

Recursive modules for programming

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Abstract

The ML module system is useful for building large-scale programs. The programmer can factor programs into nested and parameterized modules, and can control abstraction with signatures. Yet ML prohibits recursion between modules. As a result of this constraint, the programmer may have to consolidate conceptually separate components into a single module, intruding on modular programming. Introducing recursive modules is a natural way out of this predicament. Existing proposals, however, vary in expressiveness and verbosity. In this paper, we propose a type system for recursive modules, which can infer their signatures. Opaque signatures can also be given explicitly, to provide type abstraction either inside or outside the recursion. The type system is provably decidable, and is sound for a call-by-value semantics. We also give a solution to the expression problem, in support of our design choices.

1 Introduction

When building a large software system, it is useful to decompose the system into smaller parts and to reuse them in different contexts. Module systems play an important role in facilitating such factoring of programs. Many modern programming languages provide some forms of module systems.

The family of ML programming languages, which includes SML[19] and Objective Caml [16], provides a powerful module system [17, 15]. Nested structures of modules allow hierarchical decomposition of programs. Functors can be used to express advanced forms of parameterization, which ease code reuse. Abstraction can be controlled by signatures with transparent, opaque or translucent types [10, 13].

In spite of this flexibility, the ML module language prohibits recursion between modules. This is a major disadvantage of ML, when compared to object-oriented languages, like Java. These languages have supported recursive definitions across class boundaries from the beginning, and this feature is heavily used in practice.

We, ML programmers, enjoy strong type safety. Yet, due to the lack of recursive modules, we may have to consolidate conceptually separate components into a single module, intruding on modular programming [24]. If we had both recursive modules and this flexible module language, we could enjoy a strongly type safe programming language with an equally strong expressive power.

Recently, much work has been devoted to investigating extensions with recursion of the ML module system. Two important issues involved are type checking and initialization. Crary, Harper and Puri [3], Russo [24], and Dreyer [5] have given type theoretic accounts for recursive modules. Boudol [1], Hirschowitz and Leroy [12], and Dreyer [4] have investigated type systems which guarantee well-formedness of recursive modules, ensuring that initialization of recursive modules will not attempt to access not-yet-evaluated values.

It seems that ML programmers are very close to use recursive modules in everyday programming. Indeed, some real ML family languages support recursive modules [16, 23], in which we can use them for practical programs, or, at least, get a flavor of them.

In this paper, we first review two examples. In the first one, two recursive modules **Tree** and **Forest** respect each other's privacy: we seal them with opaque signatures individually. Thus type abstraction is enforced inside the recursion. In the second, **Tree** and **Forest** are intimate: they know each other's exact implementations, and we seal them with an opaque signature as a whole. Thus type abstraction is enforced outside the recursion.

Both privacy and intimacy will be important for practical uses of recursive modules. Existing proposals, however, vary in their way to handle them. We may be

denied privacy. We may have to write two different signatures for the same module; one of the signatures is solely for assisting the type checker and does not affect the resulting signature of the module.

Our goal is to develop a type system for recursive modules, which is practical and useful from the programmer’s perspective; we want to use them easily in everyday programming, possibly combining with other constructs of the core and the module languages.

With this goal in mind, we propose a type system for recursive modules, in which modules can have privacy or intimacy depending on the situation they are in. The type system does not require additional signature annotations. Thus the programmer can either omit writing signatures or give signatures explicitly to control abstraction. Moreover, he can rely on type inference during development; all previous proposals by others do not support type inference for recursive modules.

In the paper, we also present an advanced example of recursive modules, by giving a concise and type safe solution to the expression problem [27]. In the example, we use recursive modules, applicative functors [14] and private row types [9] together. The example confirms that by combining recursive modules with other language constructions we can indeed enjoy a highly expressive power in a type safe and modular way.

Our contributions are summarized as follows.

- We examine two typical uses of recursive modules by giving concrete examples. These examples are useful for understanding basic uses of recursive modules.
- We propose a new type system for recursive modules with first-order applicative functors. The type system supports type inference for recursive modules, and is decidable and sound for a call-by-value semantics.

All examples we present in this paper are type checked in this type system, without requiring additional signature annotations.

- We give a type safe and concise solution to the expression problem, in order to demonstrate that recursive modules give us the highly expressive power in a modular way when combined with other language constructions.

The rest of the paper is organized as follows. In the next section, we review two examples of recursive modules and present the main features of our calculus, *Traviata*, used for our formal development. Section 3 gives the concrete syntax of *Traviata*. Section 4 and 5 explain the type system and present a soundness result. In Section 6,

we give a solution to the expression problem. In Section 7, we examine the double vision problem [6]. Section 10 examines related work and Section 11 concludes.

```

module TreeForest = struct (TF)
  module Tree = (struct
    datatype t = Leaf of int | Node of int * TF.Forest.t
    val max = λx.case x of Leaf i ⇒ i
      | Node (i, f) ⇒ let j = TF.Forest.max f in if i > j then i else j
    end : sig type t val max : t → int end)
  module Forest = (struct
    type t = TF.Tree.t list
    val max = λx.case x of [] ⇒ 0
      | hd :: tl ⇒ let i = TF.Tree.max hd in let j = max tl in
        if i > j then i else j
    end : sig type t val max : t → int end)
end

```

Figure 1: Modules for trees and forest

2 Examples

In this section, we review two examples to illustrate two possible uses of recursive modules and to informally present *Traviata*¹.

The first example appears in Figure 1. The top-level module **TreeForest** contains two modules **Tree** and **Forest**: **Tree** represents a module for trees whose leaves and nodes are labeled with integers; **Forest** represents a module for unordered sets of those integer trees.

The modules **Tree** and **Forest** refer to each other in a mutually recursive way. Their type components **Tree.t** and **Forest.t** refer to each other, as do their value components **Tree.max** and **Forest.max**. These functions calculate the maximum integers a tree and a forest contain, respectively.

To enable forward references, we extend structures and signatures with implicitly typed declarations of *self variables*. Components of structures and signatures can refer to each other recursively using the self variables. For instance, **TreeForest** declares a self variable named **TF**, which is used inside **Tree** and **Forest** to refer to each other recursively. We keep the usual ML scoping rules for backward references. Thus **Tree.max** can refer to the **Leaf** and **Node** constructors without going through a self variable. **Tree** might also be used without prefix inside **Forest**, but the explicit notation seems clearer.

¹In examples, we shall allow ourselves to use some usual core language constructions, such as `let` and `if` expressions and list constructors, even though they are not part of the formal development given in Section 3.

This first example illustrates a possible use of recursive modules, where they respect each other’s privacy. They are sealed with opaque signatures individually, enforcing type abstraction inside the recursion.

The second example appears in Figure 2. Now `TreeForest` is a functor, parameterized by the type of labels of trees. We assume that an applicative functor `MakeSet` is given in a library for making sets of comparable elements.

The modules `Tree` and `Forest` define the same recursive types as the first example, except that the argument types of the constructors `Leaf` and `Node` are parameterized. The module abbreviation `module F = TF.Forest` inside `Tree` allows us to use an abbreviation `F` for `TF.Forest` inside `Tree`. Similarly, the type `s` in `Tree` is an abbreviation which expands into `TF.Forest.t`.

In this second example, `Tree` and `Forest` are intimate: the functions `Tree.split` and `Forest.sweep` know the underlying implementations of the types `Forest.t` and `Tree.t` of the others, thus can construct and deconstruct values of those types. Given a tree, `split` cuts off the root node of the tree and returns the resulting forest. `sweep` gathers the leaves from a given forest.

Since the two modules are intimate, we do not seal `Tree` and `Forest` individually here. Instead, we seal them as a whole with an opaque signature. The signature only exposes functions `split`, `sweep`, and `incr`, which augments a given forest only if a given tree contains original labels that are not contained in the forest, but hides functions `Tree.labels` and `Forest.labels`, which are utility functions for `incr`. The signature also enforces type abstraction by hiding implementations of the types `Tree.t` and `Forest.t`, thus it protects privacy of the two modules from the outside.

The two examples we have seen so far illustrate two possible uses of recursive modules. They may have privacy, enforcing type abstraction inside the recursion. They may have intimacy, enforcing type abstraction outside the recursion. We think both uses are natural and would become common in practice.

Comparison with existing type systems The two examples presented are type checked in our type system without requiring additional annotations. Below, we examine the ways existing type systems handle these examples.

To avoid presenting too much annotations, we remove the module abbreviation `module F = TF.Forest` from `Tree` in Figure 2. Yet, although we can dispense with abbreviations by replacing them with their definitions altogether, they are useful in practice [21].

In Russo’s system [24] there is no obvious way to type check the first example, keeping type abstraction between `Tree` and `Forest`. A suggested solution, which is

found in his paper, is to annotate the self variable `TF` of `TreeForest` with a *recursive signature*^{2 3} [24]:

```
sig (Z : sig module Tree : sig type t end
      module Forest : sig type t = Tree.t list end
    end)
module Tree : sig
  datatype t = Leaf of int | Node of int * Z.Forest.t end
  module Forest : sig type t = Tree.t list val max : t → int end
end
```

This annotation for `TF`, however, would break type abstraction between `Tree` and `Forest`, exposing underlying implementations of types `Tree.t` and `Forest.t` to each other.

In Dreyer’s system [5], the sealing signatures for `Tree` and `Forest` must be given in advance. That is, the programmer has to write both signatures before defining either of the two modules, as opposed to Figure 1, where the signatures are written in a module-wise way.

O’Caml [16] type checks Figure 1 without modifications.

Next, we examine the second example. As we claimed, our type system type checks it without requiring additional annotations.

In Russo’s system, the programmer must annotate `TF` with a recursive signature:

```
sig (Z : sig module Tree : sig type t end
      module Forest : sig type t = Tree.t list end
    end)
module Tree : sig
  datatype t = Leaf of X.t | Node of X.t * Z.Forest.t end
  module Forest : sig
    type t = Tree.t list val labels : t → MakeSet(X).t end
  end
```

Note that this signature is solely for assisting the type checker. We have already given in Figure 2 the eventual signatures that `Tree` and `Forest` should have; these signatures do not reveal the underlying implementations of types `Tree.t` and `Forest.t` or the function `Forest.labels`.

To type check Figure 2 in Dreyer’s system and O’Caml, the programmer must write fully manifesting signatures of `Tree` and `Forest` in advance, where the signatures declare every component of the modules. The type checker first type checks the

²This recursive signature does not exactly follow his syntax, *e.g.* we have to use the keyword `structure` instead of `module` in his system.

³We note that by permuting the definition order of `Tree` and `Forest` the amount of required annotations can be reduced to some extent in this case. However permutation does not always work.

two modules assisted by these manifest signatures. Once this succeeds, type abstraction is enforced using the sealing signature given in Figure 2. Thus the programmer has to write annotations yet more verbose than in Russo’s system.

We believe that both privacy and intimacy are important for practical uses of recursive modules. Existing type systems, however, do not handle them equally. These type systems may deny privacy. They may require additional annotations that are used only for helping the type checker, but do not affect resulting signatures of modules. Even if we assume that these annotations provide some useful information, our experience with type inference in ML is that one often writes a module without its signature, and then eventually writes a signature by editing the result of type inference. This technique has not been available with recursive modules in these type systems.


```

module TreeForest =
  functor (X : sig type t val compare : t → t → int end) →
    (struct (TF)
      module S = MakeSet(X)
      module Tree = struct
        module F = TF.Forest
        type s = F.t
        datatype t = Leaf of X.t | Node of X.t * s
        val split = λx.case x of Leaf i ⇒ [Leaf i]
          | Node (i, f) ⇒ (Leaf i) :: f
        val labels = λx.case x of Leaf i ⇒ TF.S.singleton i
          | Node (i, f) ⇒ TF.S.add i (F.labels f)
        end
      module Forest = struct
        module T = TF.Tree
        type t = T.t list
        val sweep = λx.case x of [] ⇒ []
          | (T.Leaf y) :: t1 ⇒ [(T.Leaf y)]
          | (T.Node y) :: t1 ⇒ (sweep t1)
        val labels = λx.case x of [] ⇒ TF.S.empty
          | hd :: t1 ⇒ TF.S.union (T.labels hd) (labels t1)
        val incr = λf. λt. let l1 = labels f and l2 = T.labels t in
          if TF.S.diff l1 l2 = TF.S.empty then f else (t :: f)
        end
      end: sig (Z)
        module Tree : sig type t val split : t → Z.Forest.t end
        module Forest : sig
          type t val sweep : t → t val incr : Z.Tree.t → t → t end
        end)
    end)

```

Figure 2: Intimate modules for trees and forests

3 Syntax

Figure 3 gives the module language of *Traviata*, which is based on Leroy’s applicative functor calculus [14]. We use M as a metavariable for module names, X for module variables and Z for self variables. For simplicity, we distinguish them syntactically, however the context could tell them apart without this distinction. We also use t for type names and l for (core) value names.

For the purpose of both defining type equality and designing a decidable type system, we label module expressions, signatures and *module variable signatures* with integers. For instance, a module expression E is a module expression description E_d labeled with an integer i , where E_d is either a structure, a functor, a sealing, a module identifier or a module variable⁴ One can think of the integer label i of E_d^i as the location of E_d in the source program. For the interest of brevity, we may omit integer labels when they are not used. For the interest of clarity, we may write additional parentheses, for instance $(\text{functor}(X : \text{sig type } t \text{ end}^2) \rightarrow X^3)^1$. We use metavariables i, j, k for integers.

As explained in the previous section, we extend structures and signatures with implicitly typed declarations of self variables to support recursive references. In the construct `struct (Z) $D_1 \dots D_n$ end`, the self variable Z is bound in $D_1 \dots D_n$. Similarly, in the construct `sig (Z) $B_1 \dots B_n$ end`, the self variable Z is bound in $B_1 \dots B_n$.

For simplicity, we provide different syntax for signatures and module variable signatures; the latter are used to specify signatures of functor arguments and do not declare self variables. In a practical system, we can unify their syntax for the programmer’s benefit.

The construct which enables recursive references is *recursive identifiers*. A recursive identifier is constructed from a self variable and the dot notation “ $.M$ ”, which represents access to the sub-modules M of a structure. A recursive identifier may begin from any bound self variable, and may refer to a module at any level of nesting within the recursive structure, regardless of component ordering. For instance, through the self variable of the top-level structure, one can refer to any module named in that structure except for those hidden within sealed sub-structures. It is important that recursive identifiers can only contain bound self variables, and that self variables of sealed modules are unbound outside them. Otherwise type abstraction could be broken.

⁴Note that *Traviata* does not have two different notions of opaque signatures and transparent ones.

Module expression
 $E ::= E_d^i$

Module expression descriptions
 $E_d ::= \text{struct } (Z) D_1 \dots D_n \text{ end} \quad \text{structure}$
 $\quad \quad \quad | \text{functor } (X : A) \rightarrow E \quad \text{functor}$
 $\quad \quad \quad | (E : S) \quad \text{sealing}$
 $\quad \quad \quad | \text{mid} \quad \text{module identifier}$
 $\quad \quad \quad | X \quad \text{module variable}$

Definitions
 $D ::= \text{module } M = E \quad \text{module def.}$
 $\quad \quad \quad | \text{datatype } t = c \text{ of } \tau \quad \text{datatype def.}$
 $\quad \quad \quad | \text{type } t = \tau \quad \text{type abbreviation}$
 $\quad \quad \quad | \text{val } l = e \quad \text{value def.}$

Signature
 $S ::= S_d^i$

Signature descriptions
 $S_d ::= \text{sig } (Z) B_1 \dots B_n \text{ end} \quad \text{structure type}$
 $\quad \quad \quad | \text{functor}(X : A) \rightarrow S \quad \text{functor type}$

Module variable signature
 $A ::= A_d^i$

Module variable signature description
 $A_d ::= \text{sig } B_1 \dots B_n \text{ end}$

Specifications
 $B ::= \text{module } M : S \quad \text{module spec.}$
 $\quad \quad \quad | \text{datatype } t = c \text{ of } \tau \quad \text{datatype spec.}$
 $\quad \quad \quad | \text{type } t = \tau \quad \text{manifest type spec.}$
 $\quad \quad \quad | \text{type } t \quad \text{abstract type spec.}$
 $\quad \quad \quad | \text{val } l : \tau \quad \text{value spec.}$

Recursive identifiers
 $\text{rid} ::= Z \mid \text{rid}.M$

Module identifiers
 $\text{mid} ::= \text{rid} \mid \text{mid}(\text{mid}) \mid \text{mid}(X)$

Extended module identifiers
 $\text{ext_mid} ::= Z \mid \text{ext_mid}.M$
 $\quad \quad \quad | \text{ext_mid}(\text{ext_mid}) \mid \text{ext_mid}(X)$

Module paths
 $p, q, r ::= \text{ext_mid} \mid X$

Program
 $P ::= \text{struct } (Z) D_1 \dots D_n \text{ end}^i$

Figure 3: The module language of *Traviata*

<i>Core types</i>	τ	$::=$	$\mathbf{1} \mid \tau_1 \rightarrow \tau_2 \mid \tau_1 * \tau_2 \mid p.t$
<i>Core expr.</i>	e	$::=$	$x \mid () \mid (\lambda x.e : \tau) \mid (e_1, e_2) \mid \pi_i(e) \mid e_1(e_2)$ $\mid rid.c e \mid X.c e \mid \mathbf{case} e \mathbf{of} ms \mid rid.l \mid X.l$
<i>Matching</i>	ms	$::=$	$rid.c x \Rightarrow e \mid X.c x \Rightarrow e$

Figure 4: The core language of *Traviata*

For the sake of simplicity, functor applications only contain module identifiers and module variables.

To support applicative functors [14], we define a slightly extended class of identifiers, named *module paths* in Figure 3, which can liberally include functor applications. Core types defined in Figure 4 may use module paths. Applicative functors give us more flexibility in expressing type sharing constraint between recursive modules. In Section 6, we give a practical example which uses recursive modules and applicative functors together in support of our design choices. It will be useful to note that $Z \subseteq rid \subseteq mid \subseteq ext_mid \subseteq p$ holds.

A program is a top-level structure which contains a bunch of recursive modules. In this paper, we only consider recursive modules, but not ordinary ones.

To obtain a decidable type system, we impose a *first-order structure restriction* that requires functors 1) not to take functors as argument, 2) or to access sub-modules of arguments. The first condition means that our functors are first-order, and the second implies that the programmer has to pass sub-modules as independent parameters for functors instead of passing a module which contains all of them. One might have noticed that the syntax of module expression descriptions excludes those of the forms $X.M$ and $X(mid)$. This is consistent with the restriction.

Figure 4 gives the our core language of *Traviata*. We use x as a metavariable for program variables (variables, for short), and c for value constructor names.

The core language describes a simple functional language extended with *value paths* $X.l$ and $rid.l$, and *type paths* $p.t$. Value paths $X.l$ and $rid.l$ refer to the value components l in the structures referred to by X and rid , respectively. A type path $p.t$ refers to the type component t in the structure that p refers to.

We may say paths to mean module, type and value paths as a whole.

An unusual convention is that a module variable is bound inside its own signature. For instance,

```
functor(X : sig type t val l : X.t end) → X
```

is a legal expression, which should be understood as

```
functor(X : sig type t val l : t end) → X
```

This convention is convenient when proving type soundness, as the syntax of paths is kept uniform, that is, every path is prefixed by either a self variable or a module variable. In Section 6, we give examples where this this convention is useful.

We write $MVars(p)$ to denote the set of module variables contained in the module path p . We also write $MVars(\tau)$, $MVars(e)$ and the likes with obvious meanings.

In the formalization, 1) function definitions are explicitly type annotated; 2) every structure and signature type but module variable signature declares a self variable; 3) a path is always prefixed by a self variable or a module variable. Our examples do not stick to these rules. Instead, we have assumed that there is an elaboration phase, prior to type checking, that adds type annotations for functions by running a type inference algorithm on the core language. The original program may still require some type annotations, to avoid running into the polymorphic recursion problem. In Section 9, we discuss the details of this inference algorithm. The elaboration phase also infers omitted self variables, to complete implicit backward references.

We assume that the following five conventions: 1) a program does not contain free module variables or free self variables; 2) all binding occurrences of module or self variables use distinct names; 3) any sequence of module definitions, type abbreviations, datatype definitions, value definitions, module specifications, manifest and opaque type specifications, datatype specifications and value specifications does not contain duplicate definitions or specifications for the same name; 4) all occurrences of module expressions, signatures and module variable signatures in a program are labeled with distinct integers; 5) module variable signatures do not contain module specifications.

Lazy signature
 $T ::= T_d^i$

Lazy signature descriptions
 $T_d ::= \text{sig } (Z) C_1 \dots C_n \text{ end} \quad \textit{lazy structure type}$
 $\quad \quad \quad | \quad \text{functor}(X : A) \rightarrow T \quad \textit{lazy functor type}$
 $\quad \quad \quad | \quad (T_1 : T_2) \quad \textit{lazy sealing type}$
 $\quad \quad \quad | \quad p$

Lazy specifications
 $C ::= \text{module } M : T$
 $\quad \quad \quad | \quad \text{val } l : \tau$
 $\quad \quad \quad | \quad \text{type } t = \tau$
 $\quad \quad \quad | \quad \text{type } t$
 $\quad \quad \quad | \quad \text{datatype } t = c \text{ of } \tau$

Lazy program type
 $U ::= \text{sig } (Z) C_1 \dots C_n \text{ end}^i$

Figure 5: Lazy module types

4 Reconstruction

The type system is composed of two parts, namely a type reconstruction part and a type-correctness check part. Concretely, we type check a program P in two steps: 1) reconstruct a *lazy program type* of P ; at this point, we do not require the reconstructed type to be correct; 2) check type-correctness of P by type checking P in the intuitive way, using the result of the reconstruction in a type environment; once this second step is completed, we are certain both that P is type-correct and that the reconstruction was correct.

In this section we describe the reconstruction part; the next section explains the type-correctness check part.

The rest of this section is organized as follows. In Section 4.1, we define lazy program types, which are output of the reconstruction algorithm. In Section 4.2, we define *look-up judgment* for using programs and lazy program types as lookup tables. In Section 4.3, we introduce “resolution algorithms“, the key for enabling the reconstruction. Finally, in Section 4.5, we present an algorithm for reconstructing lazy program types from programs.

In the rest of the paper, we assume that self variables Z are annotated with *module variable environments* θ , written Z^θ . A module variable environment is a substitution of module paths for module variables. Correspondingly, we assume that

<i>Top-levels</i>	O	$::=$	$P \mid U$
<i>Module descriptions</i>	K, J	$::=$	$E \mid S \mid A \mid T$
	$:=$	$::=$	$= \mid :$
	ss	$::=$	$struct \mid sig$

Figure 6: Notation

each occurrence of a self variable in a program P is implicitly annotated with an identity substitution id . That is, we regard Z as an abbreviation for Z^{id} . We use θ as a metavariable for module variable environments.

4.1 Lazy module types

Figure 5 gives the syntax for lazy module types, which we use as signatures of modules during type checking. The syntax for lazy signature descriptions extends that for signature descriptions with the sealing construction $(T_1 : T_2)$ and module paths. We use the sealing construction $(T_1 : T_2)$ to check type-correctness of the sealing construction $(E : S)$ of module expression descriptions ((31) in Figure 18). We use module paths to instantiate signatures lazily ((61) in Figure 21). In the construct $sig(Z) C_1 \dots C_n end$, the self variable Z is bound in $C_1 \dots C_n$. A lazy program type is a top-level lazy structure type labeled with an integer. Note that lazy signatures include signatures.

We use the notation convention in Figure 6. In particular, we use O as a metavariable for top-levels, which are either programs or lazy program types, and K for *module descriptions*, which are either module expression descriptions, signature descriptions, module variable signature descriptions or lazy signature descriptions.

4.2 Look-up

Next, we define a look-up judgment for finding module descriptions and their integer labels from a top-level. During the reconstruction we use the judgment against programs; during the type-correctness check, we use the judgment against lazy program types.

We assume that, for a top-level O , there is a global mapping ρ_O which sends i) a self variable Z to the structure or the (lazy) structure type to which Z is *ascribed* in O , and ii) a module variable X to the module variable signature specified for X in O . We say that in the construct $struct(Z) D_1 \dots D_n end^i$ the self variable Z is ascribed to $struct(Z) D_1 \dots D_n end^i$. Similarly, in the constructs $sig(Z) B_1 \dots B_n end^i$

$$\begin{array}{c}
\overline{O \vdash Z^\theta \mapsto (\theta, \rho_O(Z))} \quad (0) \quad \overline{O \vdash X \mapsto (id, \rho_O(X))} \quad (1) \\
\frac{O \vdash p \mapsto (\theta, \text{ss} \dots \text{module } M := K^j \dots \text{end}^i) \quad K \neq (K_1^{k_1} : K_2^{k_2})}{O \vdash p.M \mapsto (\theta, K^j)} \quad (2) \\
\frac{O \vdash p \mapsto (\theta, \text{ss} \dots \text{module } M := K^j \dots \text{end}^i) \quad K = (K_1^{k_1} : K_2^{k_2})}{O \vdash p.M \mapsto (\theta, K_2^{k_2})} \quad (3) \\
\frac{O \vdash p_1 \mapsto (\theta, (\text{functor}(X : A^j) \rightarrow K^k)^i) \quad K \neq (K_1^{k_1} : K_2^{k_2})}{O \vdash p_1(p_2) \mapsto (\theta[X \mapsto p_2], K^k)} \quad (4) \\
\frac{O \vdash p_1 \mapsto (\theta, (\text{functor}(X : A^j) \rightarrow K^k)^i) \quad K = (K_1^{k_1} : K_2^{k_2})}{O \vdash p_1(p_2) \mapsto (\theta[X \mapsto p_2], K_2^{k_2})} \quad (5)
\end{array}$$

Figure 7: Look-up

and $\text{sig}(Z') C_1 \dots C_m \text{end}^j$, Z and Z' are ascribed to $\text{sig}(Z) B_1 \dots B_n \text{end}^i$ and $\text{sig}(Z') C_1 \dots C_m \text{end}^j$, respectively. The use of ρ_O makes the presentation concise ⁵.

We present inference rules for the look-up judgment in Figure 7. The judgment $O \vdash p \mapsto (\theta, K^i)$ means that the module path p refers to the module description K labeled with the integer i in the top-level O , where each module variable X is bound to $\theta(X)$.

Let us examine each rule. For self variables and module variables, the judgment consults the global mapping ρ_O . Next two rules (3) and (4) handle module paths of the form $p.M$. A module path $p.M$ refers to the sub-module M in the module that p refers to. Hence p must refer to either a structure or a (lazy) structure type. The rules (3) and (4) distinguish whether M is bound to a sealing construction $(K_1^{j_1} : K_2^{j_2})^j$ or not; when it is, then $p.M$ resolves to the sealing part $K_2^{j_2}$. Thus, the judgment prevents peeking inside of sealed modules from the outside of them. The last two rules (5) and (6) handle module paths of the form $p_1(p_2)$. When p_1 refers to either a functor or a (lazy) functor type, then $p_1(p_2)$ resolves to the body of the functor, where the module variable environment is augmented with the new binding $[X \mapsto p_2]$. Again the rules (5) and (6) distinguish whether the body is a sealing construction or not.

⁵We could avoid this assumption of a global mapping by annotating each self variable with the source program location of the structure or structure type to which the self variable is ascribed. Since the source program can be regarded as a finite tree, we can represent every node of the tree by a finite representation (i.e., we need not use file names or line numbers.)


```

struct (Z)
  module M1 = (functor(X : sig type t end3) →
    struct module M11 = struct end5 end4)2
  module M2 = struct type t = int end6
  module M3 = Z.M1(Z.M2)7
end1

```

Figure 8: A program P_1

The look-up judgment does not hold for arbitrary module paths. For instance, consider Figure 8. We have $P_1 \vdash Z.M_1(Z.M_2).M_{11} \mapsto ([X \mapsto Z.M_2], \mathbf{struct\ end}^5)$. But, the judgment does not hold for the module path $Z.M_3.M_{11}$.

Recall that we have assumed the absence of free module variables. This means that when $O \vdash p \mapsto (\theta, q^i)$, then $MVars(q) \subseteq dom(\theta)$. For a module variable environment θ , $dom(\theta)$ denotes the domain of θ .

4.3 Resolution algorithms

Our type system differs from others in that it can resolve path references. Concretely, we developed a terminating procedure for determining the component that a path refers to, where the path may contain forward references. The motivation of this procedure was to define a decidable judgment for type equality. In a language with recursive modules and applicative functors, there is the potential that a program contains pathologically cyclic type abbreviations which may cause type equality check to diverge. We later noticed that a similar procedure enables type inference for recursive modules. Note that we cannot use the well-typedness of the source program when resolving path references, since we already need type equality to ensure this well-typedness.

We implement the procedure for path resolution as three algorithms, namely, a module path expansion algorithm *PathExp*, a type expansion algorithm *TypExp* and a core type reconstruction algorithm *CtyInf*. These algorithms use termination criteria based on ground term rewriting and recursive path ordering; the criteria do not rely on the well-typedness of the source program, and still allow flexible handling of module and type abbreviations.

In this paper, we do not explain these resolution algorithms in detail. There is another paper [20], which is devoted to their explanations.

Located types We define a canonical form of types, called *located types*. The type system checks equality between two arbitrary types by reducing them into located types using *TypExp*.

A located type is a type composed of *simple located types* and $\mathbf{1}$ using \rightarrow and $*$. Intuitively, a simple located type is an abstract type which is obtained by expanding all type and module abbreviations.

We first define *located forms*, a canonical form of module paths. A module path p is in located form if and only if p does not contain a module path which resolves to a module abbreviation.

Definition 1 *A module path p is in located form with respect to a top-level O if and only if the following two conditions hold.*

- $O \vdash p \mapsto (\theta, K^i)$ where K is not a module path.
- For all q in $\text{args}(p)$, q is in located form.

For a module path p , $\text{args}(p)$ denotes the set of module paths that p contains as functor arguments, or:

$$\begin{aligned} \text{args}(Z^\theta) &= \bigcup_{X \in \text{dom}(\theta)} \{\theta(X)\} \\ \text{args}(p.M) &= \text{args}(p) \quad \text{args}(p_1(p_2)) = \text{args}(p_1) \cup \{p_2\} \end{aligned}$$

A simple located type is an abstract type whose prefix is a located form.

Definition 2 *A simple located type with respect to a top-level O is a type path $p.t$ where p is in located form with respect to O and either $O \vdash p \mapsto (\theta, \text{ss} \dots \text{datatype } t = c \text{ of } \tau \dots \text{end}^i)$ or $O \vdash p \mapsto (\theta, \text{ss} \dots \text{type } t \dots \text{end}^i)$ holds.*

Now located types are defined below.

Definition 3 *A located type with respect to a top-level O is a type τ where each type τ' in $\text{typaths}(\tau)$ is a simple located type with respect to O .*

For a type τ , $\text{typaths}(\tau)$ denotes the set of type paths that τ contains. Precisely,

$$\text{typaths}(\tau) = \begin{cases} \text{typaths}(\tau_1) \cup \text{typaths}(\tau_2) & \text{when } \tau = \tau_1 \rightarrow \tau_2 \\ & \text{or } \tau = \tau_1 * \tau_2 \\ \{p.t\} & \text{when } \tau = p.t \\ \emptyset & \text{when } \tau = \mathbf{1} \end{cases}$$

$$\begin{array}{c}
\overline{O, \Sigma \vdash X \rightsquigarrow_g X} \qquad \overline{O, \Sigma \vdash Z^\theta \rightsquigarrow_g Z^\theta} \\
\frac{O, \Sigma \vdash p \rightsquigarrow_g p' \quad O \vdash p'.M \mapsto (\theta, q^i)}{O \vdash p'.M \mapsto (\theta, K^i) \quad K \notin mid} \quad \frac{O, \Sigma \vdash p \rightsquigarrow_g p' \quad O \vdash p'.M \mapsto (\theta, q^i)}{q \neq X \quad O, \Sigma \uplus i \vdash q \rightsquigarrow_g r} \\
\frac{}{O, \Sigma \vdash p.M \rightsquigarrow_g p'.M} \quad \frac{}{O, \Sigma \vdash p.M \rightsquigarrow_g \theta(r)} \\
\frac{O, \Sigma \vdash p_1 \rightsquigarrow_g p'_1 \quad O, \Sigma \vdash p_2 \rightsquigarrow_g p'_2 \quad O \vdash p'_1(p'_2) \mapsto (\theta, K^i) \quad K \notin mid}{O, \Sigma \vdash p_1(p_2) \rightsquigarrow_g p'_1(p'_2)} \\
\frac{O, \Sigma \vdash p_1 \rightsquigarrow_g p'_1 \quad O, \Sigma \vdash p_2 \rightsquigarrow_g p'_2 \quad O \vdash p'_1(p'_2) \mapsto (\theta, q^i) \quad q \neq X \quad O, \Sigma \uplus i \vdash q \rightsquigarrow_g r}{O, \Sigma \vdash p_1(p_2) \rightsquigarrow_g \theta(r)}
\end{array}$$

Figure 9: Ground-normalization with respect to O

$$\begin{aligned}
\eta_O(Z^\theta) &= Z^{\theta'} \\
\text{where } \text{dom}(\theta) &= \text{dom}(\theta'), \\
\text{and, for all } X \in \text{dom}(\theta), &\theta'(X) = \eta_O(\theta(X)) \\
\eta_O(X) &= X \\
\eta_O(p.M) &= \zeta_O(\eta_O(p).M) \\
\eta_O(p_1(p_2)) &= \zeta_O(\eta_O(p_1)(\eta_O(p_2))) \\
\zeta_O(p) &= \begin{cases} \theta(X) & \text{when } O \vdash p \mapsto (\theta, X^i) \\ p & \text{otherwise} \end{cases}
\end{aligned}$$

Figure 10: Variable normalization with respect to O

4.3.1 Module path expansion

We define the module path expansion algorithm $PathExp$ by composing *ground normalization* and *variable normalization*, which are defined below.

We define the ground normalization in Figure 9. The judgment $O, \Sigma \vdash p \rightsquigarrow_g q$ means that the ground normalization expands p into q where Σ is locked, with respect to the top-level O . We use Σ as a metavariable for sets of integers. The notation $\Sigma \uplus i$ means $\Sigma \cup \{i\}$ whenever $i \notin \Sigma$. Note that derivations of the ground normalization are deterministic. In particular, it is an error state when there are no applicable rules.

We define the variable normalization with respect to a top-level O using functions η_O and ζ_O , found in Figure 10.

Then we define $PathExp$ such that it takes as argument a top-level O and a module path p , then either returns a module path q when $O, \emptyset \vdash p \rightsquigarrow_g p'$ and $\eta_O(p') = q$ hold or else raises an error when this cannot be done.

Definition 4 *A module path p (resp. a type τ and an expression e) has located variables if and only if all the self variables contained in p (resp. τ and e) are in located form.*

Since Z^{id} is in located form, all module paths, types and expressions appearing in the source program have located variables.

Proposition 1 ([20]) *For any top-level O and module path p having located variables, if $PathExp(O, p) = q$, then q is in located form with respect to O .*

4.3.2 Type expansion

We define the type expansion algorithm in Figure 11. The judgment $O, \Omega \vdash \tau_1 \downarrow \tau_2$ means that the algorithm expands the type τ_1 into the type τ_2 where Ω is locked, with respect to the top-level O . We use Ω as a metavariable for pairs (i, t) of an integer i and a type name t .

Then we define $TypExp$ such that it takes as argument a top-level O and a type τ , then either returns a type τ' when $O, \emptyset \vdash \tau \downarrow \tau'$ holds or else raises an error when no rule applies, *i.e.* it cannot prove that the input type does not contain cyclic or dangling references.

Proposition 2 ([20]) *For any top-level O and type τ having located variables, $TypExp(O, \tau)$ either returns a located type with respect to O or else raises an error.*

$$\begin{array}{c}
\overline{O, \Omega \vdash \mathbf{1} \downarrow \mathbf{1}} \\
\frac{O, \Omega \vdash \tau_1 \downarrow \tau'_1 \quad O, \Omega \vdash \tau_2 \downarrow \tau'_2}{O, \Omega \vdash \tau_1 \rightarrow \tau_2 \downarrow \tau'_1 \rightarrow \tau'_2} \quad \frac{O, \Omega \vdash \tau_1 \downarrow \tau'_1 \quad O, \Omega \vdash \tau_2 \downarrow \tau'_2}{O, \Omega \vdash \tau_1 * \tau_2 \downarrow \tau'_1 * \tau'_2} \\
\frac{\text{PathExp}(O, p) = p' \quad O \vdash p' \mapsto (\theta, \text{ss} \dots \text{type } t \dots \text{end}^i)}{O, \Omega \vdash p.t \downarrow p'.t} \\
\frac{\text{PathExp}(O, p) = p' \quad O \vdash p' \mapsto (\theta, \text{ss} \dots \text{datatype } t = c \text{ of } \tau \dots \text{end}^i)}{O, \Omega \vdash p.t \downarrow p'.t} \\
\frac{\text{PathExp}(O, p) = p' \quad O \vdash p' \mapsto (\theta, \text{ss} \dots \text{type } t = \tau_1 \dots \text{end}^i) \quad O, \Omega \uplus (i, t) \vdash \tau_1 \downarrow \tau_2 \quad O, \Omega \vdash \theta(\tau_2) \downarrow \tau}{O, \Omega \vdash p.t \downarrow \tau}
\end{array}$$

Figure 11: Type expansion with respect to O

$$\begin{array}{c}
\overline{P, \Psi, \Gamma \vdash x \triangleright \Gamma(x)} \quad \overline{P, \Psi, \Gamma \vdash () \triangleright \mathbf{1}} \quad \frac{P, \Psi, \Gamma \vdash e_1 \triangleright \tau_1 \quad P, \Psi, \Gamma \vdash e_2 \triangleright \tau_2}{P, \Psi, \Gamma \vdash (e_1, e_2) \triangleright \tau_1 * \tau_2} \\
\frac{P, \Psi, \Gamma \vdash e \triangleright \tau_1 * \tau_2}{P, \Psi, \Gamma \vdash \pi_i(e) \triangleright \tau_i} \quad \frac{P, \Psi, \Gamma \vdash e_1 \triangleright \tau' \rightarrow \tau}{P, \Psi, \Gamma \vdash e_1(e_2) \triangleright \tau} \quad \frac{\text{TypExp}(P, \tau') = \tau}{P, \Psi, \Gamma \vdash (\lambda x. e : \tau') \triangleright \tau} \\
\frac{\text{PathExp}(P, p) = p' \quad \gamma(O, p', c) = (t, \tau_1)}{P, \Psi, \Gamma \vdash p.c \ e \triangleright p'.t} \\
\frac{\text{PathExp}(P, p) = p' \quad \gamma(O, p', c) = (t, \tau_1) \quad P, \Psi, \Gamma, x : \tau_1 \vdash e_2 \triangleright \tau}{P, \Psi, \Gamma \vdash \text{case } e_1 \text{ of } p.c \ x \Rightarrow e_2 \triangleright \tau} \\
\frac{\text{PathExp}(P, p) = p' \quad P \vdash p' \mapsto (\theta, \text{struct} \dots \text{val } l = e \dots \text{end}^i) \quad P, \Psi \uplus (i, l), \emptyset \vdash e \triangleright \tau_1 \quad \text{TypExp}(P, \theta(\tau_1)) = \tau}{P, \Psi, \Gamma \vdash p.l \triangleright \tau} \\
\frac{\text{PathExp}(P, p) = p' \quad P \vdash p' \mapsto (\theta, \text{sig} \dots \text{val } l : \tau' \dots \text{end}^i) \quad \text{TypExp}(P, \theta(\tau')) = \tau}{P, \Psi, \Gamma \vdash p.l \triangleright \tau}
\end{array}$$

Figure 12: Core type reconstruction with respect to P

$$\gamma(O, p, c) = (t, \tau) \text{ when}$$

$$O \vdash p \mapsto (\theta, \text{ss} \dots \text{datatype } t = c \text{ of } \tau' \dots \text{end}^i) \text{ and } \text{TypExp}(O, \theta(\tau')) = \tau$$

Figure 13: Datatype look-up with respect to O

4.4 Core type reconstruction

We define the core type reconstruction algorithm in Figure 12. The judgment $P, \Psi, \Gamma \vdash e \triangleright \tau$ means that the algorithm reconstructs the type τ for the expression e where Ψ is locked, with respect to the program P . We use Ψ as a metavariable for pairs (i, l) of an integer i and a value name l .

Then we define CtyInf such that it takes as argument a program P and a core expression e , then either returns a type τ when $P, \emptyset, \emptyset \vdash e \triangleright \tau$ holds or else raises an error when this cannot be done.

Proposition 3 ([20]) *For any program P and core expression e having located variables, $\text{CtyInf}(P, e)$ either returns a located type with respect to P or else raises an error.*

For a program P and a core expression e , $\text{CtyInf}(P, e)$ returns a located type that e would have when e is type-correct, but it does not check that e is indeed type-correct. For instance, for an expression $e_1(e_2)$, CtyInf only reconstructs a type of e_1 , which must be of the form $\tau_1 \rightarrow \tau_2$, then returns the result type τ_2 ; it does not check that e_2 has a type which is equivalent to τ_1 . In Section 5, we explain the type-correctness check part of the type system. Type-correctness of $e_1(e_2)$ is ensured in that part.

4.5 Lazy program type reconstruction algorithm

Figure 14 presents inference rules for the lazy program type reconstruction algorithm with respect to a program P . The algorithm uses CtyInf (see (10)), hence it does not ensure type-correctness of the program P . It either returns a lazy program type that P would have when P is type-correct, or else raises an error when it cannot prove that P does not contain cyclic or dangling references. Note that it does not check type-correctness of functor applications (see (16)).

Then we define ReconstP such that it takes a program P as argument, then either returns U when $P \vdash P \triangleright U$ holds or else raises an error when this cannot be done.

Definitions and Specifications

$$\frac{P \vdash E \triangleright T}{P \vdash \text{module } M = E \triangleright \text{module } M : T} \quad (6) \quad \frac{P \vdash S \triangleright T}{P \vdash \text{module } M : S \triangleright \text{module } M : T} \quad (7)$$

$$\frac{\text{TypExp}(P, \tau) = \tau'}{P \vdash \text{datatype } t = c \text{ of } \tau \triangleright \text{datatype } t = c \text{ of } \tau'} \quad (8) \quad \frac{\text{TypExp}(P, \tau) = \tau'}{P \vdash \text{type } t = \tau \triangleright \text{type } t = \tau'} \quad (9)$$

$$\frac{\text{CtyInf}(P, e) = \tau}{P \vdash \text{val } l = e \triangleright \text{val } l : \tau} \quad (10) \quad \frac{\text{TypExp}(P, \tau) = \tau'}{P \vdash \text{val } l : \tau \triangleright \text{val } l : \tau'} \quad (11)$$

Module expression

$$\frac{P \vdash E_d \triangleright T_d}{P \vdash E_d^i \triangleright T_d^i} \quad (12)$$

Module expression descriptions

$$\frac{P \vdash D_1 \triangleright C_1 \dots P \vdash D_n \triangleright C_n}{P \vdash \text{struct } (Z) D_1 \dots D_n \text{ end} \triangleright \text{sig } (Z) C_1 \dots C_n \text{ end}} \quad (13)$$

$$\frac{P \vdash A \triangleright A' \quad P \vdash E \triangleright T}{P \vdash \text{functor}(X : A) \rightarrow E \triangleright \text{functor}(X : A') \rightarrow T} \quad (14)$$

$$\frac{P \vdash E \triangleright T_1 \quad P \vdash S \triangleright T_2}{P \vdash (E : S) \triangleright (T_1 : T_2)} \quad (15) \quad \frac{}{P \vdash p \triangleright p} \quad (16)$$

Signature

$$\frac{P \vdash S_d \triangleright T_d}{P \vdash S_d^i \triangleright T_d^i} \quad (17)$$

Signature descriptions

$$\frac{P \vdash B_1 \triangleright C_1 \dots P \vdash B_n \triangleright C_n}{P \vdash \text{sig } (Z) B_1 \dots B_n \text{ end} \triangleright \text{sig } (Z) C_1 \dots C_n \text{ end}} \quad (18)$$

$$\frac{P \vdash A \triangleright A' \quad P \vdash S \triangleright T}{P \vdash \text{functor}(X : A) \rightarrow S \triangleright \text{functor}(X : A') \rightarrow T} \quad (19)$$

Module variable signature

$$\frac{P \vdash A_{d1} \triangleright A_{d2}}{P \vdash A_{d1}^i \triangleright A_{d2}^i} \quad (20)$$

Module variable signature description

$$\frac{P \vdash B_1 \triangleright B'_1 \dots P \vdash B_n \triangleright B'_n}{P \vdash \text{sig } B_1 \dots B_n \text{ end} \triangleright \text{sig } B'_1 \dots B'_n \text{ end}} \quad (21)$$

Figure 14: Lazy signature reconstruction with respect to P

Proposition 4 *For any program P , $\text{ReconstP}(P)$ either returns a lazy program type or raises an error.*

Usually, we write U_P to denote the lazy program type such that $\text{ReconstP}(P) = U_P$ holds.

$$\frac{U \vdash \text{TypExp}(U, \tau_1) \equiv_{\tau} \text{TypExp}(U, \tau_2)}{U \vdash \tau_1 \equiv \tau_2} \quad (22)$$

Figure 15: Type equivalence with respect to U

5 Type system

One of the main difficulties in type checking recursive modules is how to reason about forward references. Usually, a type checker consults a type environment for the necessary type information about paths. When paths only contain backward references, it is sufficient to accumulate in the type environment signatures of previously type checked modules. When modules are defined recursively, however, paths may contain forward references. Then the type checker may attempt to ask the type environment for a signature of a module which is not yet type checked.

To circumvent difficulties arising from forward references, other type systems rely on signature annotations. As we examined in Section 2, this requirement compels the programmer to write two different signatures for the same module to enforce type abstraction outside the recursion. Moreover, the programmer cannot rely on type inference during development due to it. This is unfortunate since a lot of useful inference algorithms have been and will be developed to support smooth development of programs.

We have a reconstruction algorithm, hence we do not need the assistance of signature annotations. That is, we use the result of reconstruction as type environment instead of using programmer-supplied annotations.

There are three tasks to be completed in this type-correctness check part: 1) to check type-correctness of core expressions. (Recall that *CtyInf* does not ensure type-correctness of expressions that it reconstructs types for.); 2) to check well-formedness of module paths, that is, to check that functor applications contained in the paths are type-correct and that references of the paths are not cyclic or dangling; 3) to check that, for every sealing construction $(E : S)$, the module expression E inhabits the signature S .

5.1 Type equality

We define a type equivalence judgment in Figure 15, with auxiliaries in Figure 16 and 17. The judgment $\tau_1 \vdash \tau_2 \equiv$ means that two types τ_1 and τ_2 are equivalent with respect to the lazy program type U . We check equivalence between two arbitrary types by reducing them into located types.

$$\begin{array}{c}
\frac{}{U \vdash \mathbf{1} \equiv_{\tau} \mathbf{1}} \quad (23) \qquad \frac{U \vdash \tau_1 \equiv_{\tau} \tau'_1 \quad U \vdash \tau_2 \equiv_{\tau} \tau'_2}{U \vdash \tau_1 \rightarrow \tau_2 \equiv_{\tau} \tau'_1 \rightarrow \tau'_2} \quad (24) \\
\frac{U \vdash \tau_1 \equiv_{\tau} \tau'_1 \quad U \vdash \tau_2 \equiv_{\tau} \tau'_2}{U \vdash \tau_1 * \tau_2 \equiv_{\tau} \tau'_1 * \tau'_2} \quad (25) \qquad \frac{U \vdash p_1 \equiv_p p_2}{U \vdash p_1.t \equiv_{\tau} p_2.t} \quad (26)
\end{array}$$

Figure 16: Equivalence on located types with respect to U

$$\frac{U \vdash p_1 \mapsto (\theta_1, T_{d1}^{i_1}) \quad U \vdash p_2 \mapsto (\theta_2, T_{d2}^{i_2}) \quad i_1 = i_2 \quad \forall X \in \text{dom}(\theta_1), U \vdash \theta_1(X) \equiv_p \theta_2(X)}{U \vdash p_1 \equiv_p p_2} \quad (27)$$

Figure 17: Equivalence on located forms with respect to U

Figure 16 defines equivalence on located types. The first three rules are straightforward. The last rule judges whether two abstract types are equivalent. Two types $p_1.t$ and $p_2.t$ are equivalent if and only their prefixes p_1 and p_2 are equivalent module paths. (Note that since $p_1.t$ is a located type, p_1 is in located form.)

Figure 17 defines a judgment for equivalence on module paths in located form. Two located forms p_1 and p_2 are equivalent if and only if they refer to module descriptions at the same location (i.e., labeled with the same integer) and their functor arguments are equivalent. Take a look at the look-up judgment (Figure 7) again. The module variable environment θ_1 collects all module paths contained in p_1 as functor arguments.

5.2 Typing rules

In Figure 18 and 19, we present typing rules for the type-correctness check, with auxiliaries in Figure 20, 21 and 22.

The judgment $U \vdash E : T$ means that the module expression E of lazy signature T is type-correct with respect to the lazy program type U . The judgment $e, \Gamma \vdash \tau :$ means that the core expression e of type τ is type-correct under the type environment Γ with respect to U . A type environment assigns a located type to a variable. Other judgments are read similarly.

The typing rules in Figure 18 are mostly straightforward. Here we only explain the rule for sealing.

The rule (31) checks that the sealing construction $(E : S)$ is type-correct. In particular, the third premise is for ensuring that the module expression E inhabits the signature S ; it checks that the lazy signature T_1 of E_1 is a subtype of $\text{Subst}(T_1, S)$.

Module expression

$$\frac{U \vdash E_d : T_d}{U \vdash E_d^i : T_d^i} \quad (28)$$

Module expression descriptions

$$\frac{U \vdash D_1 : C_1 \dots U \vdash D_n : C_n}{U \vdash \text{struct } (Z) D_1 \dots D_n \text{ end} : \text{sig } (Z) C_1 \dots C_n \text{ end}} \quad (29)$$

$$\frac{U \vdash A : A' \quad U \vdash E : T}{U \vdash \text{functor}(X : A) \rightarrow E : \text{functor}(X : A') \rightarrow T} \quad (30)$$

$$\frac{U \vdash E : T_1 \quad U \vdash S : T_2 \quad T_1 \vdash \text{Subst}(T_1, S) <}{U \vdash (E : S) : (T_1 : T_2)} \quad (31) \quad \frac{U \vdash p \text{ wf}}{U \vdash p : p} \quad (32)$$

Definitions and Specifications

$$\frac{U \vdash E : T}{U \vdash \text{module } M = E : \text{module } M : T} \quad (33) \quad \frac{e, \emptyset \vdash \tau :}{U \vdash \text{val } l = e : \text{val } l : \tau} \quad (34)$$

$$\frac{U \vdash \tau \diamond \quad \text{TypExp}(U, \tau) = \tau'}{U \vdash \text{datatype } t = c \text{ of } \tau : \text{datatype } t = c \text{ of } \tau'} \quad (35)$$

$$\frac{U \vdash \tau \diamond \quad \text{TypExp}(U, \tau) = \tau'}{U \vdash \text{type } t = \tau : \text{type } t = \tau'} \quad (36) \quad \frac{U \vdash S : T}{U \vdash \text{module } M : S : \text{module } M : T} \quad (37)$$

$$\frac{}{U \vdash \text{type } t : \text{type } t} \quad (38) \quad \frac{U \vdash \tau \diamond \quad \text{TypExp}(U, \tau) = \tau'}{U \vdash \text{val } l : \tau : \text{val } l : \tau'} \quad (39)$$

Signature

$$\frac{U \vdash S_d : T_d}{U \vdash S_d^i : T_d^i} \quad (40)$$

Signature descriptions

$$\frac{U \vdash B_1 : C_1 \dots U \vdash B_n : C_n}{U \vdash \text{sig } (Z) B_1 \dots B_n \text{ end} : \text{sig } (Z) C_1 \dots C_n \text{ end}} \quad (41)$$

$$\frac{U \vdash A : A' \quad U \vdash S : T}{U \vdash \text{functor}(X : A) \rightarrow S : \text{functor}(X : A') \rightarrow T} \quad (42)$$

Module variable signature

$$\frac{U \vdash A_{d1} : A_{d2}}{U \vdash A_{d1}^i : A_{d2}^i} \quad (43)$$

Module variable signature description

$$\frac{U \vdash B_1 : B'_1 \dots U \vdash B_n : B'_n}{U \vdash \text{sig } B_1 \dots B_n \text{ end} : \text{sig } B'_1 \dots B'_n \text{ end}} \quad (44)$$

Figure 18: Typing rules for the module language with respect to U

$$\begin{array}{c}
\text{Core types} \\
\frac{}{U \vdash \mathbf{1} \diamond} \quad (45) \quad \frac{U \vdash \tau_1 \diamond \quad U \vdash \tau_2 \diamond}{U \vdash \tau_1 \rightarrow \tau_2 \diamond} \quad (46) \quad \frac{U \vdash \tau_1 \diamond \quad U \vdash \tau_2 \diamond}{U \vdash \tau_1 * \tau_2 \diamond} \quad (47) \\
\frac{U \vdash p \text{ wf} \quad \text{TypExp}(U, p.t) = \tau}{U \vdash p.t \diamond} \quad (48) \\
\text{Core expressions} \\
\frac{}{U, \Gamma \vdash () : \mathbf{1}} \quad (49) \quad \frac{x \in \text{dom}(\Gamma)}{U, \Gamma \vdash x : \Gamma(x)} \quad (50) \\
\frac{U, \Gamma \vdash e_1 : \tau_1 \quad U, \Gamma \vdash e_2 : \tau_2}{U, \Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2} \quad (51) \quad \frac{U, \Gamma \vdash e : \tau_1 * \tau_2}{U, \Gamma \vdash \pi_i(e) : \tau_1} \quad (52) \\
\frac{U \vdash \tau \diamond \quad \text{TypExp}(U, \tau) = \tau_1 \rightarrow \tau_2 \quad U, \Gamma, x : \tau_1 \vdash e : \tau_3 \quad U \vdash \tau_2 \equiv \tau_3}{U, \Gamma \vdash (\lambda x. e : \tau) : \tau_1 \rightarrow \tau_2} \quad (53) \\
\frac{U, \Gamma \vdash e_1 : \tau_1 \rightarrow \tau_2 \quad U, \Gamma \vdash e_2 : \tau_3 \quad U \vdash \tau_1 \equiv \tau_3}{U, \Gamma \vdash e_1 (e_2) : \tau_2} \quad (54) \\
\frac{U \vdash p \text{ wf} \quad \text{PathExp}(U, p) = p' \quad \gamma(U, p', c) = (t, \tau_1) \quad U, \Gamma \vdash e : \tau_2 \quad U \vdash \tau_1 \equiv \tau_2}{U, \Gamma \vdash p.c \ e : p'.t} \quad (55) \\
\frac{U, \Gamma \vdash e_1 : \tau_1 \quad U \vdash p \text{ wf} \quad \text{PathExp}(U, p) = p' \quad \gamma(U, p', c) = (t, \tau_2) \quad U \vdash \tau_1 \equiv p'.t \quad U, \Gamma, x : \tau_2 \vdash e_2 : \tau}{U, \Gamma \vdash \text{case } e_1 \text{ of } p.c \ x \Rightarrow e_2 : \tau} \quad (56) \\
\frac{U \vdash p \text{ wf} \quad \text{PathExp}(U, p) = p' \quad U \vdash p' \mapsto (\theta, \text{sig} \dots \text{val } l : \tau' \dots \text{end}^i) \quad \text{TypExp}(U, \theta(\tau')) = \tau}{U, \Gamma \vdash p.l : \tau} \quad (57)
\end{array}$$

Figure 19: Typing rules for the core language with respect to U

$$\begin{aligned}
\text{Subst}(T_d^i, S_d^j) &= \text{subst1}(T_d, S_d)^j \\
\text{subst1}(p, \text{sig } (Z) B_1 \dots B_n \text{ end}) &= (\text{sig } (Z) \text{ subst2}(p, [Z \mapsto p]B_1) \dots \text{subst2}(p, [Z \mapsto p]B_n) \text{ end}) \\
\text{subst1}(p, \text{functor}(X : A) \rightarrow S_d^i) &= \text{functor}(X : A) \rightarrow \text{subst1}(p(X), S_d)^i \\
\text{subst1}(\text{sig } (Z) C_1 \dots C_n \text{ end}, \text{sig } (Z') B_1 \dots B_m \text{ end}) &= \text{sig } (Z') \\
&\quad \text{subst3}(C_{\sigma(1)}, [Z' \mapsto Z]B_1) \dots \text{subst3}(C_{\sigma(m)}, [Z' \mapsto Z]B_m) \text{ end} \\
\text{subst1}(\text{sig } \dots \text{end}, \text{functor}(X : A) \rightarrow S) &= \text{raise Error} \\
\text{subst1}(\text{functor}(X : A) \rightarrow T_d^i, \text{functor}(X' : A') \rightarrow S_d^j) &= \text{functor}(X' : A') \rightarrow \text{subst1}([X \mapsto X']T_d, S_d)^j \\
\text{subst1}(\text{functor}(X : A) \rightarrow T, \text{sig } \dots \text{end}) &= \text{raise Error} \\
\text{subst1}((T : T_d^i), S_d) &= \text{subst1}(T_d, S_d) \\
\text{subst2}(p, \text{module } M : S_d^i) &= \text{module } M : \text{subst1}(p.M, S_d)^i \\
\text{subst2}(p, B) &= B \quad \text{where } B \text{ is not a module specification} \\
\text{subst3}(\text{module } M : T_d^i, \text{module } M : S_d^j) &= \text{module } M : \text{subst1}(T_d, S_d)^j \\
\text{subst3}(C, B) &= B \quad \text{where } B \text{ is not a module specification}
\end{aligned}$$

Figure 20: Substitution

$$\begin{array}{c}
\frac{U \vdash T_d < S_d}{U \vdash T_d^i < S_d^j} \quad (58) \quad \frac{U \vdash T_d < A_d}{U \vdash T_d^i < A_d^j} \quad (59) \\
\frac{U \vdash T_d < S_d}{U \vdash (T : T_d^i) < S_d} \quad (60) \\
\frac{\text{PathExp}(U, p) = p' \quad U \vdash p' \mapsto (\theta, T_d^i) \quad U \vdash \theta(T_d) < S_d}{U \vdash p < S_d} \quad (61) \\
\frac{\sigma : \{1, \dots, m\} \mapsto \{1, \dots, n\} \quad \forall i \in \{1, \dots, m\}, U \vdash C_{\sigma(i)} < B_i}{U \vdash \text{sig}(Z) C_1 \dots C_n \text{ end} < \text{sig}(Z') B_1 \dots B_m \text{ end}} \quad (62) \\
\frac{U \vdash A' < A \quad U \vdash [X \mapsto X']T < S}{U \vdash \text{functor}(X : A) \rightarrow T < \text{functor}(X' : A') \rightarrow S} \quad (63) \\
\frac{\sigma : \{1, \dots, m\} \mapsto \{1, \dots, n\} \quad \forall i \in \{1, \dots, m\}, U \vdash C_{\sigma(i)} < B_i}{U \vdash \text{sig} C_1 \dots C_n \text{ end} < \text{sig} B_1 \dots B_m \text{ end}} \quad (64) \\
\overline{U \vdash \text{type } t < \text{type } t} \quad (65) \quad \overline{U \vdash \text{type } t = \tau < \text{type } t} \quad (66) \\
\overline{U \vdash \text{datatype } t = c \text{ of } \tau < \text{type } t} \quad (67) \\
\frac{U \vdash \tau_1 \equiv \tau_2}{U \vdash \text{type } t = \tau_1 < \text{type } t = \tau_2} \quad (68) \\
\frac{U \vdash \tau_1 \equiv \tau_2}{U \vdash \text{val } l : \tau_1 < \text{val } l : \tau_2} \quad (69) \\
\frac{U \vdash \tau_1 \equiv \tau_2}{\overline{U \vdash \text{datatype } t = c \text{ of } \tau_1 < \text{datatype } t = c \text{ of } \tau_2}} \quad (70) \\
\frac{U \vdash T < S}{\overline{U \vdash \text{module } M : T < \text{module } M : S}} \quad (71)
\end{array}$$

Figure 21: Subtyping with respect to U

$$\begin{array}{c}
\overline{U \vdash X \text{ wf}} \quad (72) \quad \overline{U \vdash Z^{id} \text{ wf}} \quad (73) \quad \frac{U \vdash p \text{ wf} \quad \text{PathExp}(U, p.M) = q}{U \vdash p.M \text{ wf}} \quad (74) \\
\frac{\text{PathExp}(U, p_1) = p'_1 \quad \text{PathExp}(U, p_2) = p'_2 \quad \text{PathExp}(U, p_1(p_2)) = q}{U \vdash p'_1 \mapsto (\theta, (\text{functor}(X : A_d^j) \rightarrow T)^i) \quad p'_2 \vdash \theta[X \mapsto p'_2](A_d) <} \\
\quad \overline{U \vdash p_1(p_2) \text{ wf}} \quad (75)
\end{array}$$

Figure 22: Well-formed module paths with respect to U

The subtyping relation, to be given below, follows that of Leroy’s applicative functor calculus. In particular, for two manifest type specifications `type t : τ_1` and `type t : τ_2` to be in subtyping relations, τ_1 and τ_2 must be equivalent. To check type equivalence, the type system expands types using *TypExp*; here is the reason that we define the function *Subst*, which is found in Figure 20.

The function *Subst* performs explicit substitution for self variables declared inside sealing signatures. For instance, consider Figure 2. The reconstruction algorithm infers that the function `split` in `Forest` has a type `TF.Tree.t \rightarrow TF.Tree.t list` (For clarity, we add omitted self variables.). The sealing signature specifies that `split` has a type `Z.Tree.t \rightarrow Z.Forest.t`. Both the reconstructed type and the specified type are located types, but they are not equivalent according to the type equivalence judgment. In fact, for `Forest` to inhabit the sealing signature, the reconstructed type `TF.Tree.t \rightarrow TF.Tree.t list` should be equivalent to `TF.Tree.t \rightarrow TF.Forest.t`, which is the type obtained by substituting `TF` for `Z` in the specified type `Z.Tree.t \rightarrow Z.Forest.t`. Indeed, this is satisfied since the type `TF.Forest.t` expands into `TF.Tree.t list`.

One may think that it would be more natural to identify signatures related by α -renaming rather than to perform explicit substitution. Yet implicit renaming makes it complex to use the type expansion algorithm, which is developed separately from the typing rules.

In Figure 21, we define subtyping relations between a lazy signature and a signature (58), between a lazy signature and a module variable signature (59), between a lazy signature description and a signature description ((60) to (63)), between a lazy signature description and a module variable description ((64)) and between a lazy specification and a specification ((65) to (71)). The rules are mostly intuitive. The reader should only look at the rule (61). A lazy signature description can be a module path p . To check that p is a subtype of a signature description S_d , we instantiate the lazy signature of the module that p refers to; we use the module path expansion algorithm *PathExp* to resolve p ’s reference. For the decidability of the subtyping relations, it is important that only lazy signature descriptions can be module paths, but ordinary signature descriptions cannot.

The judgment $U \vdash p$ wf, defined in Figure 22, checks that the module path p is well-formed. For instance, the rule (32) in Figure 18 uses this judgment for checking type-correctness of module paths. The judgment ensures that the module path p does not contain cyclic or dangling references and that functor applications contained in p are type-correct.

Definition 5 *A program P is well-typed if and only if $\text{Reconst}P(P) = U$ and $U \vdash$*

$P : U$ holds.

Proposition 5 *For any program P , it is decidable whether P is well-typed or not.*


```

module type E =
  sig type exp val eval : exp → int val simp : exp → exp end
module PF = functor(X : E with type exp = private [> PF(X).exp ] ) →
  struct
    type exp = ['Num of int | 'Plus of X.exp * X.exp]
    val eval : exp → int = λx.case x of 'Num n ⇒ n
      | 'Plus (e1, e2) ⇒ X.eval e1 + X.eval e2
    val simp : exp → X.exp = λx.case x of 'Num n ⇒ 'Num n
      | 'Plus(e1, e2) ⇒ case (X.simp e1, X.simp e2) of
          ('Num m, 'Num n) ⇒ 'Num(m+n)
          | e12 ⇒ 'Plus e12
    end
  module Plus = (PF(Plus) : E with type exp = PF(Plus).exp)

```

Figure 23: A first language

6 The expression problem

In this section, we present an advanced example of recursive modules, by giving a solution to the expression problem [27].

The expression problem, originally coined by Phil Wadler, dates back to Cook, who first discussed this problem [2]. It is one of the most fundamental problems one faces during the development of extensible software. Here, we paraphrase a typical example of this problem in the following way: suppose that we have a small expression language, composed of a recursively defined datatype and processors which operate on this datatype; then we want to extend the expression language in two dimensions, that is, to extend the datatype with new constructors and to add new processors that operate on both existing and new constructors. That a programming language can solve this problem in a type safe and concise way has been regarded as a measure of the expressive power of the language. Many researchers have addressed themselves to this problem, using different programming languages [22, 28, 26].

Our aim here is not to draw a conclusion that our solution is better than other solutions. It is not easy to compare the quality of different solutions, without deep understandings of each implementation language that is used to express each solution. Instead, we aim to give a useful example of recursive modules, in order to show that by combining recursive modules with other constructs of the core and the module languages we can obtain more expressive power in a modular way.

The example we use here extends the one in [9]. It is a variation on the expression problem, where we only insist on the addition of new constructors. Adding new processors is easy in this setting.

We shall assume that we have extended *Traviata* with polymorphic variants [7], private row types [9] and some usual module language constructions. Adding polymorphic variants and private row types is straightforward. We add typing rules for them to our language. Allowing structures to contain module type definitions may not be easy, but having module type definitions in the top-level is easy.

To reduce notational burden, we omit, here and elsewhere, preceding self variables even for forward references when no ambiguity seems to arise. We also omit the top-level `struct` and `end`.

We define our first expression language in Figure 23, using the functor `PF`. The type `exp` defined in the body of `PF` indicates that the first language supports expressions composed of integer constants and addition. The function `eval` is for evaluating the expressions into integers. The function `simp` is for simplifying the expressions, by reducing the `'Plus` constructor into the `'Num` constructor when possible.

To keep the first language extensible, we leave `PF` open recursion; the polymorphic variant type `exp` and functions `eval` and `simp` recur through `PF`'s parameter `X`.

The intuition of the example is that `PF` takes as argument an expression language which is built by extending the addition language that `PF` defines. This is exactly what the signature of `X` expresses; here is the key of the example. The type specification `type t = private [> PF(X).exp]` specifies an abstract type into which the type `PF(X).exp` can be coerced, or, informally, an abstract type which is a supertype of `PF(X).exp`. The type `PF(X).exp` refers to the type `exp` defined inside `PF`'s body. Hence `X`'s signature specifies that `PF` can only be applied to a module whose defining expression language supports both integers and addition. This recursive use of `PF(X).exp` to constrain `PF`'s argument is the main difference with the solution in [9]. By avoiding the need to define types outside of the functor, it allows for a more concise and scalable solution. Observe that if it were not for all of applicative functors, private row types and flexible path references, we could not write `X`'s signature in this way.

The use of polymorphic variants, which are structural types unlike usual nominal datatypes, is important also for defining the function `simp`. The function `simp` has the type `exp → X.exp`. Since the type `X.exp` structurally contains the type `exp`, as specified in the `X`'s signature, all of `'Num n`, `'Num(m+n)` and `'Plus e12`, which are the results of the case branches, are citizens of the type `X.exp`.

The module `Plus` instantiates the addition language, by closing `PF`'s open re-

```

module MF = functor(X : E with type exp = private [> MF(X).exp ]) →
  struct
    module Plus = PF(X)
    type exp = [Plus.exp | 'Mult of X.exp * X.exp ]
    val eval : exp → int = λx.case x of
      #Plus.exp as e ⇒ Plus.eval e
    | 'Mult(e1, e2) ⇒ X.eval e1 * X.eval e2
    val simp : exp → X.exp = λx.case x of
      #Plus.exp as e ⇒ Plus.simp e
    | 'Mult(e1, e2) ⇒ case (X.simp e1, X.simp e2) of
      ('Num m, 'Num n) ⇒ 'Num(m*n)
    | e12 ⇒ 'Mult e12
  end
module Mult = (MF(Mult) : E with type exp = MF(Mult).exp)

```

Figure 24: A second language

cursion. Observe that both the type and the value level open recursion are closed simultaneously, that is, by taking the fix-point of `PF`, the forwardings `X.exp`, `X.eval` and `X.simp` are connected to `exp`, `simp` and `eval` themselves, thus yielding self contained recursive type `exp` and recursive functions `eval` and `simp`.

Now we can perform addition on the first language. For instance,

```
val e1 = Plus.eval ('Plus('Num 3, 'Num 4))
```

Next, we define our second expression language using the functor `MF` in Figure 24. The second language supports expressions composed of multiplication and addition on integer constants.

We use the exactly same idiom as the first language to define this second language. In particular, the type `MF(X).exp` appearing in `X`'s signature refers to the type `exp` defined in the body of `MF`.

Note that we instantiate the first addition language inside `MF`, and use it in functions `eval` and `simp` to delegate known cases by variant dispatch. Thus we avoid duplication of program codes.

The module `Mult` instantiates the second language, by closing `MF`'s open recursion. Now we can do arithmetic on the second language. For instance,

```
val e2 = Mult.eval ('Plus('Mult('Num 3, 'Num 4), 'Num 5))
```

Finally, we demonstrate in Figure 25 that it is easy to compose independent

```

module NF =
  functor(X: E with type exp = private [> NF(X).exp]) →
  struct
    type exp = ['Num of int | 'Minus of X.exp * X.exp ]
    val eval : exp →int = λx.case x of 'Num n ⇒n
      | 'Minus(e1, e2) ⇒(X.eval e1) - (X.eval e2)
    val simp : exp →X.exp = λx.case x of 'Num n ⇒'Num n
      | 'Minus(e1, e2) ⇒case (X.simp e1, X.simp e2) of
          ('Num m, 'Num n) ⇒'Num(m-n)
      | e12 ⇒'Minus e12
  end
end
module GF =
  functor(X:E with type exp = private [> GF(X).exp]) →
  struct
    module Plus = PF(X)
    module Minus = NF(X)
    type exp = [Plus.exp | Minus.exp]
    val eval : exp →int = λx.case x of
      #Plus.exp as e ⇒ Plus.eval e
      | #Minus.exp as e ⇒ Minus.eval e
    val simp : exp →X.exp = λx.case x of
      #Plus.exp as e ⇒ Plus.simp e
      | #Minus.exp as e ⇒ Minus.simp e
  end
end

```

Figure 25: To merge independantly developed extensions

extensions into a single expression language.

Having seen examples here and in Section 2, we confirm that recursive modules are useful in several situations. Moreover, when combined with other language constructions, they give us the highly expressive power in a modular way. We believe that recursive modules are a promising candidate for supporting robust extensible software.

```

module TreeForest = struct (TF)
  module Tree = (struct
    datatype t = Leaf of int | Node of int * TF.Forest.t
    val max = ...
    val mk_tree = λx.let i = TF.Forest.max x in Node(i, x)
  end : sig type t val max : t → int val mk_tree : TF.Forest.t → t end)
  module Forest = (struct
    type t = TF.Tree.t list
    val max = ...
    val combine = λx.λy.TF.Tree.mk_tree [x;y]
  end : sig
    type t val max : t → int val combine : TF.Tree.t → TF.Tree.t → TF.Tree.t
  end)
end

```

Figure 26: An example for the double vision problem

7 The double vision problem

Here we examine the double vision problem [6], a typing difficulty involved in recursive modules, in the context of *Traviata*. Detailed examinations of this problem are found in [6, 3].

7.1 The situation we have to handle

When a module is sealed with a signature, the type system distinguishes the module defined inside the signature and the module which inhabits the signature. For instance, consider Figure 1. Inside `Forest`, the type `t` and the type `TF.Forest.t` are not equivalent; the former is an internal type, which refers to `Forest`'s type `t` inside the sealing, but the latter is an external type, which refers to `Forest`'s type `t` outside.

This design choice of type equivalence keeps the type equivalence judgment simple. Yet, it might be occasionally inconvenient, for instance, when the programmer wants to build a value of an external type inside sealing.

To see a concrete situation, consider Figure 26. This is the same program as in Figure 1, but here `Tree` and `Forest` contain new functions `mk_tree` and `combine`, respectively; the former is for building a tree from a given forest and the latter for building a tree from given two trees.

Our type system cannot type check the defining expression of `combine`. For the

expression `[x;y]` inside the body of `combine`, the core type reconstruction algorithm infers that the expression has a type `TF.Tree.t list`; the function `TF.Tree.mk_tree` takes an argument of type `TF.Forest.t`, which is specified in `Tree`'s sealing signature. According to our type equivalence judgment, however, the types `TF.Forest.t` and `TF.Tree.t list` are not equivalent, since `TF.Forest.t` is an abstract type thus is not equivalent to any other types than itself.

This kind of situation typically occurs when the programmer attempts to cyclically import, inside a sealed module, a value that is exported by the same module as a value of an abstract type. Note that such reimportation is only possible with recursive modules, but not with ordinary modules.

7.2 Type coercion

Currently we provide a core language construction, called *type coercion*, that allows the programmer to coerce types of expressions from internal types to external types and vice versa, in an explicit way. The type coercion construction is of the form $(e : \tau ::> \tau')$, which informally reads as “to coerce the type τ of the expression e into τ' ”. For instance, the programmer can define a type-correct `combine` as

```
val combine =
  λx.λy.TF.Tree.mk_tree ([x;y] : t ::> TF.Forest.t)
```

(Observe that the internal type `t` of `Forest` is only visible inside `Forest`.)

In the rest of this section, we formalize type coercion.

Note that the programmer can avoid this situation by providing the following module `Ty` inside `Forest`, instead of providing the type definition `type t = TF.Tree.t list` as in Figure 26.

```
module Ty = (struct
  type t = TF.Tree.t list val inj = λx.x val prj = λx.x
end : sig
  type t val inj : TF.Tree.t list → t val prj : t → TF.Tree.t list
end)
```

The programmer needs to use the functions `inj` and `prj` as needed when defining functions `Forest.max` and `Forest.combine`. By hiding `inj` and `prj` from `Tree`, but only exporting the abstract type `Ty.t`, he can produce the same effect as in Figure 26 without type errors.

Locating paths First, we introduce *locating paths*. Intuitively, a locating path is an absolute module path which refers to a module relative to the top-level, whereas

$$\overline{O \vdash \epsilon \mapsto_l (id, O)} \quad (76)$$

$$\frac{O \vdash lc \mapsto_l (\theta, \text{ss} \dots \text{module } M := K^{j'} \dots \text{end}^j) \quad K \neq (K_1^{k_1} : K_2^{k_2})}{O \vdash [lc.M, 0] \mapsto_l (\theta, K^{j'})} \quad (77)$$

$$\frac{O \vdash lc \mapsto (\theta, (\text{functor}(X : A^{j_2}) \rightarrow K^{j_3})^{j_1}) \quad K \neq (K_1^{k_1} : K_2^{k_2})}{O \vdash [lc(p), 0] \mapsto_l (\theta[X \mapsto p], K^{j_3})} \quad (78)$$

$$\frac{O \vdash lc \mapsto_l (\theta, \text{ss} \dots \text{module } M := K^{j'} \dots \text{end}^j) \quad K \equiv (\dots (K_{i+1}^{k_{i+1}} : K_i^{k_i}) \dots K_0^{k_0})}{O \vdash [lc.M, i] \mapsto_l (\theta, K_i^{k_i})} \quad (79)$$

$$\frac{O \vdash lc \mapsto_l (\theta, (\text{functor}(X : A^{j_1}) \rightarrow K^{j_2})^{j_0}) \quad K \equiv (\dots (K_{i+1}^{k_{i+1}} : K_i^{k_i}) \dots K_0^{k_0})}{O \vdash [lc(p), i] \mapsto_l (\theta[X \mapsto p], K_i^{k_i})} \quad (80)$$

$$\frac{O \vdash lc \mapsto_l (\theta, \text{ss} \dots \text{module } M := K^{j'} \dots \text{end}^j) \quad i \geq 1 \quad K \equiv (\dots (K_i^{k_i} : K_{i-1}^{k_{i-1}}) \dots K_0^{k_0}) \quad K_i \neq (J_1^{j_1} : J_2^{j_2})}{O \vdash [lc.M, i] \mapsto_l (\theta, K_i^{k_i})} \quad (81)$$

$$\frac{O \vdash lc \mapsto_l (\theta, (\text{functor}(X : A^{j_1}) \rightarrow K^{j_2})^{j_0}) \quad i \geq 1 \quad K \equiv (\dots (K_i^{k_i} : K_{i-1}^{k_{i-1}}) \dots K_0^{k_0}) \quad K_i \neq (J_1^{j_1} : J_2^{j_2})}{O \vdash [lc(p), i] \mapsto_l (\theta[X \mapsto p], K_i^{k_i})} \quad (82)$$

Figure 27: Locating path look-up with respect to O

a module path refers a module relative to the structure or (lazy) structure type to which the path's preceding self variable is ascribed.

The syntax for locating paths is:

$$lc ::= \epsilon \mid [lc.M, i] \mid [lc(p), i]$$

Let us examine each construct. The construct ϵ represents the top-level. When lc refers to a structure or (lazy) structure type containing a module binding $\text{module } M := K^j$, then $[lc.M, i]$ resolves to the module expression or (lazy) signature obtained from K by erasing K 's sealing signatures i times. Similarly, when lc refers to a functor $(\text{functor}(X : A) \rightarrow K^{j_2})^{j_1}$, then $[lc(p), i]$ resolves to the module expression obtained from K by erasing K 's sealing signatures i times. In the constructs $[lc.M, i]$ and $[lc(p), j]$, we call the integers i and j locating integers.

In Figure 27, we define *locating path look-up judgment*. The judgment $O \vdash lc \mapsto_l (\theta, K^i)$ informally means that the locating path lc refers to the module description K labeled with the integer i in the top-level O , where each module variable X bound to $\theta(X)$.


```

struct (Z(id,ε))
  module M =
    ((struct (Z1(id,[ε.M,2])) type t = int end
     : sig (Z2(id,[ε.M,1])) type t end)
     : sig (Z3(id,[ε.M,0])) end)
  module F = (functor (X:sig type t val t : X.t end) →
    struct (Z4(id,[ε.F(X),0])) module N = struct (Z5(id,[ε.F(X),N,0])) end end)
end

```

Figure 28: An example for annotations on self variables

$$\gamma(Z^{\langle\theta,lc\rangle}) = lc \quad \gamma(p.M) = [\gamma(p).M, 0] \quad \gamma(p_1(p_2)) = [\gamma(p_1)(p_2), 0]$$

Figure 29: Turning module paths into locating paths

We make the assumption that each occurrence of a self variable Z in a program P is annotated with a locating path lc in addition to an identity substitution, written $Z^{\langle id,lc \rangle}$, such that $P \vdash lc \mapsto_l (id, \rho_P(Z))$ holds. In a practical system, we provide an elaboration phase for complementing these annotations. For an explanatory purpose, we give an example of a program which reflects our assumptions on self variables in Figure 28.

For a module variable environment θ , we define $\theta(lc)$ as follows:

$$\theta(\epsilon) = \epsilon \quad \theta([lc.M, i]) = [\theta(lc).M, i] \quad \theta([lc(p), i]) = [\theta(lc)(\theta(p)), i]$$

We also define a function γ for turning extended module identifiers (i.e., module paths other than module variables) into locating paths in Figure 29. We may say that $\gamma(p)$ is the locating path of p . Note that if $O \vdash p \mapsto (\theta, K^i)$ then $O \vdash \gamma(p) \mapsto_l (\theta, K^i)$ and vice versa.

Coercible judgments Here, we define *coercible judgments* for judging whether two types are coercible.

Definition 6 *A module path p is in structure form with respect to a top-level O if and only if $O \vdash p \mapsto (\theta, \text{ss} \dots \text{end}^i)$ and, for all X in $\text{dom}(\theta)$, $\theta(X)$ is in structure form with respect to O .*

We define *coercible judgments* on types and locating paths in Figure 30 and 31, respectively. The judgment $U \vdash \tau ::> \tau'$ means that the types τ and τ' are coercible with respect to the lazy program type U ; the judgment $U \vdash lc ::>_l lc'$ reads similarly.

$$\frac{\overline{U \vdash \mathbf{1} ::> \mathbf{1}} \quad \frac{U \vdash \tau_{11} ::> \tau_{21} \quad U \vdash \tau_{12} ::> \tau_{22}}{U \vdash \tau_{11} * \tau_{12} ::> \tau_{21} * \tau_{22}} \quad \frac{U \vdash \tau_{11} ::> \tau_{21} \quad U \vdash \tau_{12} ::> \tau_{22}}{U \vdash \tau_{11} \rightarrow \tau_{12} ::> \tau_{21} \rightarrow \tau_{22}}}{\frac{p_1 \text{ and } p_2 \text{ are in structure form with respect to } U \quad U \vdash \gamma(p_1) ::>_l \gamma(p_2)}{U \vdash p_1.t ::> p_2.t}}$$

Figure 30: Convertible relation on types with respect to U

$$\frac{\overline{U \vdash \epsilon ::>_l \epsilon} \quad \overline{U \vdash X ::>_l X} \quad \frac{U \vdash lc_1 ::>_l lc_2}{U \vdash [lc_1.M, i_1] ::>_l [lc_2.M, i_2]}}{\frac{U \vdash lc_1 ::>_l lc_2 \quad U \vdash \gamma(p_1) ::>_l \gamma(p_2)}{U \vdash [lc_1(p_1), i_1] ::>_l [lc_2(p_2), i_2]}}$$

Figure 31: Convertible relation on locations with respect to U

For the expression $(e : \tau ::> \tau')$ to be type-correct, two types τ and τ' must be coercible.

The rules in Figure 30 are mostly straightforward. The last rule says that for two type paths $p_1.t$ and $p_2.t$ to be coercible they must be in structure form and their locating paths must be coercible. Figure 31 defines the coercible judgment on locating paths. Two locating paths are convertible if and only if they differ only in locating integers.

For instance, consider Figure 1. Assume that the self variable **TF** of **TreeForest** is annotated with (id, ϵ) , and that the module **Tree** declares a self variable named **T**, whose annotation would be $(id, [\epsilon.\text{Tree}, 1])$. Then the locating path of $\text{TF}^{(id, \epsilon)}.\text{Tree}$ is $[\epsilon.\text{Tree}, 0]$ and that of $\text{T}^{(id, [\epsilon.\text{Tree}, 1])}$ is $[\epsilon.\text{Tree}, 1]$. The two locating paths are coercible, hence so are the types $\text{TF}^{(id, \epsilon)}.\text{Tree.t}$ and $\text{T}^{(id, [\epsilon.\text{Tree}, 1])}.\text{t}$.

Typing rule In Figure 32, we give a typing rule for type coercion. Observe that when checking coercibility between the types τ_1 and τ_2 , the type system does not expand them.

For conciseness, we usually do not write locating path annotations of self variables.

$$\frac{U \vdash \tau_1 \diamond \quad U \vdash \tau_2 \diamond \quad U, \Gamma \vdash e : \tau \quad U \vdash \tau_1 \equiv \tau \quad U \vdash \tau_1 ::> \tau_2 \quad \text{TypExp}(U, \tau_2) = \tau'_2}{U, \Gamma \vdash (e : \tau_1 ::> \tau_2) : \tau'_2} \quad (83)$$

Figure 32: Typing rule for the type coercion with respect to U

$$\begin{array}{c}
\frac{P \vdash p \rightsquigarrow_n p'}{P \vdash p.M \rightsquigarrow_n p'.M} \qquad \frac{P \vdash p \rightsquigarrow_n p'}{P \vdash p(q) \rightsquigarrow_n p'(q)} \\
\frac{P \vdash q \rightsquigarrow_n q'}{P \vdash p(q) \rightsquigarrow_n p(q')} \qquad \frac{P \vdash p \mapsto_d (\theta, q^i)}{P \vdash p \rightsquigarrow_n \theta(q)}
\end{array}$$

Figure 33: Normalization of module paths with respect to P

8 Soundness

In this section, we present a call-by-value operational semantics and prove a soundness result.

First we define the *normalization* of module paths in Figure 33. The judgment $P \vdash p \rightsquigarrow_n q$ means that p reduces into q in one step, with respect to the program P . The normalization traces module abbreviations in the intuitive way, and is defined for module paths containing no module variables.

During normalization and reductions to be defined below, we use *implementation look-up judgment* instead of the look-up judgment (Figure 7), to look up concrete modules from a program. The judgment is defined in Figure 34, with an auxiliary in Figure 35.

Values v and evaluation contexts E are:

$$\begin{array}{l}
v ::= () \mid (v_1, v_2) \mid p.c \ v \mid (\lambda x.e : \tau) \\
E ::= \{\} \mid (E, e) \mid (v, E) \mid \pi_i(E) \mid E(e) \mid v(E) \mid p.c \ E \\
\quad \mid \text{case } E \text{ of } ms \mid (E : \tau_1 : \tau_2)
\end{array}$$

where p does not contain module variables.

Then a small step reduction is either:

$$\begin{array}{l}
p.l \xrightarrow{\text{mp}} p'.l \quad \text{when } P \vdash p \rightsquigarrow_n p' \quad \pi_i(v_1, v_2) \xrightarrow{\text{prj}} v_i \quad (v : \tau_1 : \tau_2) \xrightarrow{\text{convt}} v \\
(\lambda x.e : \tau) v \xrightarrow{\text{fun}} [x \mapsto v]e \quad \text{case } p.c \ v \text{ of } q.c \ x \Rightarrow e \xrightarrow{\text{case}} [x \mapsto v]e \\
p.l \xrightarrow{\text{vpth}} \theta(e) \quad \text{when } P \vdash p \mapsto_d (\theta, \text{struct } \dots \text{val } l = e \dots \text{end}^i)
\end{array}$$

or an inner reduction obtained by induction:

$$\frac{e_1 \rightarrow e_2 \quad E \neq \{\}}{E\{e_1\} \rightarrow E\{e_2\}}$$

Again, these reductions are defined with respect to a program P .

When deconstructing a value through the case expression **case** $p.c \ v$ **of** $q.c \ x$, we do not explicitly check that p and q are equivalent. The type system already ensures that p and q expand into equivalent module paths.

$$\begin{array}{c}
\frac{}{P \vdash Z^\theta \mapsto_d (\theta, \rho_P(Z))} \\
\frac{P \vdash p \mapsto_d (\theta, \mathbf{struct} \dots \mathbf{module} M = E \dots \mathbf{end}^i)}{P \vdash p.M \mapsto_d (\theta, \mathit{erase}(E))} \\
\frac{P \vdash p_1 \mapsto_d (\theta, (\mathbf{functor}(X : A) \rightarrow E)^i)}{P \vdash p_1(p_2) \mapsto_d (\theta[X \mapsto p_2], \mathit{erase}(E))}
\end{array}$$

Figure 34: Implementation look-up

$$\mathit{erase}((E : S)^i) = \mathit{erase}(E) \qquad \mathit{erase}(E) = E \text{ otherwise}$$

Figure 35: Sealing erasure

We assume that the top-level structure of every program P contains a value component named `main`. The evaluation of P begins by reducing the defining expression of `main`.

Proposition 6 (Soundness) *Let a program P be well-typed. Then the evaluation of P either returns a value or else gives rise to an infinite reduction sequence.*

8.1 Proof of the soundness

Our proof of Proposition 6 proceeds in the following three steps.

1. We define a type system $\mathit{TraviataY}$, which uses the intuitive expansion algorithms for expanding module paths and types. We prove that when a program P is type-correct in $\mathit{Traviata}$, then it is type-correct in $\mathit{TraviataY}$.
2. We define a type system $\mathit{TraviataX}$, whose type equivalence relation is defined by the weak bisimulation relation on a labeled transition system on types. We establish a soundness result for $\mathit{TraviataX}$, by proving progress and subject reduction properties.
3. We prove that if P is type-correct in $\mathit{TraviataY}$, then it is type-correct in $\mathit{TraviataX}$.

The purpose of the use of locks Σ , Ω and Ψ during expansions (Figure 9 and 11) and core type reconstruction (Figure 12) is for the decidability result. In the soundness proof, we are interested in a derivation tree which proves well-typedness of P but not in how we can construct the tree. Hence, in the proofs below, we use judgments

of the ground normalization, the type expansion and the core type reconstruction that do not hold locks. For instance, we may say that “ $U \vdash p \rightsquigarrow_g q$ holds”, when $U, \Sigma \vdash p \rightsquigarrow_g q$ can be proven for some Σ by the inference rules that are completely same as the rules in Figure 9 but do not have locks. (It is clear that whether or not the inference rules use locks does not affect outputs of the ground normalization; the ground normalization without locks may diverge and the ground normalization with locks may raise more errors than without.)

In the rest of this section, we only consider programs that are well-typed in *Traviata*, that is, programs P such that $ReconstP(P) = U_P$ and $U_P \vdash P : U_P$ hold. In particular, we do not explicitly include this premise when stating lemmas. Recall that all core types appearing in U_P are located types. This is important for proving Lemma 2. We also assume that all module paths, types and core expressions have located variables. Again, we do not include this premise when stating lemmas and propositions.

8.1.1 The type system *TraviataY*

TraviataY does not have a lazy program type reconstruction algorithm; it checks that P is type-correct with respect to a given U_P . *TraviataY* differs from *Traviata* in that it expands module paths and types in the intuitive way.

We define the module path expansion algorithm and the type expansion algorithm that *TraviataY* uses in Figure 36 and Figure 37, respectively. In Figure 39, we present typing rules for *TraviataY*, with auxiliaries found in Figure 41, 42 and 43. The typing rules are same as those for *Traviata*, except for the expansion algorithms.

Lemma 1 ([20]) *If $PathExp(U_P, p) = q$, then $U_P \vdash_Y p \rightsquigarrow q$.*

Lemma 2 *If $U_P \vdash \tau \downarrow \tau'$, then $U_P \vdash_Y \tau \downarrow \tau'$.*

Proposition 7 *Suppose $ReconstP(P) = U_P$ and $U_P \vdash P : U_P$, then $U_P \vdash_Y P : U_P$.*

Proof. By Lemma 1 and 2. □

In the rest of proofs, we assume that $ReconstP(P) = U_P$ and $U_P \vdash_Y P : U_P$ hold. In particular, we do not explicitly include this premise when stating lemmas.

For the purpose of proofs, we strengthen the inference rules of well-formedness of module paths (Figure 42), by replacing the rule for self variables with the rule:

$$\frac{U \vdash_Y \theta \text{ wf}}{U \vdash_Y Z^\theta \text{ wf}}$$

where $U \vdash_Y \theta \text{ wf}$ is defined as follows.

Definition 7 A module variable environment θ is well-formed with respect to U in *TraviataY*, written $U \vdash_Y \theta$ wf, if and only if, for all $X \in \text{dom}(\theta)$, $U \vdash_Y \theta(X)$ wf and $U \vdash_Y \theta(X) < \theta(\rho_U(X))$.

Lemma 3 Let θ be in located form and $O \vdash_Y p \rightsquigarrow q$, then $O \vdash_Y \theta(p) \rightsquigarrow \theta(q)$.

Lemma 4 Let θ_1 and θ_2 be module variable environments such that $\text{dom}(\theta_1) = \text{dom}(\theta_2)$ and for all $X \in \text{dom}(\theta)$ $O \vdash_Y \theta_1(X) \rightsquigarrow \theta_2(X)$. If $O \vdash_Y p \rightsquigarrow q$, then $O \vdash_Y \theta_1(p) \rightsquigarrow \theta_2(q)$.

Lemma 5 Suppose $U_P \vdash_Y \theta$ wf and $U_P \vdash_Y p$ wf, then $U_P \vdash_Y \theta(p)$ wf.

Lemma 6 Suppose $U_P \vdash_Y \theta$ wf and $U_P \vdash_Y \tau \diamond$, then $U_P \vdash_Y \theta(\tau) \diamond$.

Lemma 7 Suppose $U_P \vdash_Y \theta$ wf and $U_P, \Gamma \vdash_Y e : \tau$. Then $U_P, \Gamma_1 \vdash_Y \theta(e) : \tau'$ with $U_P \vdash_Y \theta(\tau) \equiv \tau'$, where $\text{dom}(\Gamma) = \text{dom}(\Gamma_1)$ and, for all x in $\text{dom}(\Gamma_1)$, $U_P \vdash_Y \theta(\Gamma(x)) \equiv \Gamma_1(x)$.

8.1.2 The type system *TraviataX*

Before presenting *TraviataX*, we build a lazy program type U_P^\sharp from U_P by making all abstract type specifications except for those appearing in module variable signatures transparent. We define a function *Trans* in Figure 44, which builds U_P^\sharp from U_P . We let U_P^\sharp be *Trans*(U_P). Note that bound self variables may escape their scope in U_P^\sharp .

TraviataX differs from *TraviataY* in that a type equivalence relation of *TraviataX* is defined by the weak bisimulation relation on a labeled transition system on types.

We define labeled transition systems on module paths and types in Figure 46 and 47, respectively. Note that, in U_P^\sharp , abstract type specifications may only appear in module variable signatures.

We write $U \vdash \tau \xrightarrow{\mathcal{C}} \tau'$ to mean $U \vdash \tau \Rightarrow \xrightarrow{\mathcal{C}} \Rightarrow \tau'$, where \Rightarrow is the reflective transitive closure of $\xrightarrow{\mathcal{C}}$. (We use juxtaposition to denote relation composition.)

Definition 8 ([18]) Let \mathcal{R} be a binary relation on types. Then \mathcal{R} is a weak simulation with respect to a lazy program type U if, whenever $\tau_1 \mathcal{R} \tau_2$,

1. if $U \vdash \tau_1 \xrightarrow{\mathcal{T}} \tau'_1$ then there exists τ'_2 such that $U \vdash \tau_2 \Rightarrow \tau'_2$ and $\tau'_1 \mathcal{R} \tau'_2$.
2. if $U \vdash \tau_1 \xrightarrow{\mathcal{C}} \tau'_1$ then there exists τ'_2 such that $U \vdash \tau_2 \xrightarrow{\mathcal{C}} \tau'_2$ and $\tau'_1 \mathcal{R} \tau'_2$.

Definition 9 ([18]) *A binary relation \mathcal{R} on types is said to be a weak bisimulation with respect to a lazy program type U if both \mathcal{R} and its converse are weak simulations with respect to U . We say that τ and τ' are weakly bisimilar with respect to U , written $U \vdash \tau \approx \tau'$, if there exists a weak bisimulation \mathcal{R} with respect to U such that $\tau \mathcal{R} \tau'$.*

Again, we usually write $\tau \approx \tau'$ to denote $U_P^\sharp \vdash \tau \approx \tau'$.

Lemma 8 ([18]) *The relation \approx is a weak bisimulation.*

We present typing rules for *TraviataX* in Figure 49, with auxiliaries in Figure 50, 51 and 52.

Definition 10 *A program P is type-correct with respect to U in *TraviataX* if and only if $U \vdash_X P : U$ holds.*

For the purpose of proofs, we strengthen the inference rules of well-formedness of module paths (Figure 51), by replacing the rule for self variables with the rule:

$$\frac{U \vdash_X \theta \text{ wf}}{U \vdash_X Z^\theta \text{ wf}}$$

where $U \vdash_X \theta \text{ wf}$ is defined as follows.

Definition 11 *A module variable environment θ is well-formed with respect to a lazy program type U in *TraviataX*, written $U \vdash_X \theta \text{ wf}$, if and only if, for all $X \in \text{dom}(\theta)$, $U \vdash_X \theta(X) \text{ wf}$ and $U \vdash_X \theta(X) < \theta(\rho_U(X))$.*

Definition 12 *For types τ and τ' , we write $U \vdash \tau \overset{\tau^*}{\leftrightarrow} \tau'$ when (τ, τ') is an element of the smallest transitive and symmetric relation containing $\{(\tau, \tau') \mid U \vdash \tau \overset{\tau}{\rightarrow} \tau'\}$.*

Lemma 9 *If $U_P^\sharp \vdash \tau \overset{\tau}{\rightarrow} \tau_1$ and either $U_P^\sharp \vdash \tau \overset{\tau}{\rightarrow} \tau'$ or $U_P^\sharp \vdash \tau' \overset{\tau}{\rightarrow} \tau$, then $U_P^\sharp \vdash \tau' \overset{\tau}{\rightarrow} \tau_2$ and $U_P^\sharp \vdash \tau_1 \overset{\tau^*}{\leftrightarrow} \tau_2$.*

Lemma 10 *If $U_P^\sharp \vdash \tau_0 \overset{\tau}{\rightarrow} \tau_1$ and $U_P^\sharp \vdash \tau_0 \overset{\tau}{\rightarrow} \tau_2$, then $U_P^\sharp \vdash \tau_1 \overset{\tau}{\rightarrow} \tau_3$ and $U_P^\sharp \vdash \tau_2 \overset{\tau^*}{\leftrightarrow} \tau_3$.*

Lemma 11 *If $U_P^\sharp \vdash \tau \overset{\tau^*}{\leftrightarrow} \tau'$ and $U_P^\sharp \vdash \tau \overset{\tau}{\rightarrow} \tau_1$, then $U_P^\sharp \vdash \tau' \overset{\tau}{\rightarrow} \tau_2$ and $U_P^\sharp \vdash \tau_1 \overset{\tau^*}{\leftrightarrow} \tau_2$.*

The following lemma is important; it says that τ -transitions preserve bisimilarity. In particular, using this lemma we prove Lemma 16.

Lemma 12 *If $U_P^\sharp \vdash \tau \stackrel{\tau}{\sim} \tau'$, then $U_P^\sharp \vdash \tau \approx \tau'$.*

Proof. Prove and use Lemmas 9 to 11. □

Lemma 13 *If $U_P \vdash_Y p \rightsquigarrow p'$, then $U_P^\sharp \vdash p \Rightarrow p'$.*

Lemma 14 *If $U_P \vdash_Y \tau \downarrow \tau'$, then $U_P^\sharp \vdash \tau \approx \tau'$.*

Lemma 15 *If $U_P \vdash \tau \equiv_\tau \tau'$, then $U_P^\sharp \vdash \tau \approx \tau'$.*

The following lemma is important; it says that type equivalence in *TraviataY* implies that in *TraviataX*.

Lemma 16 *If $U_P \vdash_Y \tau \equiv \tau'$, then $U_P^\sharp \vdash \tau \approx \tau'$.*

Lemma 17 *If $U_P \vdash_Y p$ wf and $U_P^\sharp \vdash p \stackrel{\tau}{\sim} p'$, then $U_P \vdash_Y p'$ wf.*

Proof. Use Lemma 5. □

Lemma 18 *If $U_P \vdash_Y \tau \diamond$ and $U_P \vdash \tau \stackrel{\tau}{\sim} \tau'$, then $U_P \vdash_Y \tau' \diamond$.*

Proof. Use Lemma 6. □

Lemma 19 *If $U_P^\sharp, \Gamma \vdash_X e : \tau_1$ and $U_P^\sharp, \Gamma \vdash_X e : \tau_2$, then $U_P^\sharp \vdash \tau_1 \approx \tau_2$.*

Lemma 20 *Let a relation \mathcal{R} on types be defined as:*

$$\mathcal{R} \stackrel{\text{def}}{=} \{(\theta(\tau), \theta(\tau')) \mid U_P \vdash_Y \theta \text{ wf and } U_P^\sharp \vdash \tau \approx \tau'\}$$

If $(\tau, \tau') \in \mathcal{R}$, then $U_P^\sharp \vdash \tau \approx \tau'$.

Lemma 21 *If $U_P \vdash_Y p$ wf, then $U_P^\sharp \vdash_X p$ wf.*

Proof. Use Lemma 20. □

Lemma 22 *If $U_P \vdash_Y \tau \diamond$, then $U_P^\sharp \vdash_X \tau \diamond$.*

Proof. Use Lemma 21. □

Lemma 23 Let $U_P^\sharp \vdash_X \theta$ wf and θ is in located form. Let a relation \mathcal{R} on types be defined as:

$$\mathcal{R} \stackrel{def}{=} \{(\theta(\tau), \theta(\tau')) \mid U_P^\sharp \vdash \tau \approx \tau'\}$$

If $(\tau, \tau') \in \mathcal{R}$, then $U_P^\sharp \vdash \tau \approx \tau'$.

Lemma 24 If $U_P^\sharp \vdash_X \theta$ wf and θ is in located form and $U_P^\sharp \vdash_X p$ wf, then $U_P^\sharp \vdash_X \theta(p)$ wf.

Lemma 25 Let $U_P^\sharp \vdash_X p$ wf and $U_P^\sharp \vdash_Y p \rightsquigarrow q$, then $U_P^\sharp \vdash_X q$ wf.

Lemma 26 Let $U_P^\sharp \vdash_X \theta$ wf and $U_P^\sharp \vdash_X p$ wf, then $U_P^\sharp \vdash_X \theta(p)$ wf.

Lemma 27 Let $U_P^\sharp \vdash_X p$ wf and $U_P^\sharp \vdash p \overset{\tau}{\sim} p'$, then $U_P^\sharp \vdash_X p'$ wf.

Lemma 28 Let a relation \mathcal{R} on types be defined as:

$$\mathcal{R} \stackrel{def}{=} \{(\theta(\tau), \theta(\tau')) \mid U_P^\sharp \vdash_X \theta \text{ wf and } U_P^\sharp \vdash \tau \approx \tau'\}$$

If $(\tau, \tau') \in \mathcal{R}$, then $U_P^\sharp \vdash \tau \approx \tau'$.

Lemma 29 Let $U_P^\sharp \vdash_X \theta$ wf and $U_P^\sharp, \Gamma \vdash_X e : \tau$, then $U_P^\sharp, \Gamma_1 \vdash_X \theta(e) : \theta(\tau)$, where $\text{dom}(\Gamma) = \text{dom}(\Gamma_1)$, and for all $x \in \text{dom}(\Gamma)$ $U_P^\sharp \vdash \Gamma_1(x) \approx \theta(\Gamma(x))$.

We build a mapping from self variables to module paths, using functions defined in Figure 45. We let \mathcal{S} be $\text{SelfMap}(U_P)$. Intuitively, \mathcal{S} corrects substitutions of module paths for self variables which are performed by TraviataY during type checking of P for ensuring that sealing expressions $(E : S)$ are type-correct.

For a type τ , we write $\tau^{\mathcal{S}}$ to denote the set of types obtained from τ by replacing some occurrences of Z^θ in τ with $\theta(\mathcal{S}(Z))$. We use τ^s , τ^{s_1} , τ^{s_2} and the likes as metavariables for elements of $\tau^{\mathcal{S}}$. We also write $p^{\mathcal{S}}$ and p^s with obvious meanings.

Observe that, for all $Z \in \text{dom}(\mathcal{S})$, we have $U_P^\sharp \vdash_X \mathcal{S}(Z) < T_d$, where $U_P^\sharp \vdash Z^{id} \mapsto (id, T_d^i)$.

We define a binary relation $\approx_{\mathcal{S}}$ on types as follows:

$$\approx_{\mathcal{S}} = \{(\tau, \tau^s) \mid U_P^\sharp \vdash_X \tau \text{ wf and } \tau^s \in \tau^{\mathcal{S}}\}.$$

Lemma 30 If $U_P^\sharp \vdash \tau \approx_{\mathcal{S}} \tau'$ then $U_P^\sharp \vdash \tau \approx \tau'$.

Lemma 31 *If $U_P^\# \vdash_X \tau \diamond$ and $U_P^\# \vdash_X \tau' \diamond$ and $U_P^\# \vdash \tau ::> \tau'$, then $U_P^\# \vdash \tau \approx \tau'$.*

Lemma 32 *If $U_P, \Gamma \vdash_Y e : \tau$, then $U_P^\#, \Gamma \vdash_X e : \tau$.*

Proposition 8 *Assume $\text{Reconst}P(P) = U_P$ and $U_P \vdash_Y P : U_P$ and $\text{Trans}(U_P) = U_P^\#$, then $U_P^\# \vdash_X P : U_P^\#$.*

Proposition 9 (Subject reduction in TraviataX) *Assume $\text{Reconst}P(P) = U_P$ and $U_P \vdash_Y P : U_P$ and $\text{Trans}(U_P) = U_P^\#$, and $U_P^\# \vdash_X P : U_P^\#$. If $U_P^\#, \emptyset \vdash_X e : \tau_1$ and $e \rightarrow e'$, then $U_P^\#, \emptyset \vdash_X e' : \tau_1$.*

Definition 13 *A type τ is stable with respect to a lazy program type U if and only if, for all τ' in $\text{comps}(\tau)$, τ' is a type path $p.t$ where p does not contain module variables and $U_P^\# \vdash p \mapsto (\theta, \text{sig} \dots \text{datatype } t = c \text{ of } \tau'' \dots \text{end}^i)$ holds.*

The function *comps* on types is defined as follows:

$$\text{comps}(\tau) = \begin{cases} \emptyset & \tau = \tau_1 \rightarrow \tau_2 \text{ or } \tau = \mathbf{1} \\ \text{comps}(\tau_1) \cup \text{comps}(\tau_2) & \tau = \tau_1 * \tau_2 \\ \{p.t\} & \tau = p.t \end{cases}$$

Lemma 33 *If $U_P^\#, \emptyset \vdash_X v : \tau$, then there is a stable type τ' with respect to $U_P^\#$ such that $U_P^\#, \emptyset \vdash_X v : \tau'$.*

Lemma 34

1. *There are no types τ_1, τ_2 such that either $U_P^\#, \Gamma \vdash_X () : \tau_1 * \tau_2$ or $U_P^\#, \Gamma \vdash_X () : \tau_1 \rightarrow \tau_2$ holds.*
2. *There is not a stable type $p.t$ such that $U_P^\#, \Gamma \vdash_X () : p.t$.*
3. *If $U_P^\#, \Gamma \vdash_X (v_1, v_2) : \tau$, then there are no types τ_1, τ_2 such that $U_P^\#, \Gamma \vdash_X (v_1, v_2) : \tau_1 \rightarrow \tau_2$.*
4. *If $U_P^\#, \Gamma \vdash_X (v_1, v_2) : \tau$, then $U_P^\#, \Gamma \vdash_X (v_1, v_2) : \mathbf{1}$ does not hold.*
5. *If $U_P^\#, \Gamma \vdash_X (v_1, v_2) : \tau$, then there is no stable type $p.t$ such that $U_P^\#, \Gamma \vdash_X (v_1, v_2) : p.t$.*
6. *If $U_P^\#, \Gamma \vdash_X (\lambda x.e : \tau) : \tau'$, then there are no types τ_1, τ_2 such that $U_P^\#, \Gamma \vdash_X (\lambda x.e : \tau) : \tau_1 * \tau_2$.*

7. If $U_P^\sharp, \Gamma \vdash_X (\lambda x.e : \tau) : \tau'$, then $U_P^\sharp, \Gamma \vdash_X (\lambda x.e : \tau) : \mathbf{1}$ does not hold.
8. If $U_P^\sharp, \Gamma \vdash_X (\lambda x.e : \tau) : \tau'$, then there is no stable type $p.t$ such that $U_P^\sharp, \Gamma \vdash_X (\lambda x.e : \tau) : p.t$.
9. If $U_P^\sharp, \Gamma \vdash_X p.c v : \tau$, then there are no types τ_1, τ_2 such that either $U_P^\sharp, \Gamma \vdash_X p.c v : \tau_1 \rightarrow \tau_2$ or $U_P^\sharp, \Gamma \vdash_X p.c v : \tau_1 * \tau_2$ holds.
10. If $U_P^\sharp, \Gamma \vdash_X p.c v : \tau$, then $U_P^\sharp, \Gamma \vdash_X p.c v : \mathbf{1}$ does not hold.

Proposition 10 (Progress in TraviataX) *Assume $\text{Reconst}P(P) = U_P$ and $U_P \vdash_Y P : U_P$ and $\text{Trans}(U_P) = U_P^\sharp$, and $U_P^\sharp \vdash_X P : U_P^\sharp$. If $U_P^\sharp, \emptyset \vdash_X e : \tau$ then either e is a value or else there is some e' with $e \rightarrow e'$ with respect to P .*

$$\begin{array}{c}
\overline{O \vdash_Y X \rightsquigarrow X} \\
\frac{O \vdash_Y p \rightsquigarrow p'}{O \vdash p'.M \mapsto (\theta, K^i) \quad K \neq q} \\
\frac{O \vdash_Y p \rightsquigarrow p'}{O \vdash_Y p.M \rightsquigarrow p'.M} \\
\frac{O \vdash_Y p_1 \rightsquigarrow p'_1 \quad O \vdash_Y p_2 \rightsquigarrow p'_2}{O \vdash p'_1(p'_2) \mapsto (\theta, K^i) \quad K \neq q} \\
\frac{O \vdash_Y p_1(p_2) \rightsquigarrow p'_1(p'_2)}{O \vdash_Y p_1(p_2) \rightsquigarrow p'_1(p'_2)}
\end{array}
\qquad
\begin{array}{c}
\overline{O \vdash_Y Z^\theta \rightsquigarrow Z^\theta} \\
\frac{O \vdash_Y p \rightsquigarrow p'}{O \vdash p'.M \mapsto (\theta, q^i) \quad O \vdash_Y \theta(q) \rightsquigarrow r} \\
\frac{O \vdash_Y p \rightsquigarrow p'}{O \vdash_Y p.M \rightsquigarrow r} \\
\frac{O \vdash_Y p_1 \rightsquigarrow p'_1 \quad O \vdash_Y p_2 \rightsquigarrow p'_2}{O \vdash p'_1(p'_2) \mapsto (\theta, q^i) \quad O \vdash_Y \theta(q) \rightsquigarrow r} \\
\frac{O \vdash_Y p_1(p_2) \rightsquigarrow r}{O \vdash_Y p_1(p_2) \rightsquigarrow r}
\end{array}$$

Figure 36: Module path expansion with respect to O in *TraviataY*

$$\begin{array}{c}
\text{[uni]} \\
\frac{U \vdash_Y \mathbf{1} \downarrow \mathbf{1}}{U \vdash_Y \tau_1 \downarrow \tau'_1 \quad U \vdash_Y \tau_2 \downarrow \tau'_2} \\
\text{[arr]} \\
\frac{U \vdash_Y \tau_1 \downarrow \tau'_1 \quad U \vdash_Y \tau_2 \downarrow \tau'_2}{U \vdash_Y \tau_1 \rightarrow \tau_2 \downarrow \tau'_1 \rightarrow \tau'_2} \\
\text{[pair]} \\
\frac{U \vdash_Y \tau_1 \downarrow \tau'_1 \quad U \vdash_Y \tau_2 \downarrow \tau'_2}{U \vdash_Y \tau_1 * \tau_2 \downarrow \tau'_1 * \tau'_2} \\
\text{[dtyp]} \\
\frac{U \vdash_Y p \rightsquigarrow p' \quad U \vdash p'.t \mapsto (\theta, \text{sig} \dots \text{datatype } t = c \text{ of } \tau \dots \text{end}^i)}{U \vdash_Y p.t \downarrow p'.t} \\
\text{[opq]} \\
\frac{U \vdash_Y p \rightsquigarrow p' \quad U \vdash p'.t \mapsto (\theta, \text{sig} \dots \text{type } t \dots \text{end}^i)}{U \vdash_Y p.t \downarrow p'.t} \\
\text{[typ]} \\
\frac{U \vdash_Y p \rightsquigarrow p' \quad U \vdash p'.t \mapsto (\theta, \text{sig} \dots \text{type } t = \tau_1 \dots \text{end}^i) \quad U \vdash_Y \theta(\tau_1) \downarrow \tau}{U \vdash_Y p.t \downarrow \tau}
\end{array}$$

Figure 37: Type expansion with respect to U in *TraviataY*

$$\frac{U \vdash_Y \tau_1 \downarrow \tau'_1 \quad U \vdash_Y \tau_2 \downarrow \tau'_2 \quad U \vdash \tau'_1 \equiv_\tau \tau'_2}{U \vdash_Y \tau_1 \equiv \tau_2}$$

Figure 38: Type equivalence with respect to U in *TraviataY*

Definitions and Specifications

$$\frac{U \vdash_Y E : T}{U \vdash_Y \text{module } M = E : \text{module } M : T} \quad \frac{U \vdash_Y S : T}{U \vdash_Y \text{module } M : S : \text{module } M : T}$$

$$\frac{U \vdash_Y \tau_1 \diamond \quad U \vdash_Y \tau_1 \downarrow \tau_2}{U \vdash_Y \text{datatype } t = c \text{ of } \tau_1 : \text{datatype } t = c \text{ of } \tau_2}$$

$$\frac{U \vdash_Y \tau_1 \diamond \quad U \vdash_Y \tau_1 \downarrow \tau_2}{U \vdash_Y \text{type } t = \tau_1 : \text{type } t = \tau_2} \quad \frac{}{U \vdash_Y \text{type } t : \text{type } t}$$

$$\frac{U, \emptyset \vdash_Y e : \tau}{U \vdash_Y \text{val } l = e : \text{val } l : \tau} \quad \frac{U \vdash_Y \tau_1 \diamond \quad U \vdash_Y \tau_1 \downarrow \tau_2}{U \vdash_Y \text{val } l : \tau_1 : \text{val } l : \tau_2}$$

Module expression

$$\frac{U \vdash_Y E_d : T_d}{U \vdash_Y E_d^i : T_d^i}$$

Module expression descriptions

$$\frac{U \vdash_Y D_1 : C_1 \dots U \vdash_Y D_n : C_n}{U \vdash_Y \text{struct } (Z) D_1 \dots D_n \text{ end} : \text{sig } (Z) C_1 \dots C_n \text{ end}}$$

$$\frac{U \vdash_Y A : A' \quad U \vdash_Y E : T}{U \vdash_Y \text{functor}(X : A) \rightarrow E : \text{functor}(X : A') \rightarrow T}$$

$$\frac{U \vdash_Y E : T_1 \quad U \vdash_Y S : T_2 \quad U \vdash_Y T_1 < \text{Subst}(T_1, S)}{U \vdash_Y (E : S) : (T_1 : T_2)} \quad \frac{U \vdash_Y p \text{ wf}}{U \vdash_Y p : p}$$

Signature

$$\frac{U \vdash_Y S_d : T_d}{U \vdash_Y S_d^i : T_d^i}$$

Signature descriptions

$$\frac{U \vdash_Y B_1 : C_1 \dots U \vdash_Y B_n : C_n}{U \vdash_Y \text{sig } (Z) B_1 \dots B_n \text{ end} : \text{sig } (Z) C_1 \dots C_n \text{ end}}$$

$$\frac{U \vdash_Y A : A' \quad U \vdash_Y S : T}{U \vdash_Y \text{functor}(X : A) \rightarrow S : \text{functor}(X : A') \rightarrow T}$$

Module variable signature

$$\frac{U \vdash_Y A_{d1} : A_{d2}}{U \vdash_Y A_{d1}^i : A_{d2}^i}$$

Module variable signature description

$$\frac{U \vdash_Y B_1 : B'_1 \dots U \vdash_Y B_n : B'_n}{U \vdash_Y \text{sig } B_1 \dots B_n \text{ end} : \text{sig } B'_1 \dots B'_n \text{ end}}$$

Figure 39: Typing rules for the module language with respect to U in *TraviataY*

Core types

$$\frac{}{U \vdash_Y \mathbf{1} \diamond} \quad \frac{U \vdash_Y \tau_1 \diamond \quad U \vdash_Y \tau_2 \diamond}{U \vdash_Y \tau_1 \rightarrow \tau_2 \diamond}$$

$$\frac{U \vdash_Y \tau_1 \diamond \quad U \vdash_Y \tau_2 \diamond}{U \vdash_Y \tau_1 * \tau_2 \diamond} \quad \frac{U_P \vdash_Y p \text{ wf} \quad U \vdash_Y p.t \downarrow \tau}{U \vdash_Y p.t \diamond}$$

Core expressions

$$\frac{}{U, \Gamma \vdash_Y () : \mathbf{1}} \quad \frac{x \in \text{dom}(\Gamma)}{U, \Gamma \vdash_Y x : \Gamma(x)}$$

$$\frac{U \vdash_Y \tau_1 \downarrow \tau_2 \rightarrow \tau_3 \quad U \vdash_Y \tau_1 \diamond \quad U, \Gamma, x : \tau_2 \vdash_Y e : \tau_4 \quad U \vdash_Y \tau_4 \equiv \tau_3}{U, \Gamma \vdash_Y (\lambda x. e : \tau_1) : \tau_2 \rightarrow \tau_3}$$

$$\frac{U, \Gamma \vdash_Y e_1 : \tau_1 \quad U, \Gamma \vdash_Y e_2 : \tau_2}{U, \Gamma \vdash_Y (e_1, e_2) : \tau_1 * \tau_2} \quad \frac{U, \Gamma \vdash_Y e : \tau_1 * \tau_2}{U, \Gamma \vdash_Y \pi_i(e) : \tau_i}$$

$$\frac{U, \Gamma \vdash_Y e_1 : \tau_1 \rightarrow \tau \quad U, \Gamma \vdash_Y e_2 : \tau'_1 \quad U \vdash_Y \tau_1 \equiv \tau'_1}{U, \Gamma \vdash_Y e_1 (e_2) : \tau}$$

$$\frac{U \vdash_Y p \rightsquigarrow p' \quad \gamma_Y(U, p', c) = (t, \tau_1) \quad U, \Gamma \vdash_Y e : \tau_2 \quad U \vdash_Y \tau_1 \equiv \tau_2}{U, \Gamma \vdash_Y p.c \ e : p'.t}$$

$$\frac{U, \Gamma \vdash_Y e_1 : \tau_1 \quad U \vdash_Y p \text{ wf} \quad U \vdash_Y p \rightsquigarrow p' \quad \gamma_Y(U, p', c) = (t, \tau_2) \quad U \vdash_Y \tau_1 \equiv p'.t \quad U, \Gamma, x : \tau_2 \vdash_Y e_2 : \tau}{U, \Gamma \vdash_Y \text{case } e_1 \text{ of } p.c \ x \Rightarrow e_2 : \tau}$$

$$\frac{U \vdash_Y p \text{ wf} \quad U \vdash_Y p \rightsquigarrow p' \quad U \vdash p' \mapsto (\theta, \text{sig} \dots \text{val } l : \tau' \dots \text{end}^i) \quad U \vdash_Y \theta(\tau') \downarrow \tau}{U, \Gamma \vdash_Y p.l : \tau}$$

$$\frac{U \vdash_Y \tau_1 \diamond \quad U \vdash_Y \tau_2 \diamond \quad U \vdash_Y \tau_2 \downarrow \tau \quad \tau_1 \vdash \tau_2 :: > \quad U, \Gamma \vdash_Y e : \tau_3 \quad U \vdash \tau_1 \equiv \tau_3}{U, \Gamma \vdash_Y (e : \tau_1 :: \tau_2) : \tau}$$

Figure 40: Typing rules for the core language with respect to U in *TraviataY*

$$\gamma_Y(U, p, c) = (t, \tau) \text{ when}$$

$$U \vdash p \mapsto (\theta, \text{sig} \dots \text{datatype } t = c \text{ of } \tau' \dots \text{end}^i) \text{ and } U \vdash_Y \theta(\tau') \downarrow \tau$$

Figure 41: Datatype look-up with respect to U in *TraviataY*

$$\begin{array}{c}
\overline{U \vdash_Y X \text{ wf}} \quad \overline{U \vdash_Y Z^{id} \text{ wf}} \quad \frac{U \vdash_Y p.M \rightsquigarrow q \quad U \vdash_Y p \text{ wf}}{U \vdash_Y p.M \text{ wf}} \\
\frac{U \vdash_Y p_1 \text{ wf} \quad U \vdash_Y p_2 \text{ wf} \quad U \vdash_Y p_1 \rightsquigarrow p'_1 \quad U \vdash_Y p_2 \rightsquigarrow p'_2 \quad U \vdash_Y p_1(p_2) \rightsquigarrow q \quad U \vdash p'_1 \mapsto (\theta, (\text{functor } (X : A_d^j) \rightarrow T)^i) \quad U \vdash_Y p'_2 < \theta[X \mapsto p'_2](A_d)}{U \vdash_Y p_1(p_2) \text{ wf}}
\end{array}$$

Figure 42: Well-formed module paths with respect to U in *TraviataY*

$$\begin{array}{c}
\frac{U \vdash_Y T_d < S_d \quad U \vdash_Y T_d < A_d}{U \vdash_Y T_d^i < S_d^j \quad U \vdash_Y T_d^i < A_d^j} \\
\frac{U \vdash_Y T_d < S_d}{U \vdash_Y (T : T_d^i) < S_d} \\
\frac{U \vdash_Y p \rightsquigarrow p' \quad U \vdash p' \mapsto (\theta, T_d^i) \quad U \vdash_Y \theta(T_d) < S_d}{U \vdash_Y p < S_d} \\
\frac{\sigma : \{1, \dots, m\} \mapsto \{1, \dots, n\} \quad \forall i \in \{1, \dots, m\}, U \vdash_Y C_{\sigma(i)} < B_i}{U \vdash_Y \text{sig } (Z) C_1 \dots C_n \text{ end} < \text{sig } (Z') B_1 \dots B_m \text{ end}} \\
\frac{U \vdash_Y A' < A \quad U \vdash_Y [X \mapsto X']T < S}{U \vdash_Y \text{functor}(X : A) \rightarrow T < \text{functor}(X' : A') \rightarrow S} \\
\frac{\sigma : \{1, \dots, m\} \mapsto \{1, \dots, n\} \quad \forall i \in \{1, \dots, m\}, U \vdash_Y C_{\sigma(i)} < B_i}{U \vdash_Y \text{sig } C_1 \dots C_n \text{ end} < \text{sig } B_1 \dots B_m \text{ end}} \\
\overline{U \vdash_Y \text{type } t < \text{type } t} \quad \overline{U \vdash_Y \text{type } t = \tau < \text{type } t} \quad \overline{U \vdash_Y \text{datatype } t = c \text{ of } \tau < \text{type } t} \\
\frac{U \vdash_Y \tau_1 \equiv \tau_2}{U \vdash_Y \text{type } t = \tau_1 < \text{type } t = \tau_2} \quad \frac{U \vdash_Y \tau_1 \equiv \tau_2}{U \vdash_Y \text{val } l : \tau_1 < \text{val } l : \tau_2} \\
\frac{U \vdash_Y \tau_1 \equiv \tau_2}{U \vdash_Y \text{datatype } t = c \text{ of } \tau_1 < \text{datatype } t = c \text{ of } \tau_2} \\
\frac{U \vdash_Y T < S}{U \vdash_Y \text{module } M : T < \text{module } M : S}
\end{array}$$

Figure 43: Subtyping with respect to U in *TraviataY*

$$\begin{aligned}
\text{Trans}(T_d^i) &= \text{trans1}(T_d)^i \\
\text{trans1}(\text{sig } (Z) C_1 \dots C_n \text{ end}) &= \text{sig } (Z) \text{ trans1}(C_1) \dots \text{trans1}(C_n) \text{ end} \\
\text{trans1}(\text{functor}(X : A) \rightarrow T_d^i) &= \text{functor}(X : A) \rightarrow \text{trans1}(T_d)^i \\
\text{trans1}((T_{d1}^{i1} : T_{d2}^{i2})) &= (\text{trans1}(T_{d1})^{i1} : \text{trans2}(T_{d1}, T_{d2})^{i2}) \\
\text{trans1}(p) &= p \\
\text{trans1}(\text{module } M : T_d^i) &= \text{module } M : \text{trans1}(T_d)^i \\
\text{trans1}(C) &= C \text{ when } C \text{ is not a module specification} \\
\text{trans2}((T_{d1}^{i1} : T_{d2}^{i2}), T_d) &= \text{trans2}(T_{d2}, T_d) \\
\text{trans2}(p, \text{sig } (Z) C_1 \dots C_n \text{ end}) &= \text{sig } (Z) \text{ trans3}(p, C_1) \dots \text{trans3}(p, C_n) \text{ end} \\
\text{trans2}(p, \text{functor}(X : A) \rightarrow T_d^i) &= \text{functor}(X : A) \rightarrow \text{trans2}(p(X), T_d)^i \\
\text{trans2}(\text{sig } (Z_1) C_1 \dots C_m \text{ end}, \text{sig } (Z_2) C'_1 \dots C'_n \text{ end}) \\
&= \text{sig } (Z_2) \text{ trans4}(Z_1, C_{\sigma(1)}, C'_1) \dots \text{trans4}(Z_1, C_{\sigma(n)}, C'_n) \text{ end} \\
\text{trans2}(\text{functor}(X_1 : A_1) \rightarrow T_{d1}^{i1}, \text{functor}(X_2 : A_2) \rightarrow T_{d2}^{i2}) \\
&= \text{functor}(X_2 : A_2) \rightarrow \text{trans2}([X_1 \mapsto X_2]T_{d1}, T_{d2})^{i2} \\
\text{trans3}(p, \text{module } M : T_d^i) &= \text{module } M : \text{trans2}(p.M, T_d)^i \\
\text{trans3}(p, \text{type } t) &= \text{type } t = p.t \\
\text{trans3}(p, C) &= C \text{ when } C \text{ is not a module specification nor opaque type specification} \\
\text{trans4}(p, \text{module } M : T_{d1}^{i1}, \text{module } M : T_{d2}^{i2}) &= \text{module } M : \text{trans2}(T_{d1}, T_{d2})^{i2} \\
\text{trans4}(p, C, C') &= \text{trans3}(p, C') \text{ when } C' \text{ is not a module specification}
\end{aligned}$$

Figure 44: Breaking type abstraction

$$\begin{aligned}
SelfMap(T_d^i) &= selfmap1(T_d) \\
selfmap1(\mathbf{sig}(Z) C_1 \dots C_n \mathbf{end}) &= \bigcup_i selfmap2(C_i) \\
selfmap1(\mathbf{functor}(X : A) \rightarrow T) &= SelfMap(T) \\
selfmap1((T_d^i : T)) &= selfmap3(T_d, T) \cup selfmap1(T_d) \\
selfmap1(p) &= \emptyset \\
selfmap2(\mathbf{module} M : T) &= SelfMap(T) \\
selfmap2(C) &= \emptyset \text{ when } C \text{ is not a lazy module specification} \\
selfmap3((T_d^i : T'), T) &= selfmap3(T_d, T) \\
selfmap3(p, \mathbf{sig}(Z^{id}) C_1 \dots C_n \mathbf{end}^i) &= [Z \mapsto p] \cup \bigcup_i selfmap4(p, C_i) \\
selfmap3(p, (\mathbf{functor}(X : A) \rightarrow T)^i) &= selfmap3(p(X), T) \\
selfmap3(\mathbf{sig}(Z_1^{id}) C_1 \dots C_n \mathbf{end}, \mathbf{sig}(Z_2^{id}) C'_1 \dots C'_m \mathbf{end}^i) \\
&= [Z_1 \mapsto Z_2^{id}] \cup \bigcup_i selfmap5(C_{\sigma(i)}, C'_i) \\
selfmap3(\mathbf{functor}(X : A) \rightarrow T_d^i, (\mathbf{functor}(X' : A') \rightarrow T')^i) \\
&= selfmap3([X \mapsto X']T_d, T') \\
selfmap4(p, \mathbf{module} M : T) &= selfmap(p.M, T) \\
selfmap4(p, C) &= \emptyset \text{ when } C \text{ is not a lazy module specification} \\
selfmap5(\mathbf{module} M : T_d^i, \mathbf{module} M : T) &= selfmap3(T_d, T) \\
selfmap5(C, C') &= \emptyset \text{ otherwise}
\end{aligned}$$

Figure 45: Extracting substitutions

$$\begin{array}{c}
\text{dom}(\theta_1) = \text{dom}(\theta_2) \quad \exists X \in \text{dom}(\theta_1), U \vdash \theta_1(X) \overset{\tau}{\sim} \theta_2(X) \\
\forall X' \in \text{dom}(\theta_1) \setminus \{X\}, \theta_1(X') = \theta_2(X') \\
\hline
U \vdash Z^{\theta_1} \overset{\tau}{\sim} Z^{\theta_2} \\
\\
\frac{U \vdash p \overset{\tau}{\sim} p'}{U \vdash p.M \overset{\tau}{\sim} p'.M} \quad \frac{U \vdash p \overset{\tau}{\sim} p'}{U \vdash p(q) \overset{\tau}{\sim} p'(q)} \\
\frac{U \vdash q \overset{\tau}{\sim} q'}{U \vdash p(q) \overset{\tau}{\sim} p(q')} \quad \frac{U \vdash p \mapsto (\theta, q^i)}{U \vdash p \overset{\tau}{\sim} \theta(q)}
\end{array}$$

Figure 46: Transition rules for paths with respect to U

$$\begin{array}{c}
U \vdash \mathbf{1} \overset{\mathbf{1}}{\sim} \mathbf{0} \quad U \vdash \tau_1 \rightarrow \tau_2 \overset{\text{ar}_i}{\sim} \tau_i \quad U \vdash \tau_1 * \tau_2 \overset{\text{prd}_i}{\sim} \tau_i \\
\frac{U \vdash p \overset{\tau}{\sim} p'}{U \vdash p.t \overset{\tau}{\sim} p'.t} \quad \frac{U \vdash p.t \mapsto (\theta, \text{sig} \dots \text{type } t = \tau \dots \text{end}^i)}{U \vdash p.t \overset{\tau}{\sim} \theta(\tau)} \\
\frac{U \vdash p \mapsto (\theta, \text{sig} \dots \text{datatype } t = c \text{ of } \tau \dots \text{end}^i)}{U \vdash p.t \overset{c}{\sim} \theta(\tau)} \\
\frac{U \vdash X \mapsto (\theta, \text{sig} \dots \text{type } t \dots \text{end}^i)}{U \vdash X.t \overset{X.t}{\sim} \mathbf{0}}
\end{array}$$

Figure 47: Transition rules for types with respect to U

Definitions and Specifications

$$\begin{array}{c}
\frac{U \vdash_X E : T}{U \vdash_X \text{module } M = E : \text{module } M : T} \quad \frac{U \vdash_X S : T}{U \vdash_X \text{module } M : S : \text{module } M : T} \\
\frac{U, \emptyset \vdash_X e : \tau}{U \vdash_X \text{val } l = e : \text{val } l : \tau} \quad \frac{U \vdash_X \tau \diamond \quad U \vdash \tau \approx \tau'}{U \vdash_X \text{val } l : \tau : \text{val } l : \tau'} \\
\frac{U \vdash_X \text{type } t : \text{type } t}{U \vdash_X \text{type } t : \text{type } t = \tau} \quad \frac{U \vdash_X \tau \diamond \quad U \vdash \tau \approx \tau'}{U \vdash_X \text{type } t = \tau : \text{type } t = \tau'}
\end{array}$$

Module expression

$$\frac{U \vdash_X E_d : T_d}{U \vdash_X E_d^i : T_d^i}$$

Module expression descriptions

$$\begin{array}{c}
\frac{U \vdash_X D_1 : C_1 \dots U \vdash_X D_n : C_n}{U \vdash_X \text{struct } (Z) D_1 \dots D_n \text{ end} : \text{sig } (Z) C_1 \dots C_n \text{ end}} \\
\frac{U \vdash_X A : A' \quad U \vdash_X E : T}{U \vdash_X \text{functor}(X : A) \rightarrow E : \text{functor}(X : A') \rightarrow T} \\
\frac{U \vdash_X E : T_1 \quad U \vdash_X S : T_2 \quad U \vdash_X T_1 < S}{U \vdash_X (E : S) : (T_1 : T_2)} \quad \frac{U \vdash_X p \text{ wf}}{U \vdash_X p : p}
\end{array}$$

Signature

$$\frac{U \vdash_X S_d : T_d}{U \vdash_X S_d^i : T_d^i}$$

Signature descriptions

$$\begin{array}{c}
\frac{U \vdash_X B_1 : C_1 \dots U \vdash_X B_n : C_n}{U \vdash_X \text{sig } (Z) B_1 \dots B_n \text{ end} : \text{sig } (Z) C_1 \dots C_n \text{ end}} \\
\frac{U \vdash_X A : A' \quad U \vdash_X S : T}{U \vdash_X \text{functor}(X : A) \rightarrow S : \text{functor}(X : A') \rightarrow T}
\end{array}$$

Module variable signature

$$\frac{U \vdash_X A_{d1} : A_{d2}}{U \vdash_X A_{d1}^{i1} : A_{d2}^{i2}}$$

Module variable signature descriptions

$$\frac{U \vdash_X B_1 : C_1 \dots U \vdash_X B_n : C_n}{U \vdash_X \text{sig } B_1 \dots B_n \text{ end} : \text{sig } C_1 \dots C_n \text{ end}}$$

Figure 48: Typing rules for the module language with respect to U in *TraviataX*

$$\begin{array}{c}
\text{Core types} \\
\frac{}{U \vdash_X \mathbf{1} \diamond} \quad \frac{U \vdash_X \tau_1 \diamond \quad U \vdash_X \tau_2 \diamond}{U \vdash_X \tau_1 \rightarrow \tau_2 \diamond} \quad \frac{U \vdash_X \tau_1 \diamond \quad U \vdash_X \tau_2 \diamond}{U \vdash_X \tau_1 * \tau_2 \diamond} \\
\frac{U \vdash_X p \text{ wf} \quad U \vdash_Y p \rightsquigarrow p' \quad U \vdash p' \mapsto (\theta, T_d^i)}{U \vdash_X p.t \diamond} \\
\text{\small } T_d \text{ is a lazy signature type containing a type specification for } t \\
\text{Core expressions:} \\
\frac{U, \Gamma \vdash_X e : \tau' \quad U \vdash \tau \approx \tau'}{U, \Gamma \vdash_X e : \tau} \\
\frac{}{U, \Gamma \vdash_X () : \mathbf{1}} \quad \frac{x \in \text{dom}(\Gamma)}{U, \Gamma \vdash_X x : \Gamma(x)} \\
\frac{U \vdash \tau \approx \tau_1 \rightarrow \tau_2 \quad U \vdash_X \tau \diamond \quad U, \Gamma, x : \tau_1 \vdash_X e : \tau_2 \quad U, \Gamma \vdash_X e_1 : \tau_1 \quad U, \Gamma \vdash_X e_2 : \tau_2}{U, \Gamma \vdash_X (\lambda x. e : \tau) : \tau} \quad \frac{}{U, \Gamma \vdash_X (e_1, e_2) : \tau_1 * \tau_2} \\
\frac{U, \Gamma \vdash_X e : \tau_1 * \tau_2 \quad U, \Gamma \vdash_X e_1 : \tau_1 \rightarrow \tau_2 \quad U, \Gamma \vdash_X e_2 : \tau_1}{U, \Gamma \vdash_X \pi_i(e) : \tau_i} \quad \frac{}{U, \Gamma \vdash_X e_1 (e_2) : \tau_2} \\
\frac{U \vdash_X p \text{ wf} \quad U \vdash_Y p \rightsquigarrow p' \quad \gamma_X(p', c, t) = (\tau_1, \) \quad U, \Gamma \vdash_X e : \tau_1}{U, \Gamma \vdash_X p.c \ e : p'.t} \\
\frac{U \vdash_X p \text{ wf} \quad U \vdash_Y p \rightsquigarrow p' \quad \gamma_X(p', c, t) = (\tau_1, \) \quad U, \Gamma \vdash_X e_1 : p'.t \quad U, \Gamma, x : \tau_1 \vdash_X e_2 : \tau}{U, \Gamma \vdash_X \text{case } e_1 \text{ of } p.c \ x \Rightarrow e_2 : \tau} \\
\frac{U \vdash_X p \text{ wf} \quad U \vdash_Y p \rightsquigarrow p' \quad U \vdash p' \mapsto (\theta, \text{sig} \dots \text{val} : \tau \dots \text{end}^i)}{U, \Gamma \vdash_X p.l : \theta(\tau)} \\
\frac{U \vdash_X \tau_1 \diamond \quad U \vdash_X \tau_2 \diamond \quad U, \Gamma \vdash_X e : \tau_1 \quad U \vdash \tau_1 \approx \tau_2}{U, \Gamma \vdash_X (e : \tau_1 :: \tau_2) : \tau_2}
\end{array}$$

Figure 49: Typing rules for the core language with respect to U in *TraviataX*

$$\begin{array}{l}
\gamma_X(U, p, c) = (t, \theta(\tau)) \text{ when} \\
U \vdash p \mapsto (\theta, \text{sig} \dots \text{datatype } t = c \text{ of } \tau \dots \text{end}^i)
\end{array}$$

Figure 50: Datatype look-up with respect to U in *TraviataX*

$$\begin{array}{c}
\frac{}{U \vdash_X X \text{ wf}} \quad \frac{}{U \vdash_X Z^{id} \text{ wf}} \quad \frac{U \vdash_Y p.M \rightsquigarrow q \quad U \vdash_X p \text{ wf}}{U \vdash_X p.M \text{ wf}} \\
\frac{U \vdash_X p_1 \text{ wf} \quad U \vdash_X p_2 \text{ wf} \quad U \vdash_Y p_1 \rightsquigarrow p'_1 \quad U \vdash_Y p_2 \rightsquigarrow p'_2 \quad U \vdash_Y p_1(p_2) \rightsquigarrow q \quad U \vdash p'_1 \mapsto (\theta, (\text{functor } (X : A_d^j) \rightarrow T)^i) \quad U \vdash_X p'_2 < \theta[X \mapsto p'_2](A_d)}{U \vdash_X p_1(p_2) \text{ wf}}
\end{array}$$

Figure 51: Well-formed paths with respect to U in $\text{Traviata}X$

$$\begin{array}{c}
\frac{U \vdash_X T_d < S_d \quad U \vdash_X T_d < A_d}{U \vdash_X T_d^i < S_d^j \quad U \vdash_X T_d^i < A_d^j} \\
\frac{U \vdash_X T_d < S_d}{U \vdash_X (T : T_d^i) < S_d} \\
\frac{U \vdash_Y p \rightsquigarrow p' \quad U \vdash p' \mapsto (\theta, T_d^i) \quad U \vdash_X \theta(T_d) < S_d}{U \vdash_X p < S_d} \\
\frac{\sigma : \{1, \dots, m\} \mapsto \{1, \dots, n\} \quad \forall i \in \{1, \dots, m\}, U \vdash_X C_{\sigma(i)} < B_i}{U \vdash_X \text{sig } (Z) C_1 \dots C_n \text{ end} < \text{sig } (Z') B_1 \dots B_m \text{ end}} \\
\frac{U \vdash_X A' < A \quad U \vdash_X [X \mapsto X']T < S}{U \vdash_X \text{functor}(X : A) \rightarrow T < \text{functor}(X' : A') \rightarrow S} \\
\frac{\sigma : \{1, \dots, m\} \mapsto \{1, \dots, n\} \quad \forall i \in \{1, \dots, m\}, U \vdash_X C_{\sigma(i)} < B_i}{U \vdash_X \text{sig } C_1 \dots C_n \text{ end} < \text{sig } B_1 \dots B_m \text{ end}} \\
\frac{}{U \vdash_X \text{type } t < \text{type } t} \quad \frac{}{U \vdash_X \text{type } t = \tau < \text{type } t} \quad \frac{}{U \vdash_X \text{datatype } t = c \text{ of } \tau < \text{type } t} \\
\frac{U \vdash \tau_1 \approx \tau_2}{U \vdash_X \text{type } t = \tau_1 < \text{type } t = \tau_2} \quad \frac{U \vdash \tau_1 \approx \tau_2}{U \vdash_X \text{val } l : \tau_1 < \text{val } l : \tau_2} \\
\frac{U \vdash \tau_1 \approx \tau_2}{U \vdash_X \text{datatype } t = c \text{ of } \tau_1 < \text{datatype } t = c \text{ of } \tau_2} \\
\frac{U \vdash_X T < S}{U \vdash_X \text{module } M : T < \text{module } M : S}
\end{array}$$

Figure 52: Subtyping with respect to U in $\text{Traviata}X$

9 Type inference for the core language

We implemented a type inference algorithm for the core language by determining an inference order using the module path expansion algorithm, then running a standard inference algorithm along this order. Concretely, using *PathExp*, we build a call graph of functions (represented by a directed graph), which expresses how functions in modules depend on each other: the strongly connected components of the graph indicate sets of value components whose type should be inferred simultaneously, referring to each other monomorphically; by topologically sorting the connected components, we generalize types in a connected component before moving on to typing the next one. For instance in Figure 2, we build an inference order:

```
Tree.split → {Tree.labels, Forest.labels}
           → {Forest.sweep} → Forest.incr
```

where braces indicate strongly connected component. The inference order we build for Figure 1 is

```
{Tree.map} → {Forest.map}
```

For the purpose of type inference, we do not consider that `Tree.map` and `Forest.map` are mutually recursive, since the signatures of `Tree` and `Forest` specify exported types for these functions.

We must also check for well-formedness of types, as module variables should not escape their scope during unification. This is checked after the inference. Note that when an abstract type depends on a functor argument, then the argument explicitly appears inside the type. For instance, in Figure 2, the type `Tree.t` is internally represented as $\text{TF}^{[x \rightarrow x]}.Tree.t$.

Explicit type annotations can be used to break dependencies in the call graph, and allow polymorphic recursion. Annotations cannot be completely avoided, as type inference for polymorphic recursion is known to be undecidable.

10 Related work

Much work has been devoted to investigating recursive module extensions of the ML module system. Notably, type systems and initialization of recursive modules pose non-trivial issues, and have been the main subjects of study.

10.1 Type systems

To the best of our knowledge, no work has proposed a type system for recursive modules with applicative functors, except for the experimental implementation in Objective Caml [16], or examined type inference for recursive modules whether functors are applicative or generative. Moreover, only *Traviata* can type the examples on the expression problem in Section 6 without modifications.

The experimental implementation of recursive modules in Objective Caml is most related to our work. Indeed, we followed it in large part when designing *Traviata*. O’Caml supports a highly expressive core language and a strong type inference algorithm, which are one of our motivations for the effort to enable type inference. O’Caml also supports recursive signatures, with a rather concise syntax. However, it allows to write problematic modules whose type checking diverges. The potential for divergence when typing O’Caml modules is well-known, but is assumed to be a rare phenomenon in practice. Recursive signatures seem to make the problem much more acute. This is one of our motivations in insisting on decidable type checking for *Traviata*. Of course we obtain it through restrictions, and a less expressive signature language. Yet, this may be the price for safety. Since we have similar typing rules, we hope that our approach can apply to O’Caml with little change.

Crary, Harper and Puri [3] gave a foundational type theoretic analysis of recursive modules in the context of a phase-distinction formalism [11].

Russo [24, 23] proposed a type system for recursive modules, which we examined in Section 2.

Dreyer [5] gave a theoretical account for type abstraction inside recursive modules. In particular, he investigated generative functors in the context of recursive modules, by proposing a “destination passing” interpretation of type generativity. There is a critical difference in design choices between us, with respects to type abstraction inside recursive modules. For instance, consider the two programs:

```
module M = (struct type t = N.t end : sig type t end)
module N = (struct type t = M.t end : sig type t end)
```

and

```
module M = (struct type t = N.t list end : sig type t end)
module N = (struct type t = M.t * M.t end : sig type t end)
```

Dreyer prohibits both programs, whereas we accept both. A motivation of our design choice is that we want to keep liberal uses of polymorphic variants and objects, which are useful constructs supported in O’Caml; prohibiting the latter program may result in restriction in using these constructs and recursive modules together.

10.2 Initialization

Boudol [1], Hirschowitz and Leroy [12], and Dreyer [4] have proposed type systems which ensure that initialization of recursive modules does not try to access components of modules that are not yet evaluated. They are interested in the safety of initialization, hence their modules do not have type components.

Their type systems judge the two modules:

```
module M = struct (Z) val l = Z.m val m = Z.l end
```

and

```
module N = struct (Z) val l =  $\lambda x \rightarrow x + Z.m$  val m = Z.l(3) end
```

to be ill-typed. In both cases, evaluation of the component `m` cyclically requires evaluation of itself. Our type system, in particular the core type reconstruction algorithm, can reject the cycle for the former, but not for the latter.

11 Conclusion

In this paper, we presented a type system for recursive modules by extending Leroy’s applicative functor calculus. The type system is decidable and sound for a call-by-value operational semantics. It supports type inference for recursive modules, hence type abstraction both inside and outside the recursion is handled equally; the programmer does not need to write two different signatures for the same module to assist the type checker.

We examined three examples. The first two presented typical uses of recursive modules with different choices of where to enforce type abstraction. The last one gave a solution to the expression problem and demonstrated how recursive modules add to the expressive power of the programming language when combined with other language constructions.

Here we give a brief overview of future work.

Separate type checking Although we have not discussed, *Traviata* is already prepared for separate type checking. In short, we only have to extend the look-up judgment (Figure 7) so that the judgment informs the type system of signatures of modules which are type checked separately (i.e., to replace concrete module expressions with their signatures).

Lazy modules with eager value components The operational semantics presented in this paper uses lazy evaluation for both modules and their value components in the sense that only components of modules that are accessed are evaluated, and the evaluation is triggered at access time. This semantics simplifies the soundness statement and its proof. For a practical system, however, we are investigating lazy modules with eager value components, that is, to keep modules lazy but evaluate all the value components (but not module components) of a module at once, triggered by the first access to some component of the module. Lazy semantics of modules would allow flexible uses of recursive modules; eager semantics of value components would give the programmer a way to initialize recursive modules.

We need to explore the evaluation strategy of modules. For instance, we want to succeed in evaluating the following modules whether the evaluation begins at *M* or at *N*.

```
module M = struct val m1 = 3 val m2 = N.n1 val m3 = 7 end
module N = struct val n1 = 5 val n2 = M.m1 val n3 = M.m3 end
```

We also need to cope with unsafe modules whose evaluation cannot be successful,

for instance the modules we saw in Section 10.2; we want to avoid running into divergence but to reject them statically or, at least, to raise run-time errors.

We believe that our algorithms for path resolution are useful for efficient and safe implementation of lazy recursive modules. We need more investigation on this topic.

The double vision problem It is desirable to solve the double vision problem without requiring type coercion annotations from the programmer. The current type system always passes to *TypExp* the whole lazy program type *ReconstP* constructed. This seems too naïve. Given that *TypExp* terminates for whatever input, we think it is safe to pass *TypExp* different signature information depending on whether it is used inside sealing or not. For instance in Figure 26, we should make *TypExp* interpret the sealing signature of **Forest** transparently during type checking inside **Forest**.

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