# ON SOME EXIT CRITERIA FOR THE NEWTON METHOD

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#### Abstract

Newton's iterative method for a scalar equation f(x) = 0, is known to be convergent to the unique zero  $\alpha$  of f, for f satisfying certain conditions involving f, f' and f''.

In thi case, if  $(x_n)$  is the sequence defined by Newton's method, a stopping inequality or an aposteriori estimation of the form  $|x_{n+1} - \alpha| \leq |x_n - x_{n+1}|$ , holds.

The aim of this paper is to show that Newton's method converges under weaker conditions, involving only f and f', when a generalized stopping inequality is valid.

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## 1. Introduction

In this paper we consider the equation

$$(1) f(x) = 0$$

on an interval  $[a, b] \subseteq R$ , for a real-valued function f.

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The (one-dimensional) Newton method is given by the iteration

(2) 
$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \quad x_0 \in [a, b], \quad n \ge 0$$

assuming  $f' \neq 0$  on [a, b].

The importance of the Newton iteration (2) rests on the fact that, under certain natural conditions on f, an estimate of the form

$$|x_{n+1} - \alpha| \le C|x_n - \alpha|^2,$$

holds.

Together with the simplicity and elegance of (2), the so-called "quadratic convergence" (3) makes Newton's method a focal point in the study of iterative methods for nonlinear equations.

However, the conditions as "f'' does not change its sign on [a, b]", in [4] or "f'' > 0 on [a, b]" in [5], are too strong. Even the Ostrowski theorem on the Newton method [7], assumes "f" there exist in the neighborhood of  $\alpha$ ". But, as shown by some practical examples, (see [2], [3]), the existence of the second derivative of f is not necessary for the convergence of the Newton method.

Theorem 1 in this paper gives conditions, stated in terms of f and f', for the convergence of the Newton method, which however provides a "linear convergence" instead of the classical quadratic convergence.

# 2. An extension of the Newton method

Let  $f:[a,b]\to R$  be a real function which satisfies the following conditions

$$(f_1) \ f(a) \cdot f(b) < 0;$$

(f<sub>2</sub>) 
$$f \in C^1[a,b], f'(x) \neq 0, x \in [a,b];$$

Then, from  $(f_1)$  we deduce that  $f \in C[a, b]$  has a root  $\alpha \in (a, b)$ , and  $(f_2)$  implies that  $f \in C[a, b]$  has only a root in [a, b].

If, in addition,  $f \in C^2[a,b]$  and  $f''(x) \neq 0$  on [a,b], the Newton iteration (2) converges to  $\alpha$ , for  $x_0 \in [a,b]$  arbitrary taken and (3) holds with  $C = M_2/2m_1$ , where  $m_1 = \min_{x \in [a,b]} |f'(x)|$  and  $M_2 = \max_{x \in [a,b]} |f''(x)|$ , see [4].

If a stopping inequality is valid, i.e. an estimation of the form  $|x_{n+1} - \alpha| \le |x_n - x_{n+1}|$ , as shown in [4] or [5], then the numerical computation of the sequence  $(x_n)$  given by (2) is stopped when the distance between two successive approximations is less than a preassigned tolerance. Such an exit criterion is correct, because, from

$$|x_n - x_{n+1}| < \varepsilon,$$

and the stopping inequality we obtain

$$|x_n - \alpha| < \varepsilon$$
.

In this paper we consider a stopping inequality of the form

$$(4) |x_n - \alpha| \le c|x_n - x_{n+1}|,$$

where  $c \geq 1$  is constant. Obviously, for c = 1, we obtain the stopping inequality from [5] and [4].

The main result of this paper is given by

**Theorem 1.** Let  $f:[a,b] \rightarrow R$ , a < b, be a function which satisfies  $(f_1)$ ,  $(f_2)$  and

 $(f_3)$ : 2m > M, where

$$m = \min_{x \in [a,b]} |f'(x)|, \quad M = \max_{x \in [a,b]} |f'(x)|.$$

Then the Newton iteration (2) converges to  $\alpha$ , the unique solution of (1) and the following estimation

$$|x_n - \alpha| \leq \frac{M}{m} |x_n - x_{n+1}|, \quad n \geq 0,$$

holds.

**Proof.** From  $(f_1)$  and  $(f_2)$  it results that (1) has a unique solution  $\alpha \in (a,b)$ . Let  $x_0 \in [a,b]$ , be the initial approximation. From (2) we obtain

$$x_{n+1} - \alpha = x_n - \alpha - \frac{f(x_n) - f(\alpha)}{f'(x_n)}$$
, for all  $n = 0, 1, ...$ 

and, using the mean value theorem, this yields

(6) 
$$x_{n+1} - \alpha = \left[1 - \frac{f'(c_n)}{f'(x_n)}\right] \cdot (x_n - \alpha), \quad n \in \mathbb{N},$$

where  $c_n = \alpha + \theta(x_n - \alpha)$ ,  $0 < \theta < 1$ .

In a similar manner we deduce, directly from (2),

(7) 
$$x_{n+1} - x_n = \frac{f'(c_n)}{f'(x_n)}(x_n - \alpha), \quad \forall n \in \mathbb{N}.$$

Now, from (f<sub>2</sub>) it results

$$1 - \frac{f'(c_n)}{f'(x_n)} < 1, \quad n \in \mathbb{N}.$$

On the other hand,

$$\frac{f'(c_n)}{f'(x_n)} = \left| \frac{f'(c_n)}{f'(x_n)} \right| = \frac{|f'(c_n)|}{|f'(x_n)|} \le \frac{M}{m},$$

hence, in virtue of (f<sub>3</sub>),

$$1 - \frac{f'(c_n)}{f'(x_n)} > -1 \quad \text{for each} \ \ n \ge 0.$$

Since [a, b] is compact and  $f \in C^1[a, b]$ , we obtain

$$k = \max_{x,y \in [a,b]} \left| 1 - \frac{f'(y)}{f'(x)} \right| < 1,$$

which, together with (6), yields

$$|x_{n+1} - \alpha| \le k|x_n - \alpha|, \quad n \in N,$$

and 0 < k < 1.

By induction, we deduce

$$|x_n - \alpha| \le k^n |x_0 - \alpha|, \quad n \in N,$$

for each  $x_0 \in [a, b]$ .

However, [a, b] is generally not an invariant set with respect to the iteration (2), i.e. it is possible to obtain at a certain step  $p, x_p \notin [a, b]$ .

In order to remove difficulties we define f over the whole real axis (and denote it by f too) as follows

(8) 
$$f(x) = \begin{cases} f'(a)(x-a) + f(a), & \text{if } x < a \\ f(x), & \text{if } x \in [a,b] \\ f'(b)(x-b) + f(b), & \text{if } x > b. \end{cases}$$

If some iterate  $x_p$  does not lie in [a, b], we have either  $x_p < a$  or  $x_p > b$ . In the first case,

$$x_{p+1} = x_p - \frac{f(x_p)}{f'(x_p)} = x_p - \frac{f'(a)(x_p - a) + f(a)}{f'(a)},$$

hence

$$x_{p+1} = a - \frac{f(a)}{f'(a)},$$

which shows  $x_{p+1} > a$ , because, from  $(f_1)$ - $(f_2)$  it results f(a)f'(a) < 0.

In the second case,

$$x_{p+1} = x_p - \frac{f'(b)(x-b) + f(b)}{f'(b)} = b - \frac{f(b)}{f'(b)} < b,$$

because  $f(b) \cdot f'(b) > 0$ .

But  $(x_n)$  converges to  $\alpha$  and  $a < \alpha < b$ . This means that, begining from a step  $p_0 \ge 0$ , we necessarly have

$$x_n \in [a, b]$$
.

The desired estimation (5) may be obtained from (7). The proof is now complete.  $\Box$ 

#### Remarks.

1) The Newton iteration method given by (2) and (8) is called "the extended Newton method", see [2]. In fact, this algorithm consists in applying the Newton method on [a, b] and the modified Newton method (see [4]) on  $R \setminus [a, b]$ .

2) If the conditions of Theorem 1 are satisfied, in order to obtain  $|x_n - \alpha| < \varepsilon$  the iterative procedure must be stopped when  $|x_{n+1} - x_n| < \frac{m}{M} \varepsilon$ .

- 3) Relation (6) shows a linear rate of convergence for the extended Newton method. However, if f'' exists on  $[a, b] \setminus \{\alpha\}$ , the convergence is quadratic [4].
- 4) A fixed point proof of Theorem 1 is given in [3], and the corresponding *n*-dimensional case is treated in [1].
- 5) A classical fixed point argument, based on Edelstein's fixed point theorem shows that condition (f<sub>3</sub>) in Theorem 1 may be weakened. We also obtain

**Theorem 2.** If f satisfies  $(f_1)$ ,  $(f_2)$  and the following condition

$$(f'_3)$$
  $2m \geq M$ ,

then the conclusion of Theorem 1 remains true.

**Remarks.** The condition  $(f'_3)$  is similar to condition  $(F_4)$  in [5], but there  $f \in C^2[a, b]$ , and the studied method is a general one given by

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}g(x_n),$$

where g is a certain function.

The proof of Theorem 1 may be easily extended to this procedure, assuming  $x_n \in [a, b]$ , for each  $n \in N$ , see [1].

#### 3. Examles

The best result until now about the convergence of Newton's method in the scalar case seems to be the well-known Ostrowski's theorem (see [7], Theorem 7.2) which assumes that f'' exists in a neighborhood of  $\alpha$ . Our Theorem 2 is better than Ostrowski's theorem, as shown by Example 2.

For the convergence of the extended Newton method, the numerical tests was performed on an IBM PC, under MATHCAD.

**Example 1.** For  $f(x) = \operatorname{tg} x$ ,  $x \in [a, b] \subset (\frac{\pi}{2}, \frac{3\pi}{2})$ , we have f'(x) > 0, but

 $f''(\pi) = 0$  and  $\alpha = \pi$  is the unique solution of the equation f(x) = 0 in [a, b]. The Demidovich's theorem does not apply. The convergence of the Newton method is a consequence of Theorem 1 or 2 in this paper, or Ostrowski's theorem.

For  $a=\frac{7\pi}{12}, b=\frac{17\pi}{12}$  and  $x_0=a$ , the constant c in the stopping inequality is  $c=\frac{M}{m}=14.76$ . After 7 iterations we obtain  $\pi$  with exact digits:  $x_0=1.83; \ x_1=2.08; \ x_2=2.51; \ x_3=2.99; \ x_4=3.139; \ x_5=3.141592644; \ x_6=3.141592653589794$  and  $x_7=3.141592653589793$ .

Taking  $x_0 = \frac{2\pi}{3}$  we obtain the solution after 5 iterations:  $x_0 = 2.09$ ;  $x_1 = 2.527$ ;  $x_2 = 2.998$ ;  $x_3 = 3.139$ ;  $x_4 = 3.141592648$ ; and  $x_5 = 3.141592653589793$ .

**Example 2.** [3] Let  $f: [-1,1] \to R$  be given by  $f(x) = -x^2 + 2x$ , if  $x \in [-1,0)$  and  $f(x) = x^2 + 2x$ , if  $x \in [0,1]$ . The equation f(x) = 0 has only the solution  $\alpha = 0$  on [-1,1]. Since f'' does not exist in 0, neither Theorem 1 nor Ostrowski's theorem does apply. We have m = 2, M = 4, the condition  $(f'_3)$  in Theorem 2 is satisfied, hence the Newton method is convergent.

Indeed, if we start with  $x_0 = 0.5$ , we obtain  $x_1 = 0.833333$ ;  $x_2 = 0.0032051$ ;  $x_3 = 0.0000129$ ;  $x_4 = 0.0000001$  and  $x_5 = 0$ .

**Remarks.** The basic idea in proving the convergence of the Newton method in the classical form, i.e.  $f \in C^2[a,b]$  and  $f'' \neq 0$  on [a,b], is to show that the sequence  $(x_n)$  is monotonous. As shown by the following example, in the conditions of Theorem 1 or  $2, (x_n)$  is not generally monotonous.

**Example 3.** For  $f: [1.1, 4] \to R$ ,  $f(x) = xe^{-x} - 2e^{-2}$ , we have f' < 0, f''(2) = 0 and  $\alpha = 2$  is the unique zero of f.

Starting from  $x_0 = 1.2$ , we obtain  $x_1 = 2.7067103$ ;  $x_2 = 1.9169384$ ;  $x_3 = 2.0002041$ ;  $x_4 = 2.00...$  and  $x_5 = 2$ , hence  $(x_n)$  is not monotonous.

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