## 1-Determinacy of Feasible Sets

水産庁東海区研究所 松本敏浩(Toshiriro Matsumoto) 産能大学経営情報学部 進藤晋 (Susumu Shindoh) 東京理科大学工学部 平林隆一 (Ryuichi Hirabayashi)

#### 1. Introduction

The purpose of this paper is to present the preparation for the singularity theory on nonlinear programming problems.

In the singularity theory of smooth mappings, the following three problems are fundamental (see Gibson [1]):

- (1) Finite determinacy of smooth mappings,
- (2) The existence of universal unfolding,
- (3) Classification of singular points.

On the one hand, in nonlinear programming problems, to investigate the singularity of the solutions satisfying the Kuhn-Tucker condition is very important for the cases such as studying the bifurcation of the solutions of parametric problems. However, a feasible set as the base space changes together with the objective function, so the singularity theory of smooth mappings can not apply directly to nonlinear programming problems. Therefore, as the preparation to develop the singularity theory of objective functions on feasible sets, we discuss the simplest problem of finite determinacy, i.e., "1-determinacy of feasible sets".

We define 1-determinacy of feasible sets and (strongly)

restricted 1-determinacy of map germs to characterize each concept of 1-determinacy by a necessary and sufficient condition and to show all of these concepts are equivalent in some sense. For simplicity, we will deal with feasible sets defined only by inequalities throughout the paper. (See [5] for the general feasible sets defined by equality and inequality constraints.)

# 2. 1-Determinacy of Feasible Sets.

Let  $E_{n,p}$  be the set of all  $C^1$  (continuously differentiable) map germs at 0 of  $R^n$  (the n-dimensional Euclidean space) to  $R^p$  (see [1] for the definition of map germs),  $E_{n,p}^0$  be the subset of  $f \in E_{n,p}$  with f(0) = 0, Diff be the set of all  $C^1$ -diffeomorphic germ  $\phi$ 's of  $R^n \to R^n$  ( $\phi$ (0) = 0) and Diff be the subset of Diff such that  $D\phi$ (0) =  $I_n$  where D is the partial differential operator and  $I_n$  is the nxn unit matrix. Define  $K_n = \{\Phi_{\sigma,u} \in Diff_n : \text{ there exist a germ } u \in E_{n,n} \text{ with } u_i(0) \neq 0 \text{ (1} \leq i \leq n)$  and a permutation  $\sigma$  on  $\{1,2,\ldots,n\}$  satisfying  $\Phi_{\sigma,u}(x) = \{u_1x_{\sigma(1)},\ldots,u_nx_{\sigma(n)}\}$ . Define also  $K_n^1 = K_n \cap Diff_n^1$ . Let  $H_{n,p} = K_p \times Diff_n$  and  $H_{n,p}^1 = K_n^1 \times Diff_n^1$ . Then  $H_{n,p}^1$  is the subgroup of  $H_{n,p}$ .  $H_{n,p}$  acts on  $E_{n,p}^0$  from left as follows: for any  $\alpha = (\beta, \gamma) \in H_{n,p}$  and  $f \in E_{n,p}^0$ ,  $\alpha \cdot f := \beta f \gamma^{-1}$ .  $H_{n,p}^1$  also acts on  $E_{n,p}^0$  from left.

Let the 1-jet of  $f \in E_{n,p}^0$  at  $0 \in R^n$  by  $j^1f_i = Df_i(0)x$  and  $J_f^1 = \{g \in E_{n,p}^0 : j^1g = j^1f\}$  If  $J_f^1 \subseteq H_{n,p}$  f (resp.  $H_{n,p}^1$ .f) holds, then f is called <u>restricted 1-determined</u>

(resp. strongly restricted 1-determined). For a  $g \in E_{n,p}^0$ , define  $M[g] = \{x \in R^n : g_1(x) \geq 0, i = 1, \ldots, p\}$ , where  $g_1(x)$  is the i-th component of g. M[g] is called the feasible set defined by g. For  $0 \in R^n$ , define an equivalence relation on the set  $\{M[g] : g \in E_{n,p}^0\}$  by  $M[g_1] \sim_0 M[g_2]$  if there exists a neighborhood U of  $0 \in R^n$  such that  $M[g_1] \cap U = M[g_2] \cap U$ . A feasible set germ on  $R^n$  is defined as an equivalence class with respect to  $\sim_0$  and denoted by  $M[g]_0$ . We call  $M[g]_0$  is 1-determined if  $M[g]_0$  is diffeomorphic to  $M[h]_0$  by the action of Diff whenever  $M[j^1g]_0 = M[j^1h]_0$ .

To characterize the concepts mentioned above, we prepare two definitions and the assumption below.

<u>Definition 1</u>. Let A be a real  $p \times n$  matrix. We say that A is <u>of type 1</u> if

- (1) rank  $A = \min(p,n)$ ,
- (2)  $p \leq n+2$ ,
- (3) all the minors of degree n of A are nonzero.

# <u>Definition 2</u>. For a $g \in E_{n,p}^0$ ,

- (1) g is <u>irredundant</u> if  $Dg_{i}(0)$  and  $Dg_{j}(0)$  are linearly independent to each other for  $i \neq j$ .
- (2) g is a minimal representative if M[g]  $\neq$  M[g<sup>(i)</sup>] where g<sup>(i)</sup> is defined by g<sup>(i)</sup><sub>j</sub> =  $(1 \delta_j^i)$ g<sub>j</sub>. Here  $\delta_j^i$  is the Kronecker's delta.

Remark. The definition of "irredundant" (resp. "a minimal representative") corresponds to that of "smoothness condition" (resp. "a conical basis") in [3].

If cusp points are in M[g], then the situation becomes rather complicated. So it is natural to assume some condition to exclude the existence of cusps. Our assumption is then:

Assumption 1. (Mangasarian-Fromovitz [2]) The map germ  $g \in E_{n,p}^{0} \text{ satisfies } \underline{\text{Mangasarian-Fromovitz condition at 0}},$  i.e., there is a  $w \in \mathbb{R}^{n}$  such that Dg(0)w > 0.

Remark. In [4], it is shown that the above assumption is equivalent to the condition that  $C = R_+\{Dg_j(0)\}_{j=1,\ldots,p}$  is a strictly convex cone, i.e., C is convex and  $C \cap (-C) = \{0\}$ , where  $R_+ = \{x \in R : x \geq 0\}$  and  $R_+T = \{all\ finite\ sums\ \Sigma\ r_it_i$  for  $r_i \in R_+$  and  $t_i \in T\}$  for any subset T of  $R^n$ . Furthermore, [4] presents a new characterization of Mangasarian-Fromovitz condition

The theorem below gives a necessary and sufficient condition for  $M[g]_0$  to be 1-determined:

Theorem 1. Let  $n \ge 2$  and  $g \in E_{n,p}^0$  be irredundant, a minimal representative and satisfy Assumption 1. Then  $M[g]_0$  is 1-determined if and only if Dg(0) is of type 1.

Proof) See Theorem 3.1 and Lemma 3.4 of [3].

The next theorem characterizes the restricted 1-determinacy:

Theorem 2. Let  $n \ge 2$  and  $g \in E_{n,p}^0$ . Suppose g satisfies Assumption 1. Then g is restricted 1-determined if and only if Dg(0) is of type 1.

Proof) See Theorem 2.15 of [5].

The following result shows that the concepts of 1-determinacy mentioned above are equivalent:

Theorem 3. Let  $n \ge 2$  and  $g \in E_{n,p}^0$  be irredundant, a minimal representative and satisfy Assumption 1. Then the next three statements are equivalent:

- (1) g is restricted 1-determined,
- (2) g is strongly restricted 1-determined,
- (3)  $M[g]_0$  is 1-determined.

Proof) See Corollary 2.16 of [5].

## References

[1] Gibson, C.G.: "Singular points of smooth mappings", Research notes in Mathematics 25, Pitman (1979).

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