Recurrent Sets for Dynamic Fuzzy Systems

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0. Introduction

This paper discusses a recurrent behavior of dynamic fuzzy systems defined by fuzzy relations on a Euclidean space. By introducing a recurrence for crisp sets, we give probability-theoretical properties for the fuzzy systems. When the fuzzy relations satisfy a contraction condition, the existence of the maximum recurrent set is shown. We also consider a monotonicity condition for the fuzzy relations as an extended case of a linear structure in one-dimensional fuzzy numbers. Then we present the existence of the arcwise connected maximal recurrent sets.

1. Notations

Let S be a metric space. We write a fuzzy set on S by its membership function $\tilde{s}: S \mapsto [0,1]$ and an ordinary set $A(\subset S)$ by its indicator function $1_A: S \mapsto \{0,1\}$. The α -cut \tilde{s}_{α} is defined by

$$\tilde{s}_{\alpha} := \{ x \in S \mid \tilde{s}(x) \ge \alpha \} \ (\alpha \in (0,1]) \quad \text{and} \quad \tilde{s}_{0} := \operatorname{cl}\{ x \in S \mid \tilde{s}(x) > 0 \},$$

where cl denotes the closure of a set. $\mathcal{F}(S)$ denotes the set of all fuzzy sets \tilde{s} on S satisfying the following conditions (i) and (ii):

(i)
$$\tilde{s}_{\alpha} \in \mathcal{E}(S)$$
 for $\alpha \in [0,1]$;

(ii)
$$\bigcap_{\alpha' < \alpha} \tilde{s}_{\alpha'} = \tilde{s}_{\alpha}$$
 for $\alpha \in (0, 1]$,

where $\mathcal{E}(S) := \{A \mid A = \bigcup_{n=0}^{\infty} C_n, C_n \text{ are closed subsets of } S \ (n = 0, 1, 2, \cdots)\}$. We also define

$$\mathcal{G}(S) := \left\{ \text{ fuzzy sets } \tilde{s} \text{ on } S \mid \text{ there exists } \{\tilde{s}_n\}_{n \in \mathbb{N}} \subset \mathcal{F}(S) \text{ satisfying } \tilde{s} = \bigvee_{n \in \mathbb{N}} \tilde{s}_n \right\},\,$$

where $\mathbf{N}:=\{0,1,2,3,\cdots\}$ and for a sequence of fuzzy sets $\{\tilde{s}_n\}_{n\in\mathbb{N}}$ on S we define

$$\bigwedge_{n \in \mathbf{N}} \tilde{s}_n(x) := \inf_{n \in \mathbf{N}} \tilde{s}_n(x) \quad \text{and} \quad \bigvee_{n \in \mathbf{N}} \tilde{s}_n(x) := \sup_{n \in \mathbf{N}} \tilde{s}_n(x) \qquad x \in S.$$

Let a time space by \mathbb{N} and put $\overline{\mathbb{N}} := \mathbb{N} \cup \{\infty\}$. Let a state space E be a finite-dimensional Euclidean space. We put a path space by $\Omega := \prod_{k=0}^{\infty} E$ and we write a sample path by $\omega = (\omega(0), \omega(1), \omega(2), \cdots) \in \Omega$. We define a map $X_n(\omega) := \omega(n)$ and a shift $\theta_n(\omega) := (\omega(n), \omega(n+1), \omega(n+2), \cdots)$ for $n \in \mathbb{N}$ and $\omega = (\omega(0), \omega(1), \omega(2), \cdots) \in \Omega$. We put

σ-fields by $\mathcal{M}_n := \sigma(X_0, X_1, \dots, X_n)^{-1}$ for $n \in \mathbb{N}$ and $\mathcal{M} := \sigma(\bigcup_{n \in \mathbb{N}} \mathcal{M}_n)^{-2}$. Let Δ be not a point of E and put $E_{\Delta} := E \cup \{\Delta\}$. We can extend the state space E to E_{Δ} , setting $\tilde{s}(\Delta) := 0$ for $\tilde{s} \in \mathcal{G}(E_{\Delta})$ and $X_{\infty}(\omega) := \Delta$ for $\omega \in \Omega$ ([10, Section 2]). Let \tilde{q} be an upper semi-continuous binary relation on $E \times E$ satisfying the following normality condition:

$$\sup_{x \in E} \tilde{q}(x,y) = 1 \ (y \in E) \quad \text{and} \quad \sup_{y \in E} \tilde{q}(x,y) = 1 \ (x \in E).$$

We call \tilde{q} a fuzzy relation. We define a fuzzy expectation: For an initial state $x \in E$ and an \mathcal{M} -measurable fuzzy set $h \in \mathcal{F}(\Omega)$,

$$E_x(h) := \int_{\{\omega \in \Omega : \omega(0) = x\}} h(\omega) \, d\tilde{P}(\omega),$$

where \tilde{P} is the following possibility measure :

$$\tilde{P}(\Lambda) := \sup_{\omega \in \Lambda} \bigwedge_{n \in \mathbb{N}} \tilde{q}(X_n \omega, X_{n+1} \omega) \qquad \Lambda \in \mathcal{M}$$

and $\int d\tilde{P}$ denotes Sugeno integral (Sugeno [9]).

We need the first entry times (the first hitting times) of a set, which is adapted to the dynamic fuzzy system $X := \{X_n\}_{n \in \mathbb{N}}$, in order to define a recurrence of sets in Section 3. We define

$$\mathcal{E} := \{ A \mid A \in \mathcal{E}(E) \text{ and } E \setminus A \in \mathcal{E}(E) \}$$

and we call a map $\tau: \Omega \mapsto \overline{\mathbf{N}}$ an \mathcal{E} -stopping time if

$$\{\tau=n\}\in\mathcal{M}_n\cap\mathcal{E}(\Omega)\qquad n\in\mathbf{N}.$$

For example, a constant stopping time i.e. $\tau = n_0$ for some $n_0 \in \mathbb{N}$, is an \mathcal{E} -stopping time. For $A \in \mathcal{E}$ we put

$$\tau_A(\omega) := \inf\{n \in \mathbb{N} \mid X_n(\omega) \in A\} \quad \omega \in \Omega;$$

$$\sigma_A(\omega) := \inf\{n \in \mathbb{N} \mid n \ge 1, X_n(\omega) \in A\} \quad \omega \in \Omega,$$

where the infimums of the empty set are understood to be $+\infty$. Then the first entry time τ_A of A and the first hitting time σ_A of A are also \mathcal{E} -stopping times ([10, Lemma 1.5]).

Define a map $P: \mathcal{G}(E) \mapsto \mathcal{G}(E)$ by

$$P\tilde{s}(x) := E_x(\tilde{s}(X_1)) = \sup_{y \in E} \{\tilde{q}(x,y) \land \tilde{s}(y)\} \quad x \in E \quad \text{for } \tilde{s} \in \mathcal{G}(E),$$
 (1.1)

where we write binary operations $a \wedge b := \min\{a, b\}$ and $a \vee b := \max\{a, b\}$ for $a, b \in [0, 1]$. We call P a fuzzy transition defined by the fuzzy relation \tilde{q} . We also define n-steps fuzzy transitions $P_n : \mathcal{G}(E) \mapsto \mathcal{G}(E)$, $n \in \mathbb{N}$, by

$$P_n \tilde{s} := E.(\tilde{s}(X_n)) = \sup_{y \in E} {\{\tilde{q}^n(\cdot, y) \land \tilde{s}(y)\}} \text{ for } \tilde{s} \in \mathcal{G}(E),$$

¹It denotes the smallest σ -field on Ω relative to which X_0, X_1, \dots, X_n are measurable.

²It denotes the smallest σ -field generated by $\bigcup_{n\in \mathbb{N}} \mathcal{M}_n$.

where for $n \in \mathbb{N}$

$$\tilde{q}^1(x,y) := \tilde{q}(x,y) \quad \text{and} \quad \tilde{q}^{n+1}(x,y) := \sup_{z \in E} \{\tilde{q}^n(x,z) \wedge \tilde{q}(z,y)\} \quad x,y \in E.$$

Further for an \mathcal{E} -stopping time τ , a fuzzy transition $P_{\tau}:\mathcal{G}(E)\mapsto\mathcal{G}(E)$ is defined by

$$P_{\tau}\tilde{s} := E_{\cdot}(\tilde{s}(X_{\tau})) \quad \text{for } \tilde{s} \in \mathcal{G}(E),$$

where $X_{\tau} := X_n$ on $\{\tau = n\}, n \in \overline{\mathbb{N}}.$

2. Transitive closures and P-superharmonic fuzzy sets

We define a partial order \geq on $\mathcal{G}(E)$: For $\tilde{s}, \tilde{r} \in \mathcal{G}(E)$

$$\tilde{s} \ge \tilde{r} \iff \tilde{s}(x) \ge \tilde{r}(x) \quad x \in E.$$

Definition ([10, Section 4]). A fuzzy set $\tilde{s} \in \mathcal{G}(E)$ is called P-harmonic (P-superharmonic) provided that

$$\tilde{s} = P\hat{s} \quad (\tilde{s} \ge P\hat{s} \text{ resp.}).$$

Clearly a constant fuzzy set, $\tilde{s} = \beta$ for some $\beta \in [0, 1]$, is *P*-superharmonic. We represent the fuzzy set by β simply.

Theorem 2.1. Let \tilde{s} be P-superharmonic and let a set $A \in \mathcal{E}$. Then $P_{\tau_A}\tilde{s}$ is the smallest P-superharmonic fuzzy set which dominates $\tilde{s} \wedge 1_A$.

We define an operator $G := \bigvee_{n \in \mathbb{N}} P_n$ on $\mathcal{G}(E)$. Then we note that

$$PG1_{\{y\}}(x) = \bigvee_{n\geq 1} P_n 1_{\{y\}}(x) = \sup_{n\geq 1} \tilde{q}^n(x,y) \qquad x,y \in E.$$

This is called a transitive closure ([3, Section 3.3]). In this paper we also call PG a transitive closure. Now we need to investigate the operator G in order to analyse the transitive closure $PG := \bigvee_{n>1} P_n$. We have the following properties regarding G.

Lemma 2.1 ([10, Lemma 4.1(ii)]). Let $\tilde{s} \in \mathcal{G}(E)$. Then :

(i) It holds that

$$G\tilde{s} = \tilde{s} \vee P(G\tilde{s});$$

(ii) $G\tilde{s}$ is the smallest P-superharmonic dominating \tilde{s} .

For $A \in \mathcal{E}(E)$ we introduce an operator $I_A : \mathcal{G}(E) \mapsto \mathcal{G}(E)$ by

$$I_A \tilde{s} := \tilde{s} \wedge 1_A \qquad \tilde{s} \in \mathcal{G}(E).$$

We define a sequence of hitting times $\{\sigma_A^n\}_{n\in\mathbb{N}}$ of a set $A(\in\mathcal{E})$ by

$$\sigma_A^n := \left\{ \begin{array}{ll} 0 & \text{if } n = 0 \\ \sigma_A^{n-1} + \sigma_A \circ \theta_{\sigma_A^{n-1}} & \text{if } n \geq 1. \end{array} \right.$$

Then σ_A^n means the first time to hit A after time σ_A^{n-1} (c.f. [8]).

Proposition 2.1. Let $A \in \mathcal{E}$. Then:

- (i) $P_{\tau_A}\tilde{s} = GI_A\tilde{s}$ for P-superharmonic \tilde{s} ;
- (ii) $P_{\sigma_A^n} \tilde{s} = (PGI_A)^n \tilde{s}$ for P-superharmonic \tilde{s} and $n \in \mathbb{N}$.

3. α -recurrent sets

Definition. Let $\alpha \in (0,1]$. A set $A \in \mathcal{E}(E)$ is called α -recurrent provided:

- (a) A is non-empty;
- (b) $P_{\sigma_R^n} 1 \ge \alpha$ on A for all $n \in \mathbb{N}$ and all non-empty $B \in \mathcal{E}$ satisfying $B \subset A$.

The α -recurrence of a set A means that a possibility to transit infinite times from any point of A to any point of A is greater than α .

We give simple necessary and sufficient criteria for α -recurrence by the transitive closure PG.

Proposition 3.1. Let $\alpha \in (0,1]$ and let non-empty $A \in \mathcal{E}(E)$. Then the following statements are equivalent:

- (i) A is α -recurrent;
- (ii) $PG1_B \ge \alpha \land 1_A$ for non-empty $B \in \mathcal{E}(E)$ satisfying $B \subset A$;
- (iii) $PG1_{\{y\}} \ge \alpha \wedge 1_A$ for $y \in A$.

We gives, by the fuzzy relation \tilde{q} , a representation of the union of all α -recurrent sets.

Theorem 3.1. It holds that

$$\bigcup_{A \in \mathcal{E}(E): \alpha - \text{recurrent sets}} A = \left\{ x \in E \mid \sup_{n \geq 1} \tilde{q}^n(x, x) \geq \alpha \right\} \quad \text{for } \alpha \in (0, 1].$$

4. The contractive case

We consider the contractive case in [5] and we give the maximum α -recurrent set for the dynamic fuzzy system X.

Let E_c be a compact subset of E. We deal with a dynamic fuzzy system restricted on the compact space E_c according to [5]. Let $\mathcal{C}(E_c)$ be the set of all closed subsets of E_c and let ρ be the Hausdorff metric on $\mathcal{C}(E_c)$. Let $\mathcal{F}^0(E_c)$ be the set of all fuzzy sets \tilde{s} on E_c which are upper semi-continuous and satisfy $\sup_{x \in E_c} \tilde{s}(x) = 1$. Then we note $\mathcal{F}^0(E_c) \subset \mathcal{F}(E_c)$. Let $\tilde{p}_0 \in \mathcal{F}^0(E_c)$ be a fuzzy set. Define a sequence of fuzzy sets $\{\tilde{p}_n\}_{n=0}^{\infty}$ by

$$\tilde{p}_{n+1}(y) = \sup_{x \in E_c} \left\{ \tilde{p}_n(x) \wedge \tilde{q}(x,y) \right\} \quad y \in E_c \quad \text{for } n \ge 0.$$
(4.1)

The fuzzy set \tilde{p}_0 , in [5], is called an initial fuzzy state and the sequence $\{\tilde{p}_n\}_{n=0}^{\infty}$ is called a sequence of fuzzy states. The fuzzy relation \tilde{q} is also restricted on $E_c \times E_c$ and it is assumed to be continuous on $E_c \times E_c$ and satisfy $\tilde{q}(x,\cdot) \in \mathcal{F}^0(E)$. Define a map $\tilde{r}_{\alpha}: \mathcal{C}(E_c) \mapsto \mathcal{C}(E_c)$ ($\alpha \in [0,1]$) by

$$\tilde{r}_{\alpha}(D) := \begin{cases} \{y \mid \tilde{q}(x,y) \geq \alpha \text{ for some } x \in D\} & \text{for } \alpha > 0, \ D \in \mathcal{C}(E_c), \ D \neq \emptyset, \\ \operatorname{cl}\{y \mid \tilde{q}(x,y) > 0 \text{ for some } x \in D\} & \text{for } \alpha = 0, \ D \in \mathcal{C}(E_c), \ D \neq \emptyset, \\ E_c & \text{for } 0 \leq \alpha \leq 1, \ D = \emptyset. \end{cases}$$

In the sequel we assume the following contraction property for the fuzzy relation \tilde{q} (see [5, Section 2]): There exists a real number $\beta \in (0,1)$ satisfying

$$\rho(\tilde{r}_{\alpha}(A), \tilde{r}_{\alpha}(B)) \leq \beta \ \rho(A, B)$$
 for all $A, B \in \mathcal{C}(E_c)$ and all $\alpha \in [0, 1]$.

Lemma 4.1 ([5, Theorem 1]).

(i) There exists a unique fuzzy state $\tilde{p} \in \mathcal{F}^0(E_c)$ satisfying

$$\tilde{p}(y) = \max_{x \in E_c} \{ \tilde{p}(x) \land \tilde{q}(x, y) \} \qquad y \in E_c.$$
(4.2)

(ii) The sequence $\{\tilde{p}_n\}_{n=0}^{\infty}$ converges to a unique solution $\tilde{p} \in \mathcal{F}^0(E_c)$ of (4.2) independently of the initial fuzzy state \tilde{p}_0 . Namely,

$$\lim_{n\to\infty}\tilde{p}_n=\tilde{p},$$

where the convergence means $\sup_{\alpha \in [0,1]} \rho(\tilde{p}_{n,\alpha}, \tilde{p}_{\alpha}) \to 0 \ (n \to \infty)$ provided $\tilde{p}_{n,\alpha}, \tilde{p}_{\alpha}$ are α -cuts $(\alpha \in [0,1])$ for the fuzzy states \tilde{p}_n, \tilde{p} respectively.

Proposition 4.1. The α -cut of the solution \tilde{p} of (4.2) is

$$\tilde{p}_{\alpha} = \operatorname{cl}\left\{x \in E_c \mid \sup_{n \ge 1} \tilde{q}^n(x, x) \ge \alpha\right\} \quad \text{for } \alpha \in (0, 1].$$

Finally we prove that the closure of the union of all α -recurrent sets equals to α -cuts of the limit fuzzy state \tilde{p} . Now we compare (1.1) and (4.1). Using the inverse fuzzy relation \hat{q} ([3, Section 3.2]):

$$\hat{q}(x,y) := \tilde{q}(y,x)$$
 $x,y \in E_c$,

we find that (4.1) follows

$$\tilde{p}_{n+1}(x) = \sup_{x \in E_c} \{\hat{q}(x,y) \wedge \tilde{p}_n(y)\} \quad x \in E_c \quad \text{for } n \ge 0.$$

Therefore we can apply the results in Sections 1-3 to a dynamic fuzzy system defined by the inverse fuzzy relation \hat{q} .

Theorem 4.1.

$$\tilde{p}_{\alpha} = \operatorname{cl}\left\{x \in E_{c} \mid \sup_{n \geq 1} \tilde{q}^{n}(x, x) \geq \alpha\right\} = \operatorname{cl}\left(\bigcup_{A \in \mathcal{E}(E) : \alpha - \operatorname{recurrent sets}} A\right) \quad \text{for } \alpha \in (0, 1].$$

Further it is the maximum α -recurrent set for X.

5. The monotone case

In general, there does not always exist the maximum α -recurrent set for the dynamic fuzzy system X, however we can consider the existence of the maximal α -recurrent sets. In this section we deal with a case when the transition fuzzy relation \tilde{q} has a certain monotone property (see Section 6 for numerical examples). Then we prove the existence of at most countable arcwise connected maximal α -recurrent sets.

In this section we use the notations in Sections 1-3. Further we introduce the following notations of α -cuts ([5, Section 2]):

$$\begin{split} \tilde{q}_{\alpha}(x) &:= \{ y \in E \mid \tilde{q}(x,y) \geq \alpha \} \quad \text{for } x \in E \text{ and } \alpha \in (0,1]; \\ \tilde{q}_{\alpha}(A) &:= \bigcup_{x \in A} \tilde{q}_{\alpha}(x) \quad \text{for } A \in \mathcal{E}(E) \text{ and } \alpha \in (0,1]; \\ \tilde{q}_{0}(A) &:= \text{cl}(\bigcup_{\alpha > 0} \tilde{q}_{\alpha}(A)) \quad \text{for } A \in \mathcal{E}(E). \end{split}$$

For $\alpha \in (0,1]$ and $x \in E$ we define a sequence $\{\tilde{q}^m_\alpha(x)\}_{m=1,2,\cdots}$:

$$\tilde{q}^1_{\alpha}(x) := \tilde{q}_{\alpha}(x);$$
 and $\tilde{q}^{m+1}_{\alpha}(x) := \tilde{q}_{\alpha}(\tilde{q}^m_{\alpha}(x))$ for $m = 1, 2, \cdots$.

We also need some elementary notations in the finite dimensional Euclidean space E: x + y denotes the sum of $x, y \in E$ and γx denotes the product of a real number γ and $x \in E$. We put $A + B := \{x + y \mid x \in A, y \in B\}$ for $A, B \in \mathcal{E}(E)$. Then we define a half line on E by

$$l(x,y) := \{\gamma(y-x) \mid \text{real numbers } \gamma \geq 0\} \quad \text{for } x,y \in E.$$

Definition. We call a transition fuzzy relation \tilde{q} unimodal provided that $\tilde{q}_{\alpha}(x)$ are bounded closed convex subsets of E for all $\alpha \in (0,1]$ and all $x \in E$.

Definition. We call a unimodal transition fuzzy relation \tilde{q} monotone provided that

$$\tilde{q}_{\alpha}(y) \subset \tilde{q}_{\alpha}(x) + l(x,y)$$
 for all $\alpha \in (0,1]$ and all $x,y \in E$.

From now on we deal with only unimodal fuzzy relations \tilde{q} , which is monotone and continuous on $E \times E$. The monotonicity is a natural extension of one-dimensional models with the linear structure in [12] and means that the fuzzy relations \tilde{q} keeps the partial order of fuzzy numbers (see (C.iii') in Section 6).

Theorem 5.1. Assume that \tilde{q} is monotone. Let $\alpha \in (0,1]$. Then

$$\bigcup_{A \in \mathcal{E}(E) : \alpha - \text{recurrent sets}} A = \{ x \in E \mid \tilde{q}(x, x) \ge \alpha \}.$$

We need the following assumption on \tilde{q} , which is technical but not so strong. It means that the function \tilde{q} does not have flat areas as a curved surface (Section 6).

Assumption (A). For $\alpha \in (0,1)$,

int
$$\{(x,y) \in E \times E \mid \tilde{q}(x,y) \ge \alpha\} = \{(x,y) \in E \times E \mid \tilde{q}(x,y) > \alpha\},\$$

where int denotes the interior of a set.

Since \tilde{q} is continuous, $\{x \in E \mid \tilde{q}(x,x) \geq \alpha\}$ is represented by a disjoint sum of at most countable arcwise connected closed sets ([4]), we represent it by

$$\{x \in E \mid \tilde{q}(x,x) \ge \alpha\} = \bigcup_{n \in \mathbf{N}(\alpha)} F_{\alpha,n} \text{ for } \alpha \in (0,1),$$

where $F_{\alpha,n}$ are arcwise connected closed subsets of E and we put the index set $\mathbf{N}(\alpha)$ ($\subset \mathbf{N}$).

Theorem 5.2. We suppose Assumption (A). Let $\alpha \in (0,1)$. Then maximal α -recurrent sets for X are $F_{\alpha,n}$ $(n \in \mathbf{N}(\alpha))$.

6. Numerical examples

Let a one-dimensional state space $E = \mathbf{R}$. We consider one-dimensional numerical examples. In Section 5 we have assumed the following conditions (C.i) — (C.iv):

- (C.i) \tilde{q} is continuous on $E \times E$;
- (C.ii) \tilde{q} is unimodal;
- (C.iii) \tilde{q} is monotone;
- (C.iv) \tilde{q} satisfies Assumption (A).

When $E = \mathbf{R}$, $\mathcal{F}^0(\mathbf{R})$ means all fuzzy numbers on \mathbf{R} . From (C.ii), $\tilde{q}_{\alpha}(x)$ are bounded closed intervals of \mathbf{R} ($\alpha \in (0,1], x \in \mathbf{R}$). So we write $\tilde{q}_{\alpha}(x) = [\min \tilde{q}_{\alpha}(x), \max \tilde{q}_{\alpha}(x)]$, where $\min A$ (max A) denotes the minimum (maximum resp.) point of a interval $A \subset \mathbf{R}$. Then (C.iii) is equivalent to the following (C.iii'):

(C.iii') min $\tilde{q}_{\alpha}(\cdot)$ and max $\tilde{q}_{\alpha}(\cdot)$ are non-decreasing functions on **R** for all $\alpha \in (0,1]$.

Next we consider the following partial order \leq on $\mathcal{F}^0(\mathbf{R})$ (Nanda [6]): For $\tilde{s}, \tilde{r} \in \mathcal{F}^0(\mathbf{R})$,

 $\tilde{s} \preceq \tilde{r}$ means that $\min \tilde{s}_{\alpha} \leq \min \tilde{r}_{\alpha}$ and $\max \tilde{s}_{\alpha} \leq \max \tilde{r}_{\alpha}$ for all $\alpha \in (0,1]$.

Then we can easily find that (C.iii) is equivalent to the following (C.iii"):

(C.iii") If $\tilde{s}, \tilde{r} \in \mathcal{F}^0(\mathbf{R})$ satisfy $\tilde{s} \leq \tilde{r}$, then $Q(\tilde{s}) \leq Q(\tilde{r})$,

where $Q: \mathcal{F}^0(\mathbf{R}) \mapsto \mathcal{F}^0(\mathbf{R})$, see (4.1), is defined by

$$Q\tilde{s}(y) = \max_{x \in \mathbf{R}} {\{\tilde{s}(x) \land \tilde{q}(x,y)\}}, \quad y \in \mathbf{R} \quad \text{for } \tilde{s} \in \mathcal{F}^0(\mathbf{R}).$$

(C.iii") means that Q preserves the monotonicity on $\mathcal{F}^0(\mathbf{R})$ with respect to the order \leq . Finally (C.iv) means that the α -slice $\{x \in \mathbf{R} \mid \tilde{q}(x,x) = \alpha\}$ ($\alpha \in (0,1)$) are drawn by not areas but curved lines. We give an example of monotone fuzzy relations, which is not

contractive and does not have the linear structure in [12]. Then we calculate its maximal α -recurrent sets.

Example 6.1 (monotone case). We give a fuzzy relation by

$$\tilde{q}(x,y) = (1 - |y - x^3|) \lor 0, \quad x, y \in \mathbf{R}.$$

Then $\tilde{q}(x,y)$ satisfies the conditions (C.i) – (C.iv) (see Figure 6.1 for the fuzzy relation $\tilde{q}(x,y)$ and Figure 6.2 for the $\frac{3}{4}$ -slice).

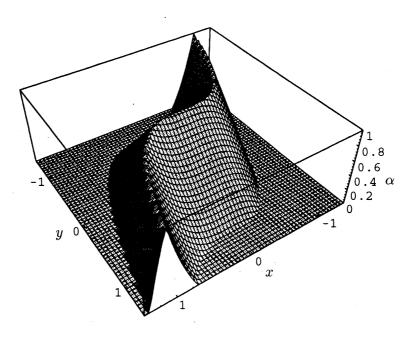


Fig. 6.1: The monotone fuzzy relation $\tilde{q}(x,y)$.

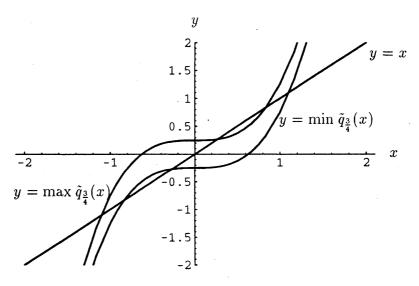


Fig. 6.2. The $\frac{3}{4}$ -level sets $\{(x,y) \mid \tilde{q}(x,y) = \frac{3}{4}\}$.

Then we have

$$\tilde{q}(x,x) = (1 - |x - x^3|) \lor 0, \quad x \in \mathbf{R}.$$

Therefore $\mathbf{N}(\frac{3}{4}) = \{0, 1, 2\}$ and

$$\begin{cases} x \in \mathbf{R} \mid \tilde{q}(x,x) \ge \frac{3}{4} \end{cases} = F_{\frac{3}{4},0} \cup F_{\frac{3}{4},1} \cup F_{\frac{3}{4},2} \\ \approx [-1.10716, -0.837565] \cup [-0.269594, 0.269594] \cup [0.837565, 1.10716].$$

By Theorem 5.2, the maximal $\frac{3}{4}$ -recurrent sets are given by three intervals

$$\begin{array}{ll} F_{\frac{3}{4},0} & \approx [-1.10716, -0.837565], \\ F_{\frac{3}{4},1} & \approx [-0.269594, 0.269594], \\ F_{\frac{3}{4},2} & \approx [0.837565, 1.10716]. \end{array}$$

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