On the integral representation of 5(3) in terms of elliptic modular forms

# §0. Introduction

In this paper the authors show the integral representation of  $\zeta(3) = \sum_{n=1}^{\infty} n^{-3}.$  Namely  $\zeta(3)$  is represented by the Mellin n=1 transformation of a modular form relative to  $\Gamma_1(6)$ . Our result is

transformation of a modular form relative to  $\Gamma_1$  (6). Our result is based on the theory developed by Apéry [A], Beukers [B1] and others.

In 1978 Apéry introduced his sequences  $\{a_n\}$ ,  $\{b_n\}$ . Those sequences satisfy the recurrence relation

$$n^3 u_n + (n-1)^3 u_{n-2} = (34n^3 - 51n^2 + 27n - 5)u_{n-1}$$
 (0-1)

with initial conditions  $a_0 = 1$ ,  $a_1 = 5$  and  $b_0 = 0$ ,  $b_1 = 6$ . And he showed the irrationality of  $\zeta(3)$  by the approximation

$$\lim_{n\to\infty} \frac{b_n}{a_n} = \zeta(3). \tag{*}$$

Beukers-Peters[B-P] studied the generating functions  $A(t) = \sum a_n t^n$ ,  $B(t) = \sum b_n t^n$  for these sequences. As easily shown those two functions satisfy the following Fuchsian type differential equation with singularities t = 0,  $\lambda = (1-\sqrt{2})^4$ ,  $\lambda' = (1+\sqrt{2})^4$ ,  $\infty$ ;

D: 
$$L(y) = 0$$
, (0-2)

$$L(y) = 6, (0-3)$$

respectively, where L indicates the differential operator  $L = (t^4 - 34t^3 + t^2)(\frac{d}{dt})^3 + (6t^3 - 153t^2 + 3t)(\frac{d}{dt})^2 + (7t^2 - 112t + 1)\frac{d}{dt} + (t - 5). \quad (0 - 4)$  As Peters[P] pointed out the differential equation (0-2) is closely related with the Picard-Fuchs equation

$$D_6: s(s-1)(9s-1)\frac{d^2z}{ds^2} + (27s^2-20s+1)\frac{dz}{ds} + (9s-3)z = 0$$

for the modular family of elliptic curves

$$\mathcal{F}_6$$
:  $y^2 + (1+s)xy - (s^2-s)y = x^3 - (s^2-s)x^2$ 

relative to a congruence subgroup of  $\Gamma = SL(2,\mathbb{Z})$ :

$$\Gamma_1(6) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL(2,\mathbb{Z}) : a \equiv 1, c \equiv 0 \pmod{6} \right\}$$

So we proceed our study as the following way

- (1) We construct the solutions  $\omega(s)$ ,  $\widetilde{\omega}(s)$  of  $D_6$  using a modular form  $\omega(\tau)$  of weight 1 and the uniformizing function  $s=s(\tau)$  relative to  $\Gamma_1(6)$ , where  $\tau$  is a variable on  $H=\{\tau\in\mathbb{C}: \text{Im }\tau>0\}$ .
- (2) We show the exact cnnection between D and  $D_6$ , and describe A(t) and B(t)in terms of  $\omega(s)$ ,  $\widetilde{\omega}(s)$ . During this procedure we find the relation t = s(9s-1)/(s-1) between the two variables t and s.
- (3) We observe the behavior of A(t) and B(t) around  $t=\lambda$ . Then we can find a linear combination of A(t) and B(t)

$$\Phi(t) = C A(t) + B(t)$$

with trivial monodromy around  $t=\lambda$  (the coefficient C is given by (4-3)). Hence  $\Phi(t)$  is single valued holomorphic on  $\{t\in\mathbb{C}: |t|<\lambda'\}$ . By this property we can deduce

$$C + \frac{p_n}{a_n} \longrightarrow 0 \qquad (n \to \infty),$$

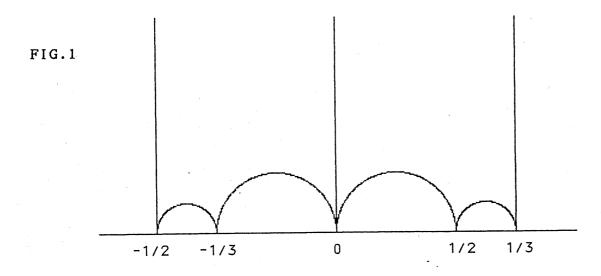
by virtue of Apéry's relation (\*) it indicates the equality  $C + \zeta(3) = 0.$ 

If we write down the coefficient c, we obtain the representation of  $\zeta(3)$ .

## §1. Statement of the result

At first we have the properties of  $\Gamma_1$  (6):

- (i)  $[\Gamma:\Gamma_1(6)] = 24$ ,
- (ii) the quatient space  $H/\Gamma_1$  (6) has 4 cusp points thier representatives are given by  $\tau$  = 0, 1/3, 1/2,  $\infty$ .
- (iii) the genus of  $H/\Gamma_1$  (6) , the compactification of  $H/\Gamma_1$  (6), is equal to 0,
  - (iv) the fundamental domain of  $\Gamma_1$  (6) is pictured in fig.1.



According to the result of Klein (see [K] p.391) we can take  $s(\tau) = \left\{ \begin{array}{l} \frac{\vartheta_2(0,3\tau)}{\vartheta_2(0,\tau)} \end{array} \right\}^4, \text{ where } \vartheta_2 \text{ denotes the Jacobi's theta function, as} \\ \text{the uniformizing function of } \Gamma_1(6) \text{ (namely } s(\tau) \text{ is the generator of the field M(H/$\Gamma_1$(6))} \text{ of meromorphic modular functions relative to} \\ \Gamma_1(6)). \text{ Using the infinite product expression of } \vartheta_2\text{:} \\ \end{array}$ 

$$\vartheta_2(0,\tau) = 2 q^{1/4} \prod_{n=1}^{\infty} (1-q^n) \prod_{n=1}^{\infty} (1+q^n)^2 \qquad (q = e^{2\pi i \tau})$$

we obtain the q-expansion of  $s(\tau)$ :

$$s(\tau) = q - 4q^2 + 10q^3 - 20q^4 + \cdots \qquad (q = e^{2\pi i \tau}).$$
 (1-1)

Using the transformation formula for  $\vartheta_2$  we obtain

$$\begin{cases} s(\infty) = 0 \\ s(0) = 1/9 \\ s(1/3) = 1 \\ s(1/2) = \infty \end{cases}$$

Next let G  $_{N,k,\vec{a}}(\tau)$  denote an Eisenstein series of level N and dimension -k, where k is a positive integer and  $\vec{a}$  is an element of  $Z^2$ , namely

$$G_{N,k,\overrightarrow{a}}(\tau) = \sum_{(m_1,m_2)\equiv \overrightarrow{a} \pmod{N}} \frac{1}{(m_1\tau + m_2)^k}$$
 for  $k \ge 3$ .

It is known that  $G_{6,1,a}^{\rightarrow}(\tau)$  can be defined and is a modular form of weight 1 for  $\Gamma(6)$  (see [S] chap. VII). If we make the linear combination  $\sum_{k=0}^{5} G_{6,1,(1,k)}^{(\tau)}$ , then we can show that it is a modular

form of weight 1 for  $\Gamma_1(6)$  with the only zero at  $\tau$ = 1/2 (cf.[S]). We set

$$\omega(\tau) = \frac{3}{2\pi i} \sum_{k=0}^{5} G_{6,1,(1,k)} = 1 - 3q - 3q^2 - 3q^3 - 3q^4 - 3q^6 - 6q^7 - \cdots$$
 (1-3)

Now we can state our result.

Proposition.

It holds

$$\zeta(3) = -3 (2\pi i)^3 \int_0^{i\infty} s(9s^2 - 18s + 1)(9s - 1)\tau^2 \omega^4 d\tau.$$

### §2. The solution of the modular differential equation.

In this section we perform the process (1) in the introduction. Set  $\widetilde{\omega}(\tau) = \tau \omega(\tau)$ . We can consider  $\omega$  and  $\widetilde{\omega}$  as multivalued function on the s-space via the mapping  $\tau \to s(\tau)$ . We denote them by  $\omega(s)$  and  $\widetilde{\omega}(s)$  Since  $s(\tau)$  gives the universal covering map of  $\mathbb{C}$ -{0, 1/9, 1}, it induces the isomorphism  $\pi_1(\mathbb{C}\setminus\{0, 1/9, 1\}) \cong \Gamma_1(6)$ . Let  $\gamma$  be a closed path in  $\mathbb{C}\setminus\{0, 1/9, 1\}$ , and let  $\binom{a}{c}$  be the corresponding element of  $\Gamma_1(6)$ . After an analytic continuation along  $\gamma$ ,  $\omega$  and  $\widetilde{\omega}$  are changed by the transformation

$$\begin{pmatrix} \widetilde{\omega}(s) \\ \omega(s) \end{pmatrix} \longrightarrow \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} \widetilde{\omega}(s) \\ \omega(s) \end{pmatrix}$$

Next we determine the differential equation for  $\omega$  and  $\widetilde{\omega}$ . It is easy to see that  $\omega$  and  $\widetilde{\omega}$  satisfy the equation

$$\begin{vmatrix} \omega & \omega' \\ \sim & \sim \\ \omega & \omega' \end{vmatrix} F'' - \begin{vmatrix} \omega & \omega'' \\ \sim & \sim \\ \omega & \omega'' \end{vmatrix} F' + \begin{vmatrix} \omega' & \omega'' \\ \sim & \sim \\ \omega' & \omega'' \end{vmatrix} F = 0$$
 (2-1)

By a little bit of calcuation we obtain

$$\begin{vmatrix} \omega & \omega \\ \sim & \sim \\ \omega & \omega \end{vmatrix} = \frac{\omega^2}{\mathrm{d}s/\mathrm{d}\tau} = \frac{1}{s} \frac{\omega^2}{\frac{1}{s} \frac{\mathrm{d}s}{\mathrm{d}\tau}},$$

$$\begin{vmatrix} \omega & \omega \\ \sim & \sim \\ \omega & \omega \end{vmatrix} = \mathrm{d} \begin{vmatrix} \omega & \omega \\ \sim & \sim \\ \omega & \omega \end{vmatrix} / \mathrm{d}s,$$

$$\begin{vmatrix} \omega' & \omega' \\ \sim & \sim \\ \omega' & \omega' \end{vmatrix} = \frac{1}{(\mathrm{d}s/\mathrm{d}\tau)^3} \{2(\mathrm{d}\omega/\mathrm{d}\tau)^2 - \omega(\mathrm{d}/\mathrm{d}\tau)^2\omega\}.$$

$$\begin{vmatrix} \omega & \omega \\ \sim & \sim \\ \omega & \omega \end{vmatrix} = \frac{1}{(\mathrm{d}s/\mathrm{d}\tau)^3} \{2(\mathrm{d}\omega/\mathrm{d}\tau)^2 - \omega(\mathrm{d}/\mathrm{d}\tau)^2\omega\}.$$

Here we note that  $\frac{1}{s} \frac{ds}{d\tau}$  is a modular form of weight 2 for  $\Gamma_1(6)$ . The values of  $\omega^2$ , s and  $\frac{1}{s} \frac{ds}{d\tau}$  at cusp points are given as the following.

Thus we obtain  $\frac{\omega^2}{\mathrm{d}s/\mathrm{d}\tau}=\frac{c}{s(s-1)(9s-1)}$ , where c is a certain constant. As for the third term of (2-2) it has double poles at s=0, 1/9, 1 and s= $\infty$  is its zero of oder 5. Then it takes the form  $\frac{as+b}{s^2(s-1)^2(9s-1)^2}$ . We can determine the constants a and b by comparing with the s-expansion of  $\omega$ :

$$\omega(s) = 1 + 3s + 15s^2 + 93s^3 + 639s^4 + \cdots$$

By this caluculation we find that (2-1) coincides with  $\mathbf{D}_{6}$ .

Here we determine the constant c from the relation

$$s \frac{\omega^2}{ds/d\tau} = \frac{c}{(s-1)(9s-1)}. \text{ In fact (1-1) and (1-3) induce the equality}$$

$$\frac{c}{(s-1)(9s-1)} = (q-4q^2+\cdots) \frac{(1-3q-\cdots)^2}{(2\pi i q + \cdots)}.$$

By substituting s=0 (namely q=0) we get  $c = \frac{1}{2\pi i}$ .

# §3. The relation between A(t), B(t) and $\omega(s)$ , $\widetilde{\omega}(s)$ .

Let us consider the intermediate differential equation  $D_6^*: t^2(t^2-34t+1)y'' + (2t^2-51t+1)y' + \frac{1}{4}(t-10)y = 0.$ 

If we substitute t=s(9s-1)/(s-1) in  $D_6^*$  and perform the gauge transformation  $y=(s-1)^{1/2}z$ , we obtain  $D_6$ . On the other hand D is the symmetric tensor product of  $D_6^*$ . Namely the vector space of solutions for D is given by the symmetric tensor of the one for  $D_6^*$ . Then we obtain three solutions of D:

Obviously  $\varphi_1$  is holomorphic at t=0.

Let us find a solution g(t) of L(y)=1 in terms of  $\varphi_i$ . Set g(t)=  $c_1\varphi_1+c_2\varphi_2+c_3\varphi_3$ , where  $c_i$  (i=1,2,3) is a function of t. We assume the following

$$\Sigma c_{i}' \varphi_{i} = 0$$

$$\Sigma c_{i}' \varphi_{i}' = 0$$

$$(3-2)$$

Then we have

$$g' = \sum_{i} c_{i} \varphi_{i}'$$

$$g'' = \sum_{i} c_{i} \varphi_{i}''$$

$$g''' = \Sigma c_i \varphi_i''' + \Sigma c_i' \varphi_i''$$

Because  $\varphi_i$  (i=1,2,3) satisfies L(y) = 0 we have

$$\begin{split} L(g) &= P_0(t)g''' + P_1(t)g'' + P_2(t)g' + P_3(t)g \\ &= \Sigma c_i(P_0(t)\varphi_i''' + P_1(t)\varphi_i'' + P_2(t)\varphi_i' + P_3(t)\varphi_i) \\ &+ P_0(t) \Sigma c_i'\varphi_i'' \\ &= P_0(t) \Sigma c_i'\varphi_i'', \end{split}$$

where  $P_i(t)$  (i=0,1,2,3) is the coefficient of (d/dt) in (0-4). So we request that

$$P_0(t) \sum_{i} q_{i}' = 1.$$
 (3-3)

From (3-2) and (3-3) we get the required condition:

$$\begin{pmatrix}
\varphi_1 & \varphi_2 & \varphi_3 \\
\varphi_1' & \varphi_2' & \varphi_3' \\
\varphi_1'' & \varphi_2'' & \varphi_3''
\end{pmatrix}
\begin{pmatrix}
c_1' \\
c_2' \\
c_3'
\end{pmatrix} = \begin{pmatrix}
0 \\
0 \\
1/P_0
\end{pmatrix}.$$

Hence we obtain the solution g(t) in a neighborhood of t=0 of L(y) = 1 by putting

$$g(t) = \varphi \int_0^t f \tau' \tau^2 \varphi^2 dt - 2\tau \varphi \int_0^t f \tau' \tau \varphi^2 dt + \tau^2 \varphi \int_0^t f \tau' \varphi^2 dt, \quad (3-4)$$
where  $f(t) = \frac{1}{P_0(t) \cdot W(t)}$ ,  $W(t) = \begin{vmatrix} \varphi_1 & \varphi_2 & \varphi_3 \\ \varphi_1' & \varphi_2' & \varphi_3' \\ \varphi_1'' & \varphi_2'' & \varphi_3'' \end{vmatrix}$  and  $\tau' = d\tau/dt$ .

In (3-4) the path of integral is supposed to be a line segment from 0 to a point t.

We can show that  $W(t) = 2\varphi^3 (d\tau/dt)^3$ . If we note  $\frac{dt}{ds} = \frac{9s^2 - 18s + 1}{(s-1)^2}$  and the first equality of (2-2), we have

$$W(t(s)) = 2(2\pi i)^{-3} \frac{(s-1)^6}{\{s(9s-1)(9s^2-18s+1)\}^3}.$$

As we will show in the next section  $\phi$  and g are holomorphic in the neiborhood of t=0. It is easy to see the relations:

(3-5) 
$$\begin{cases} A(t) = -\phi(t), \\ B(t) = 6g(t). \end{cases}$$

### §4. Monodromy trick.

The differential equations (0-2) and (0-3) have same singularities t=0,  $\lambda$ ,  $\lambda$ ',  $\infty$ . Here we calculate the monodromy of the solutions  $\varphi_i$ (t) (i=1,2,3) and g(t) around t=0 and t= $\lambda$ .

At first we examine the singularity t=0. Let  $\gamma_0$  be a closed arc in  $\mathbb{C}\setminus\{0,\lambda,\lambda'\}$  going around t=0 in the positive sense. The mapping t = s(9s-1)/(s-1) gives a biholomorphic correspondence between a

neighborhood of s=0 and that of t=0. When t moves along  $\gamma_0$ , s varies around s=0 in the same sense also. By observing the correspondence  $\tau \longrightarrow s(\tau)$  we know that  $\gamma_0$  induces the translation  $\tau \longrightarrow \tau+1$ . Because  $\omega(t)$  has a trivial monodromy around t=0,  $\gamma_0$  induces the monodromy

$$M_{O}: \begin{pmatrix} \widetilde{\omega} \\ \omega \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \widetilde{\omega} \\ \omega \end{pmatrix}. \tag{4-1}$$

Next let us study the singularity  $t=\lambda$ . This point corresponds to  $\sigma=\frac{3-2\sqrt{2}}{3}$  on the s-plane. Let  $\gamma_\lambda$  be a closed arc in  $\mathbb{C}\setminus\{0,\lambda,\lambda'\}$  going around  $t=\lambda$  in the positive sense. We supporse  $\gamma_\lambda$  starts from a point near t=0. This loop corresponds to an arc from a point  $s=s_0$  near s=0 to a point near s=1/9. Because we have  $s\big|_{\tau=\infty}=0$  and  $s\big|_{\tau=0}=1/9$ ,  $\gamma_\lambda$  should carry  $\tau=\infty$  to  $\tau=0$ . The composite loop  $\gamma_\lambda\cdot\gamma_\lambda$  corresponds to a loop starting from  $s_0$  and goes around  $s=\sigma$  in the positive sense. The point  $\sigma$  is not a singularity of  $D_6$ . Hence this loop induces a trivial monodromy. So the monodromy  $M_\lambda$  (relative to  $t(\widetilde{\omega},\omega)$ ) must be of order 2. By a little bit of observation we know that  $M_\lambda$  maps  $\tau=1/3$  and  $\tau=1/2$  to  $\tau=-1/2$  and  $\tau=-1/3$ , respectively. Hence  $\gamma_\lambda$  induces the transformation  $\tau \to -\frac{1}{6\tau}$ . If we calculate the values  $\omega(t)$  and  $\widetilde{\omega}(t/6)$ , then we have

$$M_{\lambda} = \frac{i}{\sqrt{6}} \begin{pmatrix} 0 & -1 \\ & & \\ 6 & 0 \end{pmatrix}. \tag{4-2}$$

Let  $\ell$  be a line segment from 0 to t. When t varies along  $\gamma_0$ ,  $\ell$  is deformed to the composite arc  $\ell \cdot \gamma_0$ . Then

$$\varphi \int_0^t f(t)\tau'\tau^2\varphi^2 dt$$

is changed to

$$\tilde{\varphi}$$
  $\int_{0}^{t} \tilde{f}(t)\tilde{\tau}'\tilde{\tau}^{2} \tilde{\varphi}^{2}dt$ ,

where  $\sim$  indicates the result of the monodromy along  $\gamma_0.$  Using (4-1) we have

$$\widetilde{f}(t) = f(t)$$

$$\widetilde{\tau}(t) = \tau(t) + 1$$

$$\widetilde{\tau}'(t) = \tau'(t)$$

$$\widetilde{\varphi}(t) = \varphi(t)$$

By the same way we can calculate the monodromy of other terms in (3-5). As a consequence  $\gamma_{\,0}^{\,}$  induces a monodromy relative to

$$\begin{pmatrix} \varphi_1, & \varphi_2, & \varphi_3, & g \end{pmatrix} : \\ \begin{pmatrix} \varphi_1 \\ & \varphi_2 \\ & \varphi_3 \\ & g \end{pmatrix} & \longrightarrow & \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ & 1 & 1 & 0 & 0 & 0 \\ & 1 & 2 & 1 & 0 & 0 \\ & 0 & 0 & 0 & 1 & \end{pmatrix} \begin{pmatrix} \varphi_1 \\ & \varphi_2 \\ & \varphi_3 \\ & g \end{pmatrix} .$$

Thus we know that g(t) has a trivial monodromy around t=0 and it is single valued holomorphic there.

By a similar method (4-2) induces the monodromy along  $\gamma_1$ :

$$\begin{pmatrix} \varphi_1 \\ \varphi_2 \\ \varphi_3 \\ g \end{pmatrix} \longrightarrow \begin{pmatrix} 0 & 0 & -6 & 0 \\ 0 & 1 & 0 & 0 \\ -1/6 & 0 & 0 & 0 \\ -C/6 & 0 & -C & 1 \end{pmatrix} \begin{pmatrix} \varphi_1 \\ \varphi_2 \\ \varphi_3 \\ g \end{pmatrix}, \quad (4-4)$$
where  $C = \int_0^{\lambda} f \tau' \varphi^2 dt + 6 \int_0^{\lambda} f \tau' \tau^2 \varphi^2 dt$ . (4-3)

This indicates that  $\Phi(t) = -C \ \varphi(t) + 6 \ g(t)$  is single valued holomorphic in the neighborhood of  $t=\lambda$ . Namely  $\Phi(t)$  is single valued holomorphic on  $\{t \in \mathbb{C} \ | \ |t| < \lambda'\}$ . If we recall (3-5), then we have  $\lim_{n \to \infty} \sqrt[n]{|C| a_n + b_n|} = \frac{1}{\lambda'} = \lambda.$ 

If we consider that  $\Sigma$   $a_nt^n$  has the radius of convergence  $\lambda$  and  $\{a_n\}$  satisfies (0-1), we can show that

$$|a_n| \sim (1/\lambda)^n$$
.

Then we have

$$C + \frac{b_n}{a_n} \longrightarrow 0 \qquad (n \longrightarrow \infty).$$

By changing the variable from t to s in C we obtain

$$\zeta(3) = -3 (2\pi i)^2 \int_0^{1/9} \frac{9s^2 - 18s + 1}{s - 1} \widetilde{\omega}^2(s) ds. \tag{4-4}$$

If we rewrite it in terms of the variable  $\boldsymbol{\tau}$ , we have the required form in the Proposition.

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