Semigroup theory for functional differential equations with infinite delay; a representation of infinitesimal generators

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1. Semigroups and infinitesimal generators. Suppose  $\mathcal{B}$  =  $\mathcal{B}(I,\,C^n)$  is a linear space of some functions  $\phi$  mapping an intermal I into n-dimensional comlex linear space  $C^n$ , where  $I = [-r,\,0],\,0 \le r < \infty$ , or  $I = (-\infty,\,0]$ . For a  $C^n$ -valued given function x and a parameter t in R, the function  $x_t: I \to C^n$  is defined by  $x_t(\theta) = x(t+\theta)$  for  $\theta$  in I whenever  $x(t+\theta)$  is well defined. If  $L: \mathcal{B} \to C^n$  is a given linear operator, we say that the relation

$$(1) x'(t) = L(x_t)$$

is a linear functional differential equation—with finite delay when I = [-r, 0], or with infinite delay when I = (- $\infty$ , 0]. In this lecture, L is always assumed to be continuous. Suppose for every  $\phi$  in  $\mathcal B$  Equation (1) has a unique solution  $\mathbf x(\mathbf t;\phi)$  for t in  $[0,\infty)$  with the initial condition  $\mathbf x_0 = \phi$ . Then the solution operator  $\mathbf T(\mathbf t):\mathcal B \to \mathcal B$  is defined by the relation

$$T(t)\phi = x_t(\phi), \phi \text{ in } B, t \ge 0.$$

In case  $\mathcal{B}$  is the family of continuous functions on [-r, 0] into  $\mathbb{C}^n$ , the family  $\{T(t): t \geq 0\}$  is a semigroup of class  $(\mathbb{C}_0)$  of bounded linear operators on  $\mathcal{B}$ . Let A be the infinitesimal generator of T(t); that is,  $A\phi = \lim_{t \to 0+} t^{-1}[T(t)\phi - \phi]$  whenever this limit exists. It is well known [2] that A is given by

(2) 
$$A\phi(\theta) = \begin{cases} L(\phi) & \text{for } \theta = 0 \\ \\ \phi'(\theta) & \text{for } -r \leq \theta < 0 \end{cases}$$

if and only if the function defined by the relation in the right hand side belongs to  $\ensuremath{\mathcal{B}}$ .

In the case when  $\mathcal{B}=\mathcal{B}((-\infty,\,0],\,\mathbb{C}^n)$ , several models for  $\mathcal{B}$  are proposed: for some special measure  $\mu$ ,  $\mathcal{B}=L^p(\mu)\times\mathbb{C}^n$  in which a norm is defined by  $|\phi|=[|\phi(0)|^p+\int_{-\infty}^0|\phi(\theta)|^p\,\mathrm{d}\mu(\theta)]^{1/p}$ ,  $1\leq p<\infty$ ;  $\mathcal{B}=\mathcal{C}_\gamma$ , the family of continuous functions  $\phi$  such that  $\phi(\theta)=\varphi^{\gamma\theta}\to \alpha$  limit as  $\theta\to-\infty$ , in which a norm is defined by  $|\phi|=\sup|\phi(\theta)e^{\gamma\theta}|$ . In these cases the family T(t) is again a semigroup of class  $(\mathcal{C}_0)$  of bounded linear operators on  $\mathcal{B}$ . Furthermore, the representation of A similar to Formula (2) is valid; the definition of  $\phi'$  is slightly changed according to the choice of  $\mathcal{B}$  (cf [3, 4]).

In [2, 5, 6], etc, Equation (1) is considered on some abstract phase space  $\mathcal B$  which is defined to be a space satisfying some hypotheses. The systems of hypotheses are somewhat different from each other according to the problem under discussion. In all cases, however, T(t) becomes a semigroup of bounded linear operators on  $\mathcal B$ . Further results are known [5, 6]: an asymptotic estimate of the order of |T(t)| as  $t \to \infty$ ; informations about the spectrum of  $\mathcal A$ ; and a construction of the fundamental matrix of Equation (1) with the variation-of-constants formula for the forced system of Equation (1), etc. However, it has been left unsolved to represent  $\mathcal A$  in the manner analogous to Formula (2).

- 2. Formal approaches to the problem. To explain the reason why the representation of A is difficult to obtain, we go into the details of the hypotheses on  $\mathcal{B}$  employed in [5, 6].
- (H-0). A seminorm  $|\cdot|$  is defined on  $\mathcal{B}$ : the quotient space  $\hat{\mathcal{B}} = \mathcal{B}/|\cdot|$  is a Banach space.
- (H-1). If a function  $x:(-\infty, \sigma+\alpha) \to C^n$ ,  $\alpha > 0$ , is continuous on  $[\sigma, \sigma+\alpha)$  and  $x_{\sigma}$  is in B, then  $x_t$  is in B for every t in  $[\sigma, \sigma+\alpha)$  and the map  $t \to x_t$  is continuous.
- (H-2). There exist positive continuous functions K(t) and M(t), where M(t) is submultiplicative, such that, for the function x arising in (H-2),  $|x_t| \le K(t-\sigma) \times \sup\{|x(s)|: \sigma \le s \le t\} + M(t-\sigma) |x_{\sigma}|$  for  $\sigma \le t < \sigma + \alpha$ .

(H-3).  $|\phi(0)| \leq K|\phi|$ ,  $\phi$  in  $\mathcal{B}$ , for some constant K. From these hypotheses, it follows that the solution  $x(t;\phi)$  exists on  $[0,\infty)$  uniquely: the solution operator T(t) is linear and continuous on  $\mathcal{B}$ . Hypothesis (H-1) implies that the semigroup T(t) is of class  $(C_0)$ . However, notice that no measurability condition is assumed on  $\phi$  in  $\mathcal{B}$ . We cannot, for example, discuss whether  $\phi$  in  $\mathcal{B}$  is absolutely continuous or not: the derivative  $\phi'$  has no meaning. To overcome this difficulty, we add more hypotheses on  $\mathcal{B}$ , or else we interpret Formula (2) in a different manner than ever before. In this lecture, we proceed along the latter line.

To do this, let us introduce operators  $\, {\rm B} \,$  and  $\, {\rm C}_{\rm L} \,$  defined formally by the relations

$$B\phi(\theta) = \begin{cases} 0 & \theta = 0 \\ \phi'(\theta) & \theta < 0 \end{cases} \quad C_{L}\phi(\theta) = \begin{cases} L(\phi) & \theta = 0 \\ 0 & \theta < 0. \end{cases}$$

To emphasize the operator L:B  $\rightarrow$  C<sup>n</sup>, T<sub>L</sub>(t) denotes the solution semigroup of Equation (1) and A<sub>L</sub> its infinitesimal generator. Then we can rewrite Formula (2) as

(3) 
$$A_{L}\phi = B\phi + C_{L}\phi.$$

Observe that  $B = A_0$ , the infinitesimal generator of the

solution semigroup  $T_0(t)$  of the trivial equation x'(t)=0. Usually, we use a special symbol S(t) for  $T_0(t)$ . The operator  $U_L(t)$  defined by  $U_L(t)=T_L(t)-S(t)$  is completely continuous; the decomposition  $T_L(t)=S(t)+U_L(t)$  was extremely useful to investigate the property of  $T_L(t)$ , [3,5]. Hence Relation (3) is also expected to have some meaning. However, we soon notice that this formula contains a trivial contradiction; that is, the domains of  $A_L$  and B do not coincide with each other. Furthermore, we do not know whether  $C_L$  is well defined on the space B or not. Formula (3) has an ambiguity concerning the domain where it holds.

3. Representation of A in the dual space. Fortunately, the adjoint operators of  $A_L$  and B have the same domain. Stech [7] first discovered this interesting fact in the case where B is of the type  $L^p(\mu) \times C^n$ ; the author [5] proved the same result in the case where B is an abstract space satisfying a system of hypotheses similar to (H-0, ... 4). Therefore, we hope that Formula (3) can be interpreted if the relation is transferred to the dual space. Let us introduce notations: X\* is a dual space of a Banach space X, and T\* the dual operator of a linear operator T on X if it exists.

Before the demonstration of the final result, we again refer to the hypotheses on  $\mathcal B$  which is sufficient to obtain the desired result. We leave Hypotheses (H-0) and (H-1) as

they are. The latter hypothesis implies that  $\mathcal B$  contains the space  $\mathcal C$ , the family of continuous functions on  $(-\infty, 0]$  with compact supports. Hypothesis (H-2) is replaced by

(H-2)'. There exists a continuous function K(t) such that, if  $\phi$  in C has its support in [-t, 0], then

$$|\phi| \leq K(t) \sup\{|\phi(\theta)|: -t \leq \theta \leq 0\}.$$

Suppose  $\alpha:\mathcal{B}\to\mathbb{C}$  is linear and continuous; that is,  $\alpha$  is a member of  $\mathcal{B}^*$ . Then (H-2)' implies

$$|\langle \alpha, \phi \rangle| \leq |\alpha| K(t) \sup\{|\phi(\theta)|: -t \leq \theta \leq 0\}$$

for  $\phi$  arising in (H-2)'. This means that the restriction of  $\alpha$  on C is a Radon measure on  $(-\infty, 0]$ . It is well known that, for such a measure  $\alpha$ , there exists a function  $\eta(\alpha;\theta)=(\eta_1(\alpha;\theta),\ldots,\eta_n(\alpha;\theta))$  locally of bounded variation for  $\theta$  on  $(-\infty, 0]$  such that

$$\langle \alpha, \phi \rangle = \int_{-\infty}^{0} d_{\theta} \eta(\alpha; \theta) \phi(\theta) = \int_{-\infty}^{0} \sum_{i=1}^{n} d_{\theta} \eta_{i}(\alpha; \theta) \phi^{i}(\theta)$$

for every  $\phi$  in  $\mathcal{C}$ . We can assume that  $\eta$  is normalized in the sense that  $\eta(\alpha;0)=0$  and  $\eta(\alpha;\theta)$  is continuous to the left for  $\theta<0$ . Then  $\eta(\alpha;\theta)$  is determined uniquely by  $\alpha$  in  $3^*$ . It is clear that the map  $\alpha\to\eta(\alpha;0-)$ , the left-hand limit of  $\eta$  at  $\theta=0$ , is a linear operator on

 $B^*$  into  $C^n$ . We assume the following hypothesis.

(H-4). This operator  $\alpha \to \eta(\alpha;0-)$  is continuous. Note that this condition holds [6] if we adds one more hypothesis to the system (H-0, 1, 2, 3).

Hypothesis (H-3) is also assumed and rewritten in the form

(H-3). The operator  $D:\mathcal{B}\to C^n$  defined by  $D(\varphi)=\varphi(0)$ ,  $\varphi\in\mathcal{B}$ , is continuous.

Finally, we need the following.

(H-5). For every t  $\geq$  0,  $T_L(t)$  is well defined to be a continuous linear operator on  $\mathcal{B}$ .

Hypotheses (H-1, 5) imply that  $T_L(t)$  is a semigroup of class ( $C_0$ ) of bounded linear operators on B. It is known [2, 5] that (H-5) is derived from (H-1,2,3). In this lecture, we are not interested in this fact, but we dovote ourself to the study of the representation of  $A_L$ . From this standpoint, we assume the above statement, while (H-2) is replaced by a weak Hypothesis (H-2)'.

Now observe that  $(T_L(t) - S(t))\phi$  is a menber of C for every  $\phi$  in B. From Hypothesis (H-2)', for every  $\alpha$  in  $B^*$  we can represent  $<\alpha$ ,  $(T_L(t) - S(t))\phi>$  in terms of Stirtjes integral. This implies the following Proposition.

Proposition 1. For every  $\alpha$  in  $B^*$  and every  $\phi$  in B,

$$\lim_{t \to 0+} \langle t^{-1} [T_L^*(t) - S^*(t)] \alpha, \phi \rangle = \sum_{i=1}^{n} -\eta_i(\alpha; 0-) L^i(\phi).$$

Let  $\delta^{\dot{i}}(\phi)$  and  $L^{\dot{i}}(\phi)$  denote the i-th component of  $D(\phi)$  and  $L(\phi)$ , respectively. Hypothesis (H-3) implies that  $\delta^{\dot{i}}$  is an element of  $\mathcal{B}^*$ ; clearly,  $L^{\dot{i}}$  is also in  $\mathcal{B}^*$ . From the definition of infinitesimal generators and dual operators, we have the following proposition.

Proposition 2. Every  $\delta^i$  belongs to the domain of  $A_L^*$ ; and  $A_L^*\delta^i = L^i$  for  $i=1,\ldots,n$ .

Define an operator  $P:B^* \rightarrow B^*$  by the relation

$$P\alpha = -\eta(\alpha; 0-) \cdot D = \sum_{i=1}^{n} -\eta_{i}(\alpha; 0-) \delta^{i} \quad \text{for } \alpha \quad \text{in } \mathcal{B}^{*}.$$

It is easy to see that PP = P; while Hypothesis (H-4) implies that P is continuous. Therefore P is a continuous projection on  $\mathcal{B}^*$ . Now we state the main theorem.

Theorem 3. Suppose Hypotheses (H-0,1,3,4,5) and (H-2)' hold and let  $A_L$  be the infinitesimal generator of the solution semigroup  $T_L(t)$  of Equation (1). Then the domain of  $A_L^*$  is independent of the choice of the continuous linear operator  $L:\mathcal{B}\to\mathbb{C}^n$ . If the above projection P is restricted on this common domain  $\mathcal{D}^*$ , then the restriction, denoted by P again, is also a projection on  $\mathcal{D}^*$ . The all operators  $A_L^*$ ,  $B^*$  and P are transformations of  $\mathcal{D}^*$  into  $B^*$  and they are related with each other in the manner

$$A_{L}^{*} = B^{*} + A_{L}^{*}P.$$

It is not difficult to prove this theorem if we use Proposition 1, 2 and the following result (cf. [1, p. 49]): the dual operator of the infinitesimal generator of a semigroup of class ( $C_0$ ) is equal to the weak\* infinitesimal generator of the dual semigroup. Notice that, along this line, we can again prove the existence of the common domain  $\mathcal{D}^*$ .

Corollary 4. The domain  $\mathcal{D}^*$  is decomposed into a direct sum  $\mathcal{D}^* = \mathcal{N}_\text{T}^* \oplus \mathcal{M}_\text{T}^*$  as follows:

- (i)  $A_T * \alpha = B * \alpha$  if and only if  $\alpha$  is in  $N_T *$ .
- (ii) The restriction of  $A_L^*$  on  $M_L^*$  is an isomorphism of  $M_L^*$  onto the linear manifold generated by  $\{L^1, \ldots, L^n\}$ . (iii)  $M_L^*$  is contained in  $PD^*$  and  $(I-P)D^*$  in  $N_L^*$ . On the other hand, the following conditions are equivalent: (a)  $M_L^* = PD^*$ , (b)  $N_L^* = (I-P)D^*$ , (c) the family  $\{L^1, \ldots, L^n\}$  are linearly independent.

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