

# The Einstein-Hilbert type action on almost multi-product manifolds

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**Abstract.** A Riemannian manifold endowed with  $k > 2$  complementary orthogonal distributions (called a Riemannian almost multi-product structure) appears in such topics as multiply twisted or warped products, the webs or nets composed of several foliations, Ricci curvature and Einstein equations, multi-time geometric dynamics and Dupin hypersurfaces. In the paper we consider the mixed scalar curvature of such structure, derive Euler-Lagrange equations for the Einstein-Hilbert type action with respect to adapted variations of metric, and present them in a nice form of Einstein equation.

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## 1 Introduction

Many examples of Riemannian metrics come (as critical points) from variational problems, a particularly famous of which is the *Einstein-Hilbert action*, e.g., [5]. The Euler-Lagrange equation for this action (called the *Einstein equation*) is

$$(1.1) \quad \text{Ric} - (1/2)S \cdot g + \Lambda g = \mathfrak{a} \cdot \Xi$$

where  $g$  is a pseudo-Riemannian metric on a smooth manifold  $M$ , Ric – the Ricci curvature,  $S$  – the scalar curvature,  $\Lambda$  – a constant (the “cosmological constant”),  $\mathcal{L}$  – Lagrangian describing the matter contents,  $\mathfrak{a}$  – the coupling constant involving the gravitational constant and the speed of light and  $\Xi$  – the energy-momentum tensor. The solution of (1.1) is a metric, satisfying this equation, where the tensor  $\Xi$  is given. The classification of solutions of (1.1) is a deep and largely unsolved problem [5].

Distributions on a manifold (i.e., subbundles of the tangent bundle) appear in various situations, e.g., [4, 8] and are used to build up notions of integrability, and specifically of a foliated manifold. On a manifold equipped with an additional structure, e.g., almost product or contact, one can consider an analogue of the Einstein-Hilbert

action adjusted to that structure. This approach was taken in [2, 3, 11, 14, 15], for  $M$  endowed with a distribution  $\mathcal{D}$  or a foliation.

In this article, continuing our study [2, 3, 11, 14, 14], a similar change in the classical action is considered on an almost multi-product structure  $(M, g; \mathcal{D}_1, \dots, \mathcal{D}_k)$ , see [13], i.e., a connected smooth  $n$ -dimensional manifold endowed with  $k > 2$  pairwise orthogonal  $n_i$ -dimensional distributions with  $\sum n_i = n$ . The notion of a multiply warped product, e.g., [6], is a special case of this structure, which can be also viewed in the theory of webs and nets composed of different foliations, see [1], in studies of the curvature and Einstein equations, see [7], multi-time geometric dynamics and Dupin hypersurfaces. The *mixed Einstein-Hilbert action* on  $(M, \mathcal{D}_1, \dots, \mathcal{D}_k)$ , defined by

$$(1.2) \quad J_{\mathcal{D}} : g \mapsto \int_M \left\{ \frac{1}{2\mathbf{a}} (S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - 2\Lambda) + \mathcal{L} \right\} d \text{vol}_g,$$

is an analog of the Einstein-Hilbert action, where  $S$  is replaced by the mixed scalar curvature  $S_{\mathcal{D}_1, \dots, \mathcal{D}_k}$ , see (2.1). To deal also with non-compact manifolds (“spacetimes”), it is assumed that the integral above is taken over  $M$  if it converges; otherwise, one integrates over arbitrarily large, relatively compact domain  $\Omega \subset M$ , which also contains supports of variations of  $g$ . The geometrical part of (1.2) is the *total mixed scalar curvature* of  $(M, g; \mathcal{D}_1, \dots, \mathcal{D}_k)$

$$(1.3) \quad J_{\mathcal{D}}^g : g \mapsto \int_M S_{\mathcal{D}_1, \dots, \mathcal{D}_k} d \text{vol}_g.$$

The mixed scalar curvature is the simplest curvature invariant of a pseudo-Riemannian almost product structure, which can be defined as an averaged sum of sectional curvatures of planes that non-trivially intersect with both of the distributions. Investigation of  $S_{\mathcal{D}_1, \mathcal{D}_1^\perp}$  led to multiple results regarding the existence of foliations and submersions with interesting geometry, e.g., integral formulas and splitting results, curvature prescribing and variational problems, see [12, 16, 18]. Varying (1.2) as a functional of adapted metric  $g$ , we obtain the Euler-Lagrange equations in the beautiful form of Einstein equation (1.1), i.e.,

$$(1.4) \quad \text{Ric}_{\mathcal{D}} - (1/2) S_{\mathcal{D}} \cdot g + \Lambda g = \mathbf{a} \cdot \Xi,$$

where the Ricci tensor and the scalar curvature are replaced by the Ricci type tensor  $\text{Ric}_{\mathcal{D}}$ , see (3.16), and its trace  $S_{\mathcal{D}}$ , and  $\Xi$  is given by  $\Xi_{\mu\nu} = -2 \partial \mathcal{L} / \partial g^{\mu\nu} + g_{\mu\nu} \mathcal{L}$ .

Using the equality

$$S = 2 S_{\mathcal{D}_1, \dots, \mathcal{D}_k} + \sum_i S(\mathcal{D}_i),$$

where  $S(\mathcal{D}_i)$  is the scalar curvature of the distribution  $\mathcal{D}_i$ , one can combine the Einstein-Hilbert action on  $(M, \mathcal{D}_1, \dots, \mathcal{D}_k)$  (e.g., [9] for multiply warped products) with our action (1.2). The result is the perturbed Einstein-Hilbert action, whose critical points describe the “space-times” in an extended theory of gravity. The geometrical part of this action is  $J_{\mathcal{D}, \varepsilon} : g \mapsto \int_M (S + \varepsilon S_{\mathcal{D}_1, \dots, \mathcal{D}_k}) d \text{vol}_g$ ,  $\varepsilon \in \mathbb{R}$ .

Our action (1.2) can also be useful in studying the interaction of several  $m$ -flows ( $m$ -dimensional distributions) in multi-time geometric dynamics, e.g., [10, 17].

We delegate the following questions for further study:

- a) generalize our results for arbitrary variations of metrics;
- b) extend our results for metric-affine manifolds (as in Einstein-Cartan theory);
- c) find applications of our results in geometry, dynamics and physics.

## 2 The mixed scalar curvature

Here, we recall the properties of the mixed scalar curvature of a Riemannian multi-product manifold  $(M, g; \mathcal{D}_1, \dots, \mathcal{D}_k)$ , see [13]. A pseudo-Riemannian metric  $g = \langle \cdot, \cdot \rangle$  of index  $q$  on a smooth manifold  $M$  is an element  $g \in \text{Sym}^2(M)$  (of the space of symmetric  $(0, 2)$ -tensors) such that each  $g_x$  ( $x \in M$ ) is a non-degenerate bilinear form of index  $q$  on the tangent space  $T_x M$ . For  $q = 0$  (i.e.,  $g_x$  is positive definite)  $g$  is a Riemannian metric and for  $q = 1$  it is called a Lorentz metric. A distribution  $\mathcal{D}$  on  $(M, g)$  is *non-degenerate*, if  $g_x$  is non-degenerate on  $\mathcal{D}_x \subset T_x M$  for all  $x \in M$ ; in this case, the orthogonal complement of  $\mathcal{D}^\perp$  is also non-degenerate. Denote by  $\text{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$  the subspace of *adapted pseudo-Riemannian metrics*, that is making  $\{\mathcal{D}_i\}$  pairwise orthogonal and non-degenerate. Let  $P_i : TM \rightarrow \mathcal{D}_i$  be the orthoprojector, then  $P_i^\perp = \text{id}_{TM} - P_i$  is the orthoprojector onto  $\mathcal{D}_i^\perp$ . The second fundamental form  $h_i : \mathcal{D}_i \times \mathcal{D}_i \rightarrow \mathcal{D}_i^\perp$  and the skew-symmetric integrability tensor  $T_i : \mathcal{D}_i \times \mathcal{D}_i \rightarrow \mathcal{D}_i^\perp$  of  $\mathcal{D}_i$  are defined by

$$\begin{aligned} h_i(X, Y) &= \frac{1}{2} P_i^\perp (\nabla_X Y + \nabla_Y X), \\ T_i(X, Y) &= \frac{1}{2} P_i^\perp (\nabla_X Y - \nabla_Y X) = \frac{1}{2} P_i^\perp [X, Y]. \end{aligned}$$

Similarly,  $h_i^\perp$ ,  $H_i^\perp = \text{Tr}_g h_i^\perp$ ,  $T_i^\perp$  are the second fundamental forms, mean curvature vector fields and the integrability tensors of distributions  $\mathcal{D}_i^\perp$  in  $M$ . Note that  $H_i = \sum_{j \neq i} P_j H_i$ , etc. Recall that a distribution  $\mathcal{D}_i$  is called *integrable* if  $T_i = 0$ , and  $\mathcal{D}_i$  is called *totally umbilical*, *harmonic*, or *totally geodesic*, if  $h_i = (H_i/n_i)g$ ,  $H_i = 0$ , or  $h_i = 0$ , respectively.

Given  $g \in \text{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$ , there is a local orthonormal frame  $\{E_1, \dots, E_n\}$  on  $M$ , where  $\{E_1, \dots, E_{n_1}\} \subset \mathcal{D}_1$  and  $\{E_{n_{i-1}+1}, \dots, E_{n_i}\} \subset \mathcal{D}_i$  for  $2 \leq i \leq k$ , and  $\varepsilon_a = \langle E_a, E_a \rangle \in \{-1, 1\}$ . All quantities defined below using such frame do not depend on the choice of this frame.

A plane  $X \wedge Y$  in  $TM$  spanned by two vectors belonging to different distributions  $\mathcal{D}_i$  and  $\mathcal{D}_j$  will be called *mixed*, and the sectional curvature  $K(X, Y) = R(X, Y X, Y) / (\langle X, X \rangle \langle Y, Y \rangle - \langle X, Y \rangle^2)$  is said to be mixed. The mixed scalar curvature of  $(M, g; \mathcal{D}_1, \dots, \mathcal{D}_k)$  is defined as an averaged mixed sectional curvature.

**Definition 2.1** (see [13]). Given  $g \in \text{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$  with  $k \geq 2$ , the following function on  $M$  will be called the *mixed scalar curvature*:

$$(2.1) \quad S_{\mathcal{D}_1, \dots, \mathcal{D}_k} = \sum_{i < j} \sum_{n_{i-1} < a \leq n_i, n_{j-1} < b \leq n_j} K(E_a, E_b),$$

where  $K(E_a, E_b) = \varepsilon_a \varepsilon_b \langle R(E_a, E_b) E_a, E_b \rangle$  is the mixed sectional curvature of the plane  $E_a \wedge E_b$ . The following symmetric  $(0, 2)$ -tensor  $r$  is called the *partial Ricci tensor*:

$$r(X, Y) = \frac{1}{2} \sum_i r_{\mathcal{D}_i}(X, Y), \quad X, Y \in \mathfrak{X}_M,$$

where the partial Ricci tensor related to  $\mathcal{D}_i$  is

$$(2.2) \quad r_{\mathcal{D}_i}(X, Y) = \sum_{n_{i-1} < a \leq n_i} \varepsilon_a \langle R_{E_a, P_i^\perp X} E_a, P_i^\perp Y \rangle, \quad X, Y \in \mathfrak{X}_M.$$

**Proposition 2.1.** *We have*

$$S_{\mathcal{D}_1, \dots, \mathcal{D}_k} = \frac{1}{2} \sum_i S_{\mathcal{D}_i, \mathcal{D}_i^\perp} = \text{Tr}_g r.$$

*Proof.* This follows from definitions (2.1)–(2.2) and the equality  $\text{Tr}_g r_{\mathcal{D}_i} = S_{\mathcal{D}_i, \mathcal{D}_i^\perp}$ .  $\square$

Recall that the divergence of a  $(1, s)$ -tensor field  $S$  on  $(M, g)$  is a  $(0, s)$ -tensor field

$$\text{div } S = \text{trace}(Y \rightarrow \nabla_Y S).$$

For  $s = 0$ , we get the divergence  $\text{div } X = \text{Tr}(\nabla X)$  of a vector field  $X$ , e.g., [5].

The squares of norms of tensors are obtained using

$$\begin{aligned} \langle h_i, h_i \rangle &= \sum_{n_{i-1} < a, b \leq n_i} \varepsilon_a \varepsilon_b \langle h_i(E_a, E_b), h_i(E_a, E_b) \rangle, \\ \langle T_i, T_i \rangle &= \sum_{n_{i-1} < a, b \leq n_i} \varepsilon_a \varepsilon_b \langle T_i(E_a, E_b), T_i(E_a, E_b) \rangle. \end{aligned}$$

The following formula for a Riemannian manifold  $(M, g)$  endowed with two complementary orthogonal distributions  $\mathcal{D}$  and  $\mathcal{D}^\perp$ , see [18]:

$$(2.3) \quad \begin{aligned} \text{div}(H + H^\perp) &= S_{\mathcal{D}, \mathcal{D}^\perp} \\ &+ \langle h, h \rangle + \langle h^\perp, h^\perp \rangle - \langle H, H \rangle - \langle H^\perp, H^\perp \rangle - \langle T, T \rangle - \langle T^\perp, T^\perp \rangle, \end{aligned}$$

has many interesting global corollaries (e.g., decomposition criteria using the sign of  $S$ , [16]). In [13], we generalized (2.3) to  $(M, g)$  with  $k > 2$  distributions and gave applications to splitting and isometric immersions of manifolds, in particular, multiply warped products. Set

$$(2.4) \quad Q(\mathcal{D}, g) = \langle H^\perp, H^\perp \rangle + \langle H, H \rangle - \langle h, h \rangle - \langle h^\perp, h^\perp \rangle + \langle T, T \rangle + \langle T^\perp, T^\perp \rangle,$$

then (2.3) can be written as

$$(2.5) \quad S_{\mathcal{D}, \mathcal{D}^\perp} = Q(\mathcal{D}, g) + \text{div}(H + H^\perp).$$

The mixed scalar curvature of a pair of distributions  $(\mathcal{D}_i, \mathcal{D}_i^\perp)$  on  $(M, g)$  is

$$S_{\mathcal{D}_i, \mathcal{D}_i^\perp} = \sum_{n_{i-1} < a \leq n_i, b \neq (n_{i-1}, n_i]} \varepsilon_a \varepsilon_b \langle R_{E_a, E_b} E_a, E_b \rangle.$$

If  $\mathcal{D}_i$  is spanned by a unit vector field  $N$ , i.e.,  $\langle N, N \rangle = \varepsilon_N$ , then

$$S_{\mathcal{D}_i, \mathcal{D}_i^\perp} = \varepsilon_N \text{Ric}_{N, N},$$

where  $\text{Ric}_{N, N}$  is the Ricci curvature in the  $N$ -direction. We have

$$S_{\mathcal{D}_i, \mathcal{D}_i^\perp} = \text{Tr}_g r_{\mathcal{D}_i} = \text{Tr}_g r_{\mathcal{D}_i^\perp}.$$

If  $\dim \mathcal{D}_i = 1$  then  $r_{\mathcal{D}_i} = \varepsilon_N R_N$ , where  $R_N = R(N, \cdot)N$  is the Jacobi operator, and  $r_{\mathcal{D}_i^\perp} = \text{Ric}_{N, N} g_i^\perp$ , where  $g_i^\perp(X, Y) := \langle P_i^\perp X, P_i^\perp Y \rangle$  for all  $X, Y \in \mathfrak{X}_M$ .

The  $\mathcal{D}_i$ -deformation tensor of  $Z \in \mathfrak{X}_M$  is the symmetric part of  $\nabla Z$  restricted to  $\mathcal{D}_i$ ,

$$2 \text{Def}_{\mathcal{D}_i} Z(X, Y) = \langle \nabla_X Z, Y \rangle + \langle \nabla_Y Z, X \rangle, \quad X, Y \in \mathcal{D}_i.$$

The ‘‘musical’’ isomorphisms  $\sharp$  and  $\flat$  will be used for rank one and symmetric rank 2 tensors. For example, if  $\omega \in \Lambda^1(M)$  is a 1-form and  $X, Y \in \mathfrak{X}_M$  then  $\omega(Y) = \langle \omega^\sharp, Y \rangle$  and  $X^\flat(Y) = \langle X, Y \rangle$ . For arbitrary (0,2)-tensors  $B$  and  $C$  we also have

$$\langle B, C \rangle = \text{Tr}_g(B^\sharp C^\sharp) = \langle B^\sharp, C^\sharp \rangle.$$

The shape operator  $(A_i)_Z$  of  $\mathcal{D}_i$  with  $Z \in \mathcal{D}_i^\perp$ , and the operator  $(T_i)^\sharp_Z$  are defined by

$$\langle (A_i)_Z(X), Y \rangle = h_i(X, Y, Z), \quad \langle (T_i)^\sharp_Z(X), Y \rangle = \langle T_i(X, Y), Z \rangle, \quad X, Y \in \mathcal{D}_i.$$

The Casorati type operators  $\mathcal{A}_i : \mathcal{D}_i \rightarrow \mathcal{D}_i$  and  $\mathcal{T}_i : \mathcal{D}_i \rightarrow \mathcal{D}_i$ , and the (0,2)-tensor  $\Psi_i$ , see [3, 14], are defined using  $A_i$  and  $T_i$  by

$$\begin{aligned} \mathcal{A}_i &= \sum_{E_a \in \mathcal{D}_i^\perp} \varepsilon_a ((A_i)_{E_a})^2, & \mathcal{T}_i &= \sum_{E_a \in \mathcal{D}_i^\perp} \varepsilon_a ((T_i)^\sharp_{E_a})^2, \\ \Psi_i(X, Y) &= \text{Tr}((A_i)_Y (A_i)_X + (T_i)^\sharp_Y (T_i)^\sharp_X), \quad X, Y \in \mathcal{D}_i^\perp. \end{aligned}$$

We define a self-adjoint (1,1)-tensor  $\mathcal{K}_i : \mathcal{D}_i \rightarrow \mathcal{D}_i$  by the formula with Lie bracket,

$$\mathcal{K}_i = \sum_{E_a \in \mathcal{D}_i^\perp} \varepsilon_a [(T_i)^\sharp_{E_a}, (A_i)_{E_a}].$$

For any (1,2)-tensors  $Q_1, Q_2$  and a (0,2)-tensor  $S$  define the (0,2)-tensor  $\Upsilon_{Q_1, Q_2}$  by

$$\langle \Upsilon_{Q_1, Q_2}, S \rangle = \sum_{\lambda, \mu} \varepsilon_\lambda \varepsilon_\mu [S(Q_1(e_\lambda), Q_2(e_\lambda, e_\mu)) + S(Q_2(e_\lambda, e_\mu), Q_1(e_\lambda, e_\mu))],$$

where on the left-hand side we have the inner product of (0,2)-tensors induced by  $g$ ,  $\{e_\lambda\}$  is a local orthonormal basis of  $TM$  and  $\varepsilon_\lambda = \langle e_\lambda, e_\lambda \rangle \in \{-1, 1\}$ .

**Remark 2.2.** If  $g$  is definite then  $\Upsilon_{h_i, h_i} = 0$  if and only if  $h_i = 0$ . Indeed, we have

$$\langle \Upsilon_{h_i, h_i}, X^\flat \otimes X^\flat \rangle = 2 \sum_{a, b} \langle X, h_i(E_a, E_b) \rangle^2, \quad X \in \mathcal{D}_i^\perp.$$

The above sum is equal to zero if and only if every summand vanishes. This yields  $h_i = 0$ . Thus,  $\Upsilon_{h_i, h_i}$  is a ‘‘measure of non-total geodesy’’ of the distribution  $\mathcal{D}_i$ . Similarly,  $\Upsilon_{T_i, T_i}$  can be viewed as a ‘‘measure of non-integrability’’ of  $\mathcal{D}_i$ .

The following presentation of the partial Ricci tensor in (2.2) is valid, see [3, 14]:

$$(2.6) \quad r_{\mathcal{D}_i} = \text{div } h_i + \langle h_i, H_i \rangle - \mathcal{A}_i^\flat - \mathcal{T}_i^\flat - \Psi_i^\perp + \text{Def}_{\mathcal{D}_i^\perp} H_i^\perp.$$

Tracing (2.6) over  $\mathcal{D}_i$  and applying the equalities

$$\begin{aligned} \text{Tr}_g(\text{div } h_i) &= \text{div } H_i, & \text{Tr} \langle h_i, H_i \rangle &= \langle H_i, H_i \rangle, & \text{Tr}_g \Psi_i^\perp &= \langle h_i^\perp, h_i^\perp \rangle - \langle T_i^\perp, T_i^\perp \rangle, \\ \text{Tr } \mathcal{A}_i &= \langle h_i, h_i \rangle, & \text{Tr } \mathcal{T}_i &= -\langle T_i, T_i \rangle, & \text{Tr}_g(\text{Def}_{\mathcal{D}_i^\perp} H_i^\perp) &= \text{div } H_i^\perp + g(H_i^\perp, H_i^\perp), \end{aligned}$$

we get (2.3) with  $\mathcal{D} = \mathcal{D}_i$ .

**Remark 2.3.** For an almost multi-product manifold  $(M, g; \mathcal{D}_1, \dots, \mathcal{D}_k)$  we have

$$(2.7) \quad \operatorname{div} \sum_i (H_i + H_i^\perp) = 2S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - \sum_i Q(\mathcal{D}_i, g),$$

see [13]. To illustrate the proof of (2.7) for  $k > 2$ , consider the case of  $k = 3$ . Using (2.3) for two distributions,  $\mathcal{D}_1$  and  $\mathcal{D}_1^\perp = \mathcal{D}_2 \oplus \mathcal{D}_3$ , according to (2.4) and (2.5) with  $\mathcal{D} = \mathcal{D}_1$ , we get

$$\operatorname{div}(H_1 + H_1^\perp) = 2S_{\mathcal{D}_1, \mathcal{D}_1^\perp} - Q(\mathcal{D}_1, g),$$

and similarly for  $(\mathcal{D}_2, \mathcal{D}_2^\perp)$  and  $(\mathcal{D}_3, \mathcal{D}_3^\perp)$ . Summing 3 copies of (2.8), we obtain (2.7) for  $k = 3$ . Applying Stokes' Theorem for (2.7) on a closed manifold  $M$  yields the integral formulas for all  $k \in \{2, \dots, n\}$ , which for  $k = 2$  directly follows from (2.3).

### 3 Adapted variations of metric

We consider smooth 1-parameter variations  $\{g_t \in \operatorname{Riem}(M) : |t| < \varepsilon\}$  of the metric  $g_0 = g$ . Let the infinitesimal variations, represented by a symmetric  $(0, 2)$ -tensor

$$B(t) \equiv \partial g_t / \partial t,$$

be supported in a relatively compact domain  $\Omega$  in  $M$ , i.e.,  $g_t = g$  and  $B_t = 0$  outside  $\Omega$  for  $|t| < \varepsilon$ . We adopt the notations  $\partial_t \equiv \partial / \partial t$ ,  $B \equiv \partial_t g_t|_{t=0} = \dot{g}$ , but we shall also write  $B$  instead of  $B_t$  to make formulas easier to read, wherever it does not lead to confusion. Since  $B$  is symmetric, then  $\langle C, B \rangle = \langle \operatorname{Sym}(C), B \rangle$  for any  $(0, 2)$ -tensor  $C$ . Denote by  $\otimes$  the product of tensors.

**Definition 3.1.** A family of adapted pseudo-Riemannian metrics

$$\{g(t) \in \operatorname{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k) : |t| < \varepsilon\}$$

will be called an *adapted variation*. In other words,  $\mathcal{D}_i$  and  $\mathcal{D}_j$  are  $g_t$ -orthogonal for all  $i \neq j$  and  $t$ . An adapted variation  $g_t$  is called a  $\mathcal{D}_j$ -variation (for some  $j \in [1, k]$ ) if

$$g_t(X, Y) = g_0(X, Y), \quad X, Y \in \mathcal{D}_j^\perp, \quad |t| < \varepsilon.$$

For an adapted variation we have  $g_t = g_1(t) \oplus \dots \oplus g_k(t)$ , where  $g_j(t) = g_t|_{\mathcal{D}_j}$ . Thus, the tensor  $B_t = \partial_t g_t$  of an adapted variation of metric on  $(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$  is decomposed into the sum of derivatives of  $\mathcal{D}_j$ -variations; namely,  $B_t = \sum_{j=1}^k B_j(t)$ , where  $B_j(t) = \partial_t g_j(t) = B_t|_{\mathcal{D}_j}$ .

**Lemma 3.1.** Let a local adapted frame  $\{E_a\}$  evolve by  $g_t \in \operatorname{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$  according to

$$\partial_t E_a = -(1/2) B_t^\sharp(E_a).$$

Then,  $\{E_a(t)\}$  is a  $g_t$ -orthonormal adapted frame for all  $t$ .

*Proof.* For  $\{E_a(t)\}$  we have

$$\begin{aligned} \partial_t (g_t(E_a, E_b)) &= g_t(\partial_t E_a(t), E_b(t)) + g_t(E_a(t), \partial_t E_b(t)) + (\partial_t g_t)(E_a(t), E_b(t)) \\ &= B_t(E_a(t), E_b(t)) - \frac{1}{2} g_t(B_t^\sharp(E_a(t)), E_b(t)) - \frac{1}{2} g_t(E_a(t), B_t^\sharp(E_b(t))) = 0. \end{aligned}$$

From this the claim follows.  $\square$

**Lemma 3.2.** *If  $g_t$  is a  $\mathcal{D}_j$ -variation of  $g \in \text{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$ , then*

$$\begin{aligned}
\partial_t \langle h_j^\perp, h_j^\perp \rangle &= -\langle (1/2)\Upsilon_{h_j^\perp, h_j^\perp}, B_j \rangle, \\
\partial_t \langle h_j, h_j \rangle &= \langle \text{div } h_j + \mathcal{K}_j^\flat, B_j \rangle - \text{div} \langle h_j, B_j \rangle, \\
\partial_t g(H_j^\perp, H_j^\perp) &= -\langle (H_j^\perp)^\flat \otimes (H_j^\perp)^\flat, B_j \rangle, \\
\partial_t g(H_j, H_j) &= \langle (\text{div } H_j) g_j, B_j \rangle - \text{div}((\text{Tr } B_j^\sharp) H_j), \\
\partial_t \langle T_j^\perp, T_j^\perp \rangle &= \langle (1/2)\Upsilon_{T_j^\perp, T_j^\perp}, B_j \rangle, \\
(3.1) \quad \partial_t \langle T_j, T_j \rangle &= \langle 2\mathcal{T}_j^\flat, B_j \rangle,
\end{aligned}$$

and for  $i \neq j$  (when  $k > 2$ ) we have dual equations

$$\begin{aligned}
\partial_t \langle h_i, h_i \rangle &= \langle -(1/2)\Upsilon_{h_i, h_i}, B_j \rangle, \\
\partial_t \langle h_i^\perp, h_i^\perp \rangle &= \langle \text{div } h_i^\perp + (\mathcal{K}_i^\perp)^\flat, B_j \rangle - \text{div} \langle h_i^\perp, B_j \rangle, \\
\partial_t g(H_i, H_i) &= -\langle H_i^\flat \otimes H_i^\flat, B_j \rangle, \\
\partial_t g(H_i^\perp, H_i^\perp) &= \langle (\text{div } H_i^\perp) g_j, B_j \rangle - \text{div}((\text{Tr } B_j^\sharp) H_i^\perp), \\
\partial_t \langle T_i, T_i \rangle &= \langle (1/2)\Upsilon_{T_i, T_i}, B_j \rangle, \\
(3.2) \quad \partial_t \langle T_i^\perp, T_i^\perp \rangle &= \langle 2(\mathcal{T}_i^\perp)^\flat, B_j \rangle,
\end{aligned}$$

*Proof.* The equations (3.1) coincide with equations from [15, Proposition 2] for a pair  $(\mathcal{D}_j, \mathcal{D}_j^\perp)$ , and equations (3.2) are dual to (3.1).  $\square$

For any variation  $g_t$  of metric  $g$  on  $M$  with  $B = \partial_t g$  we have, e.g., [14],

$$(3.3) \quad \partial_t (\text{d vol}_g) = \frac{1}{2} (\text{Tr}_g B) \text{d vol}_g = \frac{1}{2} \langle B, g \rangle \text{d vol}_g.$$

By (3.3), using the Divergence Theorem, for any variation  $g_t$  with  $\text{supp}(\partial_t g) \subset \Omega$ , and  $t$ -dependent  $X \in \mathfrak{X}_M$  with  $\text{supp}(\partial_t X) \subset \Omega$  we have

$$(3.4) \quad \frac{d}{dt} \int_M (\text{div } X) \text{d vol}_g = \int_M \text{div} \left( \partial_t X + \frac{1}{2} (\text{Tr}_g B) X \right) \text{d vol}_g = 0.$$

From Lemmas 3.1 and 3.2 and the equality, see (2.4),

$$Q(\mathcal{D}_i, g) = \langle H_i^\perp, H_i^\perp \rangle + \langle H_i, H_i \rangle - \langle h_i, h_i \rangle - \langle h_i^\perp, h_i^\perp \rangle + \langle T_i, T_i \rangle + \langle T_i^\perp, T_i^\perp \rangle,$$

we obtain the following.

**Proposition 3.3.** *For a  $\mathcal{D}_j$ -variation of metric  $g \in \text{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$  we have*

$$(3.5) \quad \partial_t \sum_i Q(\mathcal{D}_i, g) = \langle \mathcal{Q}_j, B_j \rangle - \text{div } X_j,$$

where  $B_j = \partial_t g_t|_{t=0}$ , and  $(0,2)$ -tensors  $\mathcal{Q}_j$  on  $\mathcal{D}_j \times \mathcal{D}_j$  and vector fields  $X_j$  are given by

$$\begin{aligned}
2X_j &= \langle h_j, B_j \rangle - (\text{Tr } B_j^\sharp) H_j + \sum_{i \neq j} (\langle h_i^\perp, B_j \rangle - (\text{Tr } B_j^\sharp) H_i^\perp), \\
\mathcal{Q}_j &= -\text{div } h_j - \mathcal{K}_j^\flat + \frac{1}{2} \Upsilon_{h_j^\perp, h_j^\perp} + \frac{1}{2} \Upsilon_{T_j^\perp, T_j^\perp} + 2\mathcal{T}_j^\flat - (H_j^\perp)^\flat \otimes (H_j^\perp)^\flat + (\text{div } H_j) g_j \\
&+ \sum_{i \neq j} \left( -\text{div } h_i^\perp|_{\mathcal{D}_j} - (P_j \mathcal{K}_i^\perp)^\flat + \frac{1}{2} \Upsilon_{P_j h_i, P_j h_i} + \frac{1}{2} \Upsilon_{P_j T_i, P_j T_i} + 2(P_j \mathcal{T}_i^\perp)^\flat \right. \\
&\quad \left. - (P_j H_i)^\flat \otimes (P_j H_i)^\flat + (\text{div } H_i^\perp) g_j \right).
\end{aligned}$$

The summation part related to  $\mathcal{D}_j^\perp$  (in  $X_j$  and  $\mathcal{Q}_j$ ) is dual to the part related to  $\mathcal{D}_j$ .

The next theorem allows us to restore the partial Ricci curvature, see (1.4). It is based on calculating the variations with respect to  $g$  of components in (2.3) and using (3.4) for divergence terms. By this theorem and Definition 3.5 in what follows we conclude that an adapted metric  $g$  is critical for the action (1.2) with respect to adapted variations of metric preserving the volume of  $\Omega$ , i.e.,  $\text{Vol}(\Omega, g_t) = \text{Vol}(\Omega, g)$  for all  $t$ , if and only if (1.4) holds.

**Theorem 3.4** (see [15]). *An adapted metric  $g \in \text{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$  is critical for the geometrical part of (1.2) (i.e.,  $\Lambda = 0 = \mathcal{L}$ ) with respect to adapted variations preserving the volume of  $\Omega$  if and only if the following Euler-Lagrange equations hold:*

$$(3.6) \quad \begin{aligned} & \text{div } h_j + \mathcal{K}_j^\flat - \frac{1}{2} \Upsilon_{h_j^\perp, h_j^\perp} - \frac{1}{2} \Upsilon_{T_j^\perp, T_j^\perp} - 2 \mathcal{T}_j^\flat + (H_j^\perp)^\flat \otimes (H_j^\perp)^\flat \\ & + \sum_{i \neq j} (\text{div } h_i^\perp|_{\mathcal{D}_j} + (P_j \mathcal{K}_i^\perp)^\flat - \frac{1}{2} \Upsilon_{P_j h_i, P_j h_i} - \frac{1}{2} \Upsilon_{P_j T_i, P_j T_i} - 2 (P_j \mathcal{T}_i^\perp)^\flat \\ & + (P_j H_i)^\flat \otimes (P_j H_i)^\flat) = (S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - \text{div}(H_j + \sum_{i \neq j} H_i^\perp) + \lambda) g_j \end{aligned}$$

for some  $\lambda \in \mathbb{R}$  and  $1 \leq j \leq k$ , or, in a short form,

$$(3.7) \quad \mathcal{Q}_j = -(S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - \frac{1}{2} \text{div} \sum_i (H_i + H_i^\perp) + \lambda) g_j, \quad 1 \leq j \leq k.$$

*Proof.* Let  $g_t$  be a  $\mathcal{D}_j$ -variation of  $g$  compactly supported in  $\Omega \subset M$ . Using Divergence theorem to (3.5) and removing integrals of divergences of vector fields supported in  $\Omega \subset M$ , we get

$$(3.8) \quad \int_\Omega \sum_i \partial_t Q(\mathcal{D}_i, g_t)|_{t=0} \text{d vol}_g = \int_\Omega \langle \mathcal{Q}_j, B_j \rangle \text{d vol}_g.$$

By (3.4) with  $X = \sum_i (H_i + H_i^\perp)$  we get

$$\frac{d}{dt} \int_\Omega \text{div} \sum_i (H_i + H_i^\perp) \text{d vol}_g = 0.$$

Thus, for the action (1.3), using (2.7), (3.3), (3.5) and (3.8), we get

$$(3.9) \quad \begin{aligned} 2 \frac{d}{dt} J_{\mathcal{D}}^g(g_t)|_{t=0} &= \frac{d}{dt} \int_\Omega \sum_i Q(\mathcal{D}_i, g_t) \text{d vol}_{g_t}|_{t=0} \\ &= \int_\Omega \sum_i \partial_t Q(\mathcal{D}_i, g_t)|_{t=0} \text{d vol}_g + \int_\Omega \sum_i Q(\mathcal{D}_i, g) \partial_t (\text{d vol}_{g_t})|_{t=0} \\ &= \int_\Omega \langle \mathcal{Q}_j + \frac{1}{2} \sum_i Q(\mathcal{D}_i, g) g, B_j \rangle \text{d vol}_g. \end{aligned}$$

If  $g$  is critical for the action  $J_{\mathcal{D}}^g$  with respect to  $\mathcal{D}_j$ -variations of  $g$ , then the integral in (3.9) is zero for any symmetric  $(0, 2)$ -tensor  $B_j$ . This yields the  $\mathcal{D}_j$ -component of Euler-Lagrange equation

$$(3.10) \quad \mathcal{Q}_j + \frac{1}{2} \sum_i Q(\mathcal{D}_i, g) g_j = 0, \quad 1 \leq j \leq k.$$



For adapted variations preserving the volume of  $\Omega$ , using (3.3), we have

$$0 = \partial_t \int_M d \operatorname{vol}_g = \int_M \partial_t d \operatorname{vol}_g = \int_M \frac{1}{2} (\operatorname{Tr} B) d \operatorname{vol}_g = \frac{1}{2} \int_\Omega \langle g, B \rangle d \operatorname{vol}_g.$$

Thus, the Euler-Lagrange equation of (1.3) with respect to  $\mathcal{D}_j$ -variations preserving the volume of  $\Omega$  are

$$\mathcal{Q}_j + \left(\frac{1}{2} \sum_i Q(\mathcal{D}_i, g) + \lambda\right) g_j = 0$$

instead of (3.10). Replacing here  $\sum_i Q(\mathcal{D}_i, g)$  according to (2.7), we get (3.6).  $\square$

**Remark 3.2.** Using the partial Ricci tensor (2.2) and replacing  $\operatorname{div} h_j$  and  $\operatorname{div} h_i^\perp$  for  $i \neq j$  in (3.6) according to (2.6), we can rewrite (3.6) as

$$\begin{aligned} & r_{\mathcal{D}_j} - \langle h_j, H_j \rangle + \mathcal{A}_j^\flat - \mathcal{T}_j^\flat + \Psi_j^\perp - \operatorname{Def}_{\mathcal{D}_j^\perp} H_j^\perp + \mathcal{K}_j^\flat + (H_j^\perp)^\flat \otimes (H_j^\perp)^\flat \\ & - \frac{1}{2} \Upsilon_{h_j^\perp, h_j^\perp} - \frac{1}{2} \Upsilon_{T_j^\perp, T_j^\perp} + \sum_{i \neq j} (r_{\mathcal{D}_i^\perp | \mathcal{D}_j} - \langle h_i^\perp | \mathcal{D}_j, H_i^\perp \rangle + (P_j \mathcal{A}_i^\perp)^\flat - (P_j \mathcal{T}_i^\perp)^\flat) \\ & + \Psi_i |_{\mathcal{D}_j} - \operatorname{Def}_{\mathcal{D}_j} H_i + (P_j \mathcal{K}_i^\perp)^\flat + (P_j H_i)^\flat \otimes (P_j H_i)^\flat - \frac{1}{2} \Upsilon_{P_j h_i, P_j h_i} - \frac{1}{2} \Upsilon_{P_j T_i, P_j T_i} \\ (3.11) \quad & = (S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - \operatorname{div}(H_j + \sum_{i \neq j} H_i^\perp) + \lambda) g_j, \quad j = 1, \dots, k. \end{aligned}$$

**Example 3.3.** A pair  $(\mathcal{D}_i, \mathcal{D}_j)$  with  $i \neq j$  of distributions on a Riemannian almost multi-product manifold  $(M, g; \mathcal{D}_1, \dots, \mathcal{D}_k)$  is called *mixed integrable*, see [13], if

$$T_{i,j}(X, Y) = 0 \quad (X \in \mathcal{D}_i, Y \in \mathcal{D}_j).$$

Let  $(M, g; \mathcal{D}_1, \dots, \mathcal{D}_k)$  with  $k > 2$  has integrable distributions  $\mathcal{D}_1, \dots, \mathcal{D}_k$  and each pair  $(\mathcal{D}_i, \mathcal{D}_j)$  is mixed integrable. Then  $T_l^\perp(X, Y) = 0$  for all  $l \leq k$  and  $X \in \mathcal{D}_i, Y \in \mathcal{D}_j$  with  $i \neq j$ , see [13, Lemma 2]. In this case, (3.11) reads as

$$\begin{aligned} & r_{\mathcal{D}_j} - \langle h_j, H_j \rangle + \mathcal{A}_j^\flat + \Psi_j^\perp - \operatorname{Def}_{\mathcal{D}_j^\perp} H_j^\perp - \frac{1}{2} \Upsilon_{h_j^\perp, h_j^\perp} + (H_j^\perp)^\flat \otimes (H_j^\perp)^\flat \\ & + \sum_{i \neq j} (r_{\mathcal{D}_i^\perp | \mathcal{D}_j} - \langle h_i^\perp | \mathcal{D}_j, H_i^\perp \rangle + (P_j \mathcal{A}_i^\perp)^\flat + \Psi_i |_{\mathcal{D}_j} - \operatorname{Def}_{\mathcal{D}_j} H_i - \frac{1}{2} \Upsilon_{P_j h_i, P_j h_i} \\ & + (P_j H_i)^\flat \otimes (P_j H_i)^\flat) = (S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - \operatorname{div}(H_j + \sum_{i \neq j} H_i^\perp) + \lambda) g_j, \quad j = 1, \dots, k. \end{aligned}$$

**Definition 3.4.** The Ricci type symmetric  $(0, 2)$ -tensor  $\operatorname{Ric}_{\mathcal{D}}$  in (1.4) is defined by its restrictions  $\operatorname{Ric}_{\mathcal{D} | \mathcal{D}_j \times \mathcal{D}_j}$  on  $k$  subbundles  $\mathcal{D}_j$  of  $TM$ ,

$$(3.12) \quad \operatorname{Ric}_{\mathcal{D} | \mathcal{D}_j \times \mathcal{D}_j} = -\mathcal{Q}_j + \mu_j g_j, \quad j = 1, \dots, k$$

(in a short form, using  $\mathcal{Q}_j$  in the LHS of (3.7)), where  $(\mu_j)$  are uniquely determined (see (3.15) and Theorem 3.5 below) so that critical metrics satisfy Einstein type equation (1.4). Using (2.6), this can be written in more detail as

$$\begin{aligned} & \operatorname{Ric}_{\mathcal{D} | \mathcal{D}_j \times \mathcal{D}_j} = r_{\mathcal{D}_j} - \langle h_j, H_j \rangle + \mathcal{A}_j^\flat + \mathcal{T}_j^\flat + \Psi_j^\perp - \operatorname{Def}_{\mathcal{D}_j^\perp} H_j^\perp + \mathcal{K}_j^\flat + (H_j^\perp)^\flat \otimes (H_j^\perp)^\flat \\ & - \frac{1}{2} \Upsilon_{h_j^\perp, h_j^\perp} - 2\mathcal{T}_j^\flat - \frac{1}{2} \Upsilon_{T_j^\perp, T_j^\perp} + \sum_{i \neq j} (r_{\mathcal{D}_i^\perp | \mathcal{D}_j} - \langle h_i^\perp | \mathcal{D}_j, H_i^\perp \rangle + (P_j \mathcal{A}_i^\perp)^\flat \\ & + (P_j \mathcal{T}_i^\perp)^\flat + \Psi_i |_{\mathcal{D}_j} - \operatorname{Def}_{\mathcal{D}_j} H_i + (P_j \mathcal{K}_i^\perp)^\flat + (P_j H_i)^\flat \otimes (P_j H_i)^\flat \\ (3.13) \quad & - \frac{1}{2} \Upsilon_{P_j h_i, P_j h_i} - \frac{1}{2} \Upsilon_{P_j T_i, P_j T_i} - 2(P_j \mathcal{T}_i^\perp)^\flat) + \mu_j g_j. \end{aligned}$$

**Theorem 3.5.** *A metric  $g \in \text{Riem}(M; \mathcal{D}_1, \dots, \mathcal{D}_k)$  is critical for the geometrical part of (1.2), i.e.,  $\Lambda = 0 = \mathcal{L}$ , with respect to adapted variations if and only if  $g$  satisfies Einstein type equation (1.4), where the tensor  $\mathcal{R}ic_{\mathcal{D}}$  is defined in (3.12).*

*Proof.* The Euler-Lagrange equations (3.6) consist of  $\mathcal{D}_j \times \mathcal{D}_j$ -components. Thus, for (1.3) we obtain (3.13). If  $n = 2$  (and  $k = 2$ ), then we take  $\mu_1 = \mu_2 = 0$ , see [11]. Assume that  $n > 2$ . Substituting (3.13) with arbitrary  $(\mu_j)$  into (1.4) along  $\mathcal{D}_j$ , we conclude that if the Euler Lagrange equations

$$\mathcal{Q}_j = -b_j g_j \quad (1 \leq j \leq k)$$

hold, where  $b_j g_j$  is the RHS of (3.6), then  $\mathcal{R}ic_{\mathcal{D}} - (1/2)\mathcal{S}_{\mathcal{D}} \cdot g = 0$ , see (1.4) with  $\Lambda = 0 = \Xi$ , if and only if  $(\mu_j)$  satisfy the linear system

$$(3.14) \quad \sum_i n_i \mu_i - 2\mu_j = a_j, \quad j = 1, \dots, k,$$

with coefficients  $a_j = \text{Tr}_g(\sum_i \mathcal{Q}_i) - 2\mathcal{Q}_j$ . The matrix of (3.14) is invertible. Its determinant  $2^{k-1}(2-n)$  is negative when  $n > 2$ . Hence, the system (3.14) has a unique solution  $(\mu_1, \dots, \mu_k)$  given by

$$(3.15) \quad \mu_i = -\frac{1}{2n-4} \left( \sum_j (a_i - a_j) n_j - 2a_i \right),$$

and  $\mathcal{R}ic_{\mathcal{D}|_{\mathcal{D}_j \times \mathcal{D}_j}}$  satisfies (3.13).  $\square$

**Example 3.5** (see [11]). The symmetric Ricci type tensor  $\mathcal{R}ic_{\mathcal{D}}$  in (1.4) with  $k = 2$ , is defined by its restrictions on two complementary subbundles  $\mathcal{D}$  and  $\mathcal{D}^\perp$  of  $TM$ ,

$$(3.16) \quad \begin{aligned} \mathcal{R}ic_{\mathcal{D}|_{\mathcal{D}^\perp \times \mathcal{D}^\perp}} &= r - \langle h^\perp, H^\perp \rangle + (\mathcal{A}^\perp)^\flat - (\mathcal{T}^\perp)^\flat + \Psi - \text{Def}_{\mathcal{D}} H + (\mathcal{K}^\perp)^\flat \\ &+ H^\flat \otimes H^\flat - \frac{1}{2} \Upsilon_{h,h} - \frac{1}{2} \Upsilon_{T,T} + \mu_1 g^\perp, \\ \mathcal{R}ic_{\mathcal{D}|_{\mathcal{D} \times \mathcal{D}}} &= r^\perp - \langle h, H \rangle + \mathcal{A}^\flat - \mathcal{T}^\flat + \Psi^\perp - \text{Def}_{\mathcal{D}^\perp} H^\perp + \mathcal{K}^\flat \\ &+ (H^\perp)^\flat \otimes (H^\perp)^\flat - \frac{1}{2} \Upsilon_{h^\perp, h^\perp} - \frac{1}{2} \Upsilon_{T^\perp, T^\perp} + \mu_2 g^\top, \end{aligned}$$

where  $\mu_1 = -\frac{n_1-1}{n-2} \text{div}(H^\perp - H)$  and  $\mu_2 = \frac{n_2-1}{n-2} \text{div}(H^\perp - H)$ . Here (3.16)<sub>2</sub> is dual to (3.16)<sub>1</sub> with respect to interchanging distributions  $\mathcal{D}$  and  $\mathcal{D}^\perp$ , and their last terms vanish if  $n_1 = n_2 = 1$ . Also, we have

$$\mathcal{S}_{\mathcal{D}} := \text{Tr}_g \mathcal{R}ic_{\mathcal{D}} = \mathcal{S}_{\mathcal{D}, \mathcal{D}^\perp} + \frac{n_2 - n_1}{n - 2} \text{div}(H^\perp - H).$$

**Example 3.6.** Totally umbilical and totally geodesic integrable distributions appear on multiply twisted products. A *multiply twisted product*  $F_1 \times_{u_2} F_2 \times \dots \times_{u_k} F_k$  of Riemannian manifolds  $(F_i, g_{F_i})$ ,  $1 \leq i \leq k$ , is the product  $M = \prod_i F_i$  with the metric  $g = g_{F_1} \oplus u_2^2 g_{F_2} \oplus \dots \oplus u_k^2 g_{F_k}$ , where  $u_i : F_1 \times F_i \rightarrow (0, \infty)$  for  $i \geq 2$  are smooth functions, see [19]. Twisted products (i.e.,  $k = 2$ ) and multiply warped products (i.e.,  $u_i : F_1 \rightarrow (0, \infty)$ , see [6]) are special cases of multiply twisted products. Let  $\mathcal{D}_i$  be the distribution on  $M$  obtained from vectors tangent to horizontal lifts of  $F_i$ . The leaves tangent to  $\mathcal{D}_i$  ( $i \geq 2$ ), are totally umbilical, with the mean curvature vector fields

$$H_i = -n_i P_1 \nabla(\log u_i),$$

and the fibers (tangent to  $\mathcal{D}_1$ ) are totally geodesic ( $h_1 = 0$ ). For  $k > 2$  each pair of distributions is mixed totally geodesic (since  $M$  is the product and the Lie bracket does not depend on metric). Using

$$\operatorname{div} H_i = -n_i (\Delta_1 u_i)/u_i - (n_i^2 - n_i) \|P_1 \nabla u_i\|^2 / u_i^2,$$

where  $\Delta_1$  is the Laplacian on  $(F_1, g_{F_1})$ , we find

$$(3.17) \quad S_{\mathcal{D}_1, \dots, \mathcal{D}_k} = \sum_{i \geq 2} n_i (\Delta_1 u_i)/u_i.$$

Let a multiply twisted product  $F_1 \times_{u_2} F_2 \times \dots \times_{u_k} F_k$  with  $k > 2$ , see Example 3.6, be critical for (1.3) with respect to adapted variations of  $g$ . Then the system (3.6) takes the form

$$(3.18) \quad \begin{aligned} & \operatorname{div} h_j - \frac{1}{2} \Upsilon_{h_j^\perp, h_j^\perp} + (H_j^\perp)^\flat \otimes (H_j^\perp)^\flat + \sum_{i \neq j} (\operatorname{div} h_i^\perp|_{\mathcal{D}_j} - \frac{1}{2} \Upsilon_{h_i, h_i} + H_i^\flat \otimes H_i^\flat) \\ & = (S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - \operatorname{div}(H_j + \sum_{i \neq j} H_i^\perp) + \lambda) g_j. \end{aligned}$$

(a) Let  $\dim F_1 = n_1 > 2$  and  $\dim F_i = n_i > 1$  for  $i \neq 1$ . In addition, assume that

$$\langle H_i, H_j \rangle = 0, \quad i \neq j.$$

From (3.18) with  $j = 1$ , using  $H_1^\perp = \sum_{i \neq 1} H_i$  and equalities

$$\begin{aligned} \frac{1}{2} \Upsilon_{h_1^\perp, h_1^\perp} &= \sum_{i \neq 1} \frac{1}{n_i} H_i^\flat \otimes H_i^\flat = \frac{1}{2} \sum_{i \neq 1} \Upsilon_{h_i, h_i}, \\ \sum_{i \neq 1} \operatorname{div} h_i^\perp|_{\mathcal{D}_1} &= (k-2) \sum_{i \neq 1} \frac{1}{n_i} \operatorname{div} H_i, \\ \operatorname{div}(\sum_{i \neq 1} H_i^\perp) &= (k-2) \sum_{i \neq 1} \operatorname{div} H_i, \\ (H_1^\perp)^\flat \otimes (H_1^\perp)^\flat &= \sum_{i \neq 1} H_i^\flat \otimes H_i^\flat, \end{aligned}$$

we obtain

$$(3.19) \quad 2 \sum_{i \neq 1} \left(1 - \frac{1}{n_i}\right) H_i^\flat \otimes H_i^\flat = (S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - (k-2) \sum_{i \neq 1} \left(1 + \frac{1}{n_i}\right) \operatorname{div} H_i + \lambda) g_1.$$

Comparing ranks (2 and  $n_1 > 2$ ) of matrices  $H_i^\flat \otimes H_i^\flat$  and  $g_1$  in (3.19), we get  $H_i = 0$  ( $i > 1$ ). Hence, each distribution  $\mathcal{D}_i$  is totally geodesic, and our multiply twisted product is the product of  $(F_1, g_{F_1})$  and  $(F_i, u_i^2 g_{F_i})$  for  $i > 1$ .

(b) Let  $\dim F_i = 1$  for  $i \neq 1$ . Then the system (3.6) takes the form

$$(3.20) \quad S_{\mathcal{D}_1, \dots, \mathcal{D}_k} - \operatorname{div}(2H_j + \sum_{i \neq j} H_i^\perp) + \lambda = 0, \quad 1 \leq j \leq k.$$

Using (3.17) and equality  $\operatorname{div} H_i = -(\Delta_1 u_i)/u_i$ , we get the linear system

$$(3.21) \quad (k-2)y_j + (k-1) \sum_{i \neq j} y_i + \lambda = 0, \quad 1 \leq j \leq k,$$

where  $y_i = (\Delta_1 u_i)/u_i$ . The unique solution of (3.21) is  $y_i = \tilde{\lambda}$ , where  $\tilde{\lambda} = \lambda / (\frac{1}{k-1} - k)$ . Thus,  $\tilde{\lambda}$  is the eigenvalue of the laplacian  $\Delta_1$  on  $(F_1, g_{F_1})$ , and  $u_i$  are the eigenfunctions:  $\Delta_1 u_i = \tilde{\lambda} u_i$ . The mixed scalar curvature in this case is constant:

$$S_{\mathcal{D}_1, \dots, \mathcal{D}_k} = \sum_{i \neq 1} (\Delta_1 u_i)/u_i = (k-1)\tilde{\lambda}.$$

Similarly, we can find critical multiply twisted products for the action (1.2).

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