# SPHERICAL CONVEX BODY OF CONSTANT WIDTH AND ITS APPROXIMATION

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## 1. Basic definitions

Throughout this note, let  $\mathbb{S}^n$  denote the unit sphere of the (n+1)-dimensional Euclidean space  $\mathbb{R}^{n+1}$ . For any given point P of  $\mathbb{S}^n$ , we denote by H(P) the hemisphere whose center is P, namely,

$$H(P) = \{ Q \in \mathbb{S}^n \mid P \cdot Q \ge 0 \}.$$

Here the dot in the center stands for the scalar product of P,Q in  $\mathbb{R}^{n+1}$ . A non-empty subset W of  $\mathbb{S}^n$  is hemispherical if there exists a point P of  $\mathbb{S}^n$  such that the intersection set  $W \cap H(P)$  is the empty set. A hemispherical set W of  $\mathbb{S}^n$  is said to be spherical convex if the arc PQ between any two points  $P,Q \in W$  lies in the W. Here

$$PQ = \left\{ \frac{tP + (1-t)Q}{||tP + (1-t)Q||} \in \mathbb{S}^n \mid 0 \le t \le 1 \right\}.$$

Denote the boundary of W is denoted by  $\partial W$ . A spherical convex set W of  $\mathbb{S}^n$  is said to be *spherical convex body* if W has an interior point and closed. For any subset W of  $\mathbb{S}^n$ , the *spherical polar set* of W, denoted by  $W^{\circ}$ , is the following set,

$$\bigcap_{P\in W} H(P).$$

For any non-empty closed hemispherical subset  $W \subset \mathbb{S}^n$ , the equality s-conv $(W) = (\text{s-conv}(W))^{\circ \circ}$  holds ([15]), where s-conv(W) is the spherical convex hull of W, that is, the smallest spherical convex body contains W. The diameter of a spherical convex body W is defined by

$$\max\{|PQ| \mid P,Q \in W\}.$$

A spherical convex body W is said to be constant diameter  $\tau$ , if the diameter of K is  $\tau$ , and for every point  $P \in \partial W$  there exists a point Q of  $\partial W$  such that  $|PQ| = \tau$  ([12]). We say a hemisphere H(Q) supports W at P if W is a subset of H(Q) and P is a point of  $\partial W \cap \partial H(Q)$ . The hemisphere H(Q) as defined above is called a supporting hemisphere of W at P. For any two points P, Q of  $\mathbb{S}^n$ , the intersection

$$H(P) \cap H(Q)$$

is called a *lune*, where  $P \neq -Q$ . The *thickness* of lune  $H(P) \cap H(Q)$  is the real number  $\pi - |PQ|$ , denoted by  $\Delta(H(P) \cap H(Q))$ . Namely,

$$\Delta(H(P) \cap H(Q)) = \pi - |PQ|$$
.

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It is clear that thickness of any lune is greater than 0 and less than  $\pi$ . Let H(P) be a supporting hemisphere of a spherical convex body W. The width of W with respect to H(P) is defined by ([9])

$$\operatorname{width}_{H(P)}(K) = \min \{ \Delta(H(P) \cap H(Q)) \mid W \subset H(Q) \}.$$

The minimum width of W is called thickness of W, denoted by  $\Delta W$ . Following [9], a spherical convex body W is said to be of constant width, if all widths of W with respect to any supporting hemispheres H(P) are equal; and a convex body W of  $\mathbb{S}^n$  is said to be reduced if  $\Delta(X) < \Delta(W)$  for every convex body X properly contained in W.

#### 2. Some results

# 2.1. Width of spherical convex bodies.

**Lemma 2.1** ([15]). The subset  $\mathcal{P}$  is a spherical polytope if and only if  $\mathcal{P}^{\circ}$  is a spherical polytope.

**Lemma 2.2** ([12]). Every spherical convex body of constant width smaller than  $\pi/2$  on  $S^n$  is strictly convex.

**Lemma 2.3** ([8]). Let C be a spherical convex body in  $S^n$ , and  $0 < \tau < \pi$ . The following two statements are equivalent:

- (1) C is of constant width  $\tau$ ;
- (2)  $C^{\circ}$  is of constant width  $\pi \tau$ .

An alternative proof of Lemma 2.3 in the case of  $\mathbb{S}^2$  is given in [14].

**Theorem 1** ([8, 13]). Let C be a spherical convex body in  $S^n$ , and  $0 < \tau < \pi$ . The following two statements are equivalent:

- (1) C is of constant diameter  $\tau$ ;
- (2) C is of constant width  $\tau$ .

Then by Theorem 1 and Lemma 2.3 we have the following:

Corollary 2.1 ([8]). Let C be a spherical convex body in  $\mathbb{S}^n$ , and  $0 < \tau < \pi$ . The following two propositions are equivalent:

- (1) C is of constant diameter  $\tau$ ;
- (2)  $C^{\circ}$  is of constant diameter  $\pi \tau$ .

We say a spherical convex body C is self-dual if  $C = C^{\circ}$ . A characterization of self-dual spherical convex body is given as follows:

**Theorem 2** ([6]). Let C be a spherical convex body. Then the following two statements are equivalent:

- (1) C is self dual;
- (2) C is of constant width  $\pi/2$ .

Let  $\mathcal{P}$  be a spherical polytope. By Lemma 2.4, its dual  $\mathcal{P}^{\circ}$  is a spherical polytope. By Lemma 2.3, if  $\mathcal{P}$  is of constant width  $\tau$  if and only if  $\mathcal{P}^{\circ}$  is of constant width  $\pi - \tau$  for any  $0 < \tau < \pi$ . Then by Lemma 2.2, we have the following fact:

**Lemma 2.4** ([2]). Let  $\mathcal{P}$  be a hemispherical convex polytope of constant width  $\tau$ . Then  $\tau = \pi/2$ .

Then by Lemma 2.4, Theorem 2 and Theorem 1, we know that the condition  $\pi/2$  of Theorem 2 is unnecessary if  $\mathcal{P}$  is a convex polytope:

**Theorem 3** ([2]). Let Wulff shape  $\mathcal{P}$  be a spherical convex polytope. Then the following there statements are equivalent:

- (1)  $\mathcal{P}$  is self-dual;
- (2)  $\mathcal{P}$  is of constant width spherical convex body;
- (3)  $\mathcal{P}$  is of constant width spherical convex body.

A Problem 2.7 from [11]: "Do there exist reduced spherical *n*-dimensional polytopes (possibly some simplices?) on  $\mathbb{S}^n$ , where  $n \geq 3$ , different from the  $1/2^n$  part of  $\mathbb{S}^n$ ?"

An affirmative answer (in the case n=3): Let Q be an interior point of the spherical convex hull of  $\{P_1, P_2, P_3, -N\}$  of  $\mathbb{S}^3$ . Set

$$Q_i = \partial H(Q) \cap NP_i, \quad i = 1, 2, 3.$$

Then the spherical polytope

$$\mathcal{P} = \text{s-conv}\{Q_1, Q_2, Q_3, P_1, P_2, P_3, Q\}$$

is of constant width  $\pi/2$  (see the proof in general case in [2]).

# 2.2. Approximation of spherical convex bodies of constant width.

**Theorem 4** ([10]). For any spherical convex body  $C \subset S^2$  of constant width  $\tau < \pi/2$ , and for any  $\varepsilon > 0$  there exists a body  $C_{\varepsilon}$  of constant width  $\Delta(C) = \Delta(C_{\varepsilon})$  whose boundary consists only of arcs of circles of radius  $\Delta(C)$  such that

$$h(C, C_{\varepsilon}) \leq \varepsilon$$
,

where  $h(C_1, C_2)$  means the Hausdorff distance between  $C_1$  and  $C_2$ .

In [4], applying the fact that spherical dual transform is an isometry ([7]) and the relationships between boundary of C and its dual obtains a counterpart result of Theorem 4 as follows:

**Theorem 5** ([4]). For any spherical convex body  $\widetilde{C} \subset S^2$  of constant width  $\tau > \pi/2$ , and for any  $\varepsilon > 0$  there exists a body  $\widetilde{C}_{\varepsilon}$  of constant width  $\tau$  whose boundary consists only of arcs of circles of radius  $\tau - \frac{\pi}{2}$  and great circle arcs, such that

$$h(\widetilde{C}, \widetilde{C}_{\varepsilon}) \le \varepsilon,$$

where h is the Hausdorff distance.

Notice that the spherical convex body of C in Theorem 4 is of constant width  $\tau < \pi/2$  and the spherical convex body of C in Theorem 5 is of constant width  $\tau > \pi/2$ . For the remaining case (the spherical convex body C of  $\pi/2$ ), we have a conjecture as follows.

Conjecture: Any spherical convex body of constant width  $\pi/2$  can be approximated by a sequence of spherical convex polytopes of constant width  $\pi/2$  ([4]).

Since a polytope  $\mathcal{P}$  is of constant width  $\tau$ , then  $\tau = \pi/2$  (Lemma 2.4). This means any spherical convex body of constant width  $\tau \neq \pi/2$  can not be approximated by a sequence of spherical convex polytopes of constant width  $\tau$ .

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## 3. Applications to Wulff shapes

Let  $\gamma: \mathbb{S}^n \to \mathbb{R}_+$  be a continuous function, where  $\mathbb{R}_+$  is the set consisting of positive real numbers. Then the Wulff shape associated with the function  $\gamma$ , denoted by  $\mathcal{W}_{\gamma}$ , is defined by

$$\bigcap_{\theta \in \mathbb{S}^n} \Gamma_{\gamma,\theta}.$$

Here  $\Gamma_{\gamma,\theta}$  is the half space determined by the given continuous function  $\gamma$  and  $\theta \in \mathbb{S}^n$ ,

$$\Gamma_{\gamma,\theta} = \{ x \in \mathbb{R}^{n+1} \mid x \cdot \theta \le \gamma(\theta) \}.$$

By definition, Wulff shape is a convex body, namely, convex, compact and contains the origin of  $\mathbb{R}^{n+1}$  as an interior point. Conversely, for any convex body W contains the origin of  $\mathbb{R}^{n+1}$  as an interior point, there exits a continuous function  $\gamma: \mathbb{S}^n \to \mathbb{R}_+$  such that  $\mathcal{W}_{\gamma} = W$ . For more details in Wulff shapes, see for instance [1, 3, 5]. Let  $Id: \mathbb{R}^{n+1} \to \mathbb{R}^{n+1} \times \{1\} \subset \mathbb{R}^{n+2}$  be the mapping defined by

$$Id(x) = (x, 1).$$

Let  $N = (0, ..., 0, 1) \in \mathbb{R}^{n+2}$  be the north pole of  $\mathbb{S}^{n+1}$ , and let  $\mathbb{S}^{n+1}_{N,+}$  denote the north open hemisphere of  $\mathbb{S}^{n+1}$ ,

$$\mathbb{S}_{N,+}^{n+1} = \mathbb{S}^{n+1} \backslash H(-N) = \{ Q \in \mathbb{S}^{n+1} \mid N \cdot Q > 0 \}.$$

Let  $\alpha_N: \mathbb{S}_{N,+}^{n+1} \to \mathbb{R}^{n+1} \times \{1\}$  be the central projection relative to N, defined by

$$\alpha_N(P_1, \dots, P_{n+1}, P_{n+2}) = \left(\frac{P_1}{P_{n+2}}, \dots, \frac{P_{n+1}}{P_{n+2}}, 1\right).$$

We call the spherical convex body  $\widetilde{W}_{\gamma} = \alpha^{-1}(Id(\mathcal{W}_{\gamma}))$  is the spherical Wulff shape of  $\mathcal{W}_{\gamma}$ . The Wulff shape

$$Id^{-1} \circ \alpha_N ((\alpha_N^{-1} \circ Id(\mathcal{W}_{\gamma}))^{\circ}).$$

is called dual Wulff shape of  $W_{\gamma}$ , denoted by  $\mathcal{D}W_{\gamma}$ . We call a Wulff shape W is a self-dual if  $W = \mathcal{D}W$ , namely, W and its dual Wulff shape  $\mathcal{D}W$  are exactly the same convex body. By Theorem 1, Lemma 2.3 and Corollary 2.1, we have the following.

Corollary 3.1 ([8]). Let  $\gamma: \mathbb{S}^n \to \mathbb{R}_+$  be a continuous function. Suppose that the spherical Wulff shape  $\widetilde{W}_{\gamma} = \alpha_N^{-1} \circ Id(\mathcal{W}_{\gamma})$  of  $\mathcal{W}_{\gamma}$  is of constant width. Then

- (1)  $\Delta(\widetilde{W}_{\gamma}) + diam(\widetilde{W}_{\gamma}^{\circ}) = \pi,$
- (2)  $\Delta(\widetilde{W}_{\gamma}) + \Delta(\widetilde{W}_{\gamma}^{\circ}) = \pi$ ,
- (3)  $diam(\widetilde{W}_{\gamma}) + \Delta (\widetilde{W}_{\gamma}^{\circ}) = \pi,$
- (4)  $\operatorname{diam}(\widetilde{W}_{\gamma}) + \operatorname{diam}(\widetilde{W}_{\gamma}^{\circ}) = \pi,$

where  $\Delta(C)$  and diam(C) are the width and the diameter of spherical convex body C in  $S^n$ , respectively.

A characterization of self-dual Wulff shape is given as follows.

**Proposition 3.1** ([6]). Let  $\gamma: \mathbb{S}^n \to \mathbb{R}_+$  be a continuous function. Then  $W_{\gamma}$  is a self-dual Wulff shape if and only if its spherical Wulff shape is of constant width  $\pi/2$ , namely, the spherical convex body  $\alpha_N^{-1} \circ Id(W_{\gamma})$  is of constant width  $\pi/2$ .

By Theorem 1, we have the following:

Corollary 3.2 ([8]). Let  $\gamma: \mathbb{S}^n \to \mathbb{R}_+$  be a continuous function. Then  $W_{\gamma}$  is a self-dual Wulff shape if and only if its spherical Wulff shape is of constant diameter  $\pi/2$ , namely, the spherical convex body  $\alpha_N^{-1} \circ Id(W_{\gamma})$  is of constant diameter  $\pi/2$ .

By Theorem 3, we have the following:

**Theorem 6** ([2]). Let Wulff shape  $W_{\gamma}$  be a convex polytope. Then the following statements are equivalent:

- (1) the Wulff shape  $W_{\gamma}$  is self-dual;
- (2) the spherical Wulff shape of  $W_{\gamma}$  is constant width;
- (3) the spherical Wulff shape of  $W_{\gamma}$  is constant diameter.

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