, $\#(t[], \text{nil}) = 1$.
- KAM **evaluates** t **with** n **pointers** if for any intermediate state $(t[], \text{nil}) \longrightarrow^* S$, $\#S \leq n$.

TM space-efficiently simulates KAM

- Naively, TM requires of $\log n$ overhead to simulate KAM:
if KAM evaluates t with n pointers, then $M(t)$ works in space $O(n \cdot \log |t|)$.
- We are interested in terms td , where t (program) is fixed while d (input) is varying.
- Consider a huge alphabet

$$\Sigma = \{u \mid u \text{ is a subterm occ. of } t\} \cup \{0, 1\}$$

TM space-efficiently simulates KAM

- t satisfies the **input condition** if in any intermediate state $(td[], \text{nil}) \longrightarrow^* S$, the number of pointers pointing subterms of d is constant (independent of d).
- Analogy: the num of heads on input tape is fixed.
- **Theorem:** There is a TM M which simulates KAM **linearly**: if KAM evaluates td with $f(|d|)$ pointers, t satisfies the input condition and $f(x) \geq \log x$, then $M(t)$ works in space $O(f(|d|))$.

Data structures

- **Booleans:** $\mathbf{t} = \lambda xy.x$, $\mathbf{f} = \lambda xy.y$
- **Scott numerals:** \mathbf{w} for $w \in \{0, 1\}^*$

$$\varepsilon = \lambda x_\varepsilon x_0 x_1. x_\varepsilon$$

$$0 \cdot \mathbf{w} = \lambda x_\varepsilon x_0 x_1. x_0 \mathbf{w}$$

$$1 \cdot \mathbf{w} = \lambda x_\varepsilon x_0 x_1. x_1 \mathbf{w}$$

- Purely linear. Successor, predecessor and conditional are also linear. Useful for **worktapes**.
- What are **read-only/write-only tapes**?
- They should be **interactive entities** (analogy: Book vs Dialogue)

Data structures

● **Databases:** For $d \in \{0, 1\}^{2^n}$, define a term $\mathbf{d} : \text{Word} \rightarrow \text{Bool}$ s.t.

Given $w \in \{0, 1\}^n$, $\mathbf{d}w$ returns the w th bit of d .

$$\begin{aligned}\mathbf{d} &= \lambda w. w \mathbf{i} \Omega \Omega && \text{if } d = i \in \{0, 1\} \\ &= \lambda w. w \Omega \mathbf{d}_0 \mathbf{d}_1 && \text{if } d_1 = i_{2^n} \cdots i_{2^{n-1}+1}, \\ &&& d_0 = i_{2^{n-1}} \cdots i_1, d = d_1 d_0\end{aligned}$$

KAM space-efficiently simulates TM

- **Theorem:** For any TM M , there is a term t_M s.t.
 - Given $d \in \{0, 1\}^*$, $t_M \mathbf{d} *_0 *_1$ returns $*_0$ or $*_1$ according to the output of $M(d)$.
 - When M works in space $f(n) \geq \log n$, KAM evaluates $t_M \mathbf{d} *_0 *_1$ with $O(f(n))$ pointers.
- Now the **space hierarchy theorem** implies

There is no TM M that evaluates $t_M \mathbf{d}$ in space $O(f(n)^\epsilon)$ with $\epsilon < 1$.
- **Corollary:** There is no evaluator that is **uniformly** (i.e. for all terms) and **significantly** (i.e. super-linearly) more space-efficient than KAM.

Composition

- Let M, N be transducer TMs which work in space $f(n), g(n)$ and produce outputs of size $2^{f(n)}$ and $2^{g(n)}$.

$$t_M : (\text{Word} \rightarrow \text{Bool}) \longrightarrow (\text{Word} \rightarrow \text{Bool})$$

$$t_N : (\text{Word} \rightarrow \text{Bool}) \longrightarrow (\text{Word} \rightarrow \text{Bool})$$

$$t_M \circ t_N : (\text{Word} \rightarrow \text{Bool}) \longrightarrow (\text{Word} \rightarrow \text{Bool})$$

- $(t_N \circ t_M)\mathbf{dw} *_0 *_1$ returns the w th bit of $N \circ M(d)$.
- KAM evaluates it with $O(f(|d|) + g(|d'|))$ pointers, where d' is the output of $M(d)$.
- KAM + canonical composition simulates the interactive composition of TMs!

Moral

	Turing Machines	λ -calculus
Composition	non canonical	canonical
Evaluation	canonical	non canonical

- In λ -calculus, **TIME-SPACE tradeoff** shows up at the stage of evaluation:
 - KAM is space-efficient
 - CBV seems to be time-efficient (cf. Dal Lago-Martini).
- **Work to be done:** identify a subclass of λ -terms (via a type system) on which space bounds are well preserved by KAM composition.

Warning

- There is no **uniformly** more efficient evaluator than KAM.
- KAM is like a student Bob with score

Math	Science	Grammer	Latin	Music
1	1	1	1	10

- Although there is no **uniformly** better student than Bob, this does not mean Bob is the best student.

From KAM to HO games

- Empirically, KAM is good at “**tall**” terms:

$$t_n = (\lambda f x. f^n(x))(\lambda y. y) *$$

KAM evaluates t_n with $O(1)$ pointers.

- KAM is not good at “**wide**” terms:

$$u_n = (\lambda x_1 \cdots \lambda x_n. x_n) *_1 \cdots *_n$$

KAM evaluates u_n with $O(n)$ pointers.

- For simply typed terms with **unbounded** width and **fixed** rank, **HO games** seem to be more efficient.

H0 games

- A fully abstract model of PCF (Hyland-Ong 00). Successfully applied to various programming languages.
- Useful for compositional and higher-order model checking (Ghica-Mckusker 00, Ong 04, etc.)

Types = Arenas

Terms = Strategies

Computation = play

- Play = interactive composition of two strategies
- Composition is effective (cf. Ong 04). Corresponds to **Pointer Abstract Machine** (Danos-Herbelin-Regnier 96).

Ranks and complexity

- The **rank** of a type: $rank(\iota) = 0$,
 $rank(A \rightarrow B) = \max(rank(A) + 1, rank(B))$
- A term is at **rank** n if all of its subterms have rank n types.

Rank	Quantative	Qualitative
1	boolean formulas $\neg b = \lambda xy. b^{\iota \rightarrow \iota \rightarrow \iota} yx$	(open) addition
2	boolean circuits $(\lambda x. F(x, \dots, x))^{bool \rightarrow bool} G(y)$	multiplication $\bar{n} \circ \bar{m}$
3	QBFs $\forall x. F(x) =$ $(\lambda X. X(\mathbf{0}) \wedge X(\mathbf{1}))^{(bool \rightarrow bool) \rightarrow bool} \lambda x. F(x)$	exponentiation $(\bar{n})^{int \rightarrow int} \bar{m}$

Ranks and complexity

- Normalization problem:

Given two terms t, u where u is normal,
does t reduce to u ?

- (Schubert 2001) shows that this problem is

1. in $DTIME(n \log n)$ for rank 1 terms

2. P-complete for rank 2 terms

3. PSPACE-complete for rank 3 terms

- Hardness is easy. Membership is difficult, since β -reduction does not work.

- Schubert uses graph rewriting. We use HO games.

HO games for simple types

- **Arena** for type A :

Moves	=	occurrences of atomic types in A
P-moves	=	negative occurrences
O-moves	=	positive occurrences
Initial move	=	$tail(A)$

$tail(B) \vdash tail(C)$ where C is an immediate subformula of B

- **Legal play**: a PO-alternating **pointing** sequence like

$$s = m_0 \overset{\curvearrowright}{m_1} \cdots m_j \overset{\curvearrowleft}{\cdots} m_i \cdots$$

- m_0 is the initial O-move

- each m_i ($1 \leq i$) is justified by a preceding move m_j
($m_j \vdash m_i$, $0 \leq j < i$).

Let's play the game!

- **P-view**: a legal play in which any O-move is justified by the move immediately before.
- Given an arbitrary legal play s , a P-view $\lceil s \rceil$ can be extracted.
- **Innocent strategy (as view function)**: a P-deterministic tree made of P-ending P-views.
- Every closed normal term $t : A$ can be interpreted by an innocent strategy.
- **HO-dialogue**: Given innocent strategies $\sigma : A \rightarrow B$ and $\tau : A$,
 1. Start with the initial move $m_0 = \text{tail}(B)$
 2. Expand an odd length play s to $s \cdot m$ such that $\lceil s \rceil \cdot m \in \sigma$
 3. Expand an even length play $m_0 \cdot s$ to $m_0 \cdot s \cdot m$ such that $\lceil s \rceil \cdot m \in \tau$

A lemma in game semantics

- **Difficulty:** HO game is **history sensitive**. But recording the whole history leads to **TIME = SPACE**.
- **Lemma** (taught by P. Boude): For any legal play satisfying P- and O-visibility

$$s = \cdots m_1 \cdots m_2 \cdots$$


if m_2 justifies no moves, **it never happens** that

$$s = \cdots m_1 \cdots m_2 \cdots$$


- So one can safely contract s to

$$s' = \cdots m_1 m_2 \cdots$$

and continue the play.

Complexity of Rank 3 games

- **Theorem:** Given a term t at rank 3 (which is an applicative combination of closed normal terms), the length of play can be kept within $O(|t|)$.
- **Corollary:** One can determine the head variable of $nf(t)$ in polynomial space via HO games.
- **Work to be done:** What about rank ≥ 4 ? Do we have a hierarchy result as in Kristiansen's talk?

Conclusion

- Lambda calculus admits a canonical composition $M \circ N$
- KAM is optimal for simulating TM.
- Composition works nicely with KAM.
- (KAM allows natural programming eg. boolean matrix closure)
- HO games seem to be good at least for rank bounded terms.
- Good understanding of game semantics leads to clever space management. Game semantics may implicitly explain complexity.