Movement of Hot Spots on the Exterior Domain of a Ball

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1 Introduction

We consider the initial-boundary value problems of the heat equation in the exterior domain of a ball,

(1.1)
$$\begin{cases} \partial_t u = \Delta u & \text{in } \Omega \times (0, \infty), \\ \partial_\nu u = 0 & \text{on } \partial\Omega \times (0, \infty), \\ u(x, 0) = \phi(x) & \text{in } \Omega \end{cases}$$

and

(1.2)
$$\begin{cases} \partial_t u = \Delta u & \text{in } \Omega \times (0, \infty), \\ u(x, t) = 0 & \text{on } \partial\Omega \times (0, \infty), \\ u(x, 0) = \phi(x) & \text{in } \Omega, \end{cases}$$

where

$$\Omega = \mathbf{R}^N \setminus \overline{B(0,L)}, \quad L > 0, \qquad N \ge 2.$$

Here $\partial_t = \partial/\partial t$, $\partial_\nu = \partial/\partial \nu$, $\nu = \nu(x)$ is the outer unit normal vector to $\partial\Omega$ at $x \in \partial\Omega$, and $B(0,L) = \{x \in \mathbf{R}^N : |x| < L\}$. Throughout this paper we assume that

$$\phi \in L^2(\Omega, e^{\lambda |x|^2} dx)$$

for some $\lambda > 0$. For any t > 0, we may denote by H(t) the set of the maximum points of $u(\cdot,t)$, that is,

$$H(t) = \left\{ x \in \overline{\Omega} \, : \, u(x,t) = \max_{y \in \overline{\Omega}} u(y,t) \right\},$$

and call H(t) the set of hot spots of the solution u at the time t. In this paper we study the movement of hot spots H(t) of the solution u of (1.1) or (1.2) as $t \to \infty$.

Chavel and Karp [3] studied the heat equation $\partial_t u = \Delta u$ in several Riemannian manifolds, and obtained some asymptotic properties of solutions concerning the movement of hot spots of the solution. In particular, for the Euclidean space \mathbf{R}^N , they proved that, for any nonzero, nonnegative initial data $\phi \in L_c^{\infty}(\mathbf{R}^N)$, the hot spots H(t) of the solution at each time t > 0 are contained in the closed convex hull of the support of ϕ , and H(t) tends to the center of mass of φ as $t \to \infty$. Subsequently, Jimbo and Sakaguchi [11] studied the movement of hot spots of the solution of the heat equation in the half space \mathbf{R}^N_+ and in the exterior domain of a ball, under boundary conditions. In particular, for the Cauchy-Neumann problem (1.1) in the exterior domain $\Omega = \mathbf{R}^N \setminus \overline{B(0,L)}$ with the nonzero, nonnegative, radially symmetric initial data $\phi \in L_c^{\infty}(\Omega)$, they proved that the hot spots H(t) satisfies

(1.3)
$$H(t) \subset \partial \Omega = \partial B(0, L)$$

for all sufficiently large t. Furthermore, for the Cauchy-Dirichlet problem in the exterior domain $\Omega = \mathbf{R}^3 \setminus \overline{B(0,L)}$ with the nonzero, nonnegative, radially symmetric initial data $\phi \in L_c^{\infty}(\Omega)$, they proved that there exist a positive constant T and a continuous function $r = r(t) \in C([T,\infty) : (L,\infty))$ such that

(1.4)
$$\lim_{t \to \infty} r(t)^3 t^{-1} = 2$$

and

$$H(t) = \{x \in \mathbf{R}^N : |x| = r(t)\}, \quad t \ge T.$$

Their proofs of (1.3) and (1.4) heavily depend on the radially symmetry of the solutions and the properties of zero sets of the heat equation in \mathbf{R} , and it seems so difficult to apply their proofs to the solutions without the radially symmetry. (For the movement of hot spots of the solution for the Cauchy-Neumann problem in bounded domains, see [1], [2], [10], [12], and [14].)

In this paper we study the movement of hot spots H(t) of the solutions of the Cauchy-Neumann problem (1.1) or the Cauchy-Dirichlet problem (1.2) in the exterior domain Ω of a ball, without the radially symmetry of the solutions. In Sections 2 and 3, we give the results on the movement of the set of hot spots H(t) for the problems (1.1) and (1.2), respectively.

2 On the Cauchy-Neumann Problem (1.1)

In this section we assume

(2.1)
$$\phi \in L^2(\Omega, e^{\lambda |x|^2} dx), \qquad \int_{\Omega} \phi(x) dx > 0,$$

and give some results on the movement of the hot spots H(t) for the solution of (1.1) as $t \to \infty$. We first give a sufficient condition for the hot spots H(t) to exist only on the boundary $\partial \Omega$ for all sufficiently large t.

Theorem 2.1 (See Theorem 1.1 in [8].)

Let u be a solution of the Cauchy-Neumann problem (1.1) under the condition (2.1). Put

$$A_{\phi}^{N} = \int_{\Omega} x \phi(x) \left(1 + \frac{L^{N}}{N-1} |x|^{-N} \right) dx / \int_{\Omega} \phi(x) dx.$$

Assume

$$(2.2) A_{\phi}^{N} \in B(0, L) = \mathbf{R}^{N} \setminus \overline{\Omega}.$$

Then there exists a positive constant T such that

(2.3)
$$H(t) \subset \partial \Omega = L\left\{x \in \mathbf{R}^N : |x| = L\right\}$$

for all t > T.

In particular, we see that, under the condition (2.1), the hot spots H(t) of the radial solution of (1.1) exists only on the boundary of the domain Ω for all sufficiently large t.

Remark 2.1 Let u be a solution of the Cauchy-Neumann problem (1.1) under the condition (2.1). Let C(t) a center of mass of u(t), that is,

$$C(t) = \int_{\Omega} x u(x,t) dx / \int_{\Omega} u(x,t) dx.$$

Then it does not necessarily hold that C(t) = C(0) for all t > 0. On the other hand, we put

$$A(t)^{N}(t) \equiv \int_{\Omega} x u(x,t) \left(1 + \frac{L^{N}}{N-1} |x|^{-N} \right) dx / \int_{\Omega} u(x,t) dx, \quad t > 0.$$

Then we have $A_{\phi}^{N}(t) = A_{\phi}^{N}$ for all t > 0, and $\lim_{t \to \infty} C(t) = A_{\phi}^{N}$.

Next we give a result on the limit of the set H(t) as $t \to \infty$.

Theorem 2.2 (See Theorem 1.2 in [8].)

Let u be a solution of the Cauchy-Neumann problem (1.1) under the condition (2.1). Assume $A_{\phi}^{N} \neq 0$. Put

$$x_{\infty} = L \frac{A_{\phi}^{N}}{|A_{\phi}^{N}|}$$
 if $A_{\phi}^{N} \in B(0, L)$ and $x_{\infty} = A_{\phi}^{N}$ if $A_{\phi}^{N} \in \overline{\Omega}$

Then

$$\lim_{t \to \infty} \sup \left\{ |x_{\infty} - y| : y \in H(t) \right\} = 0.$$

By Theorem 2.2, we see that the hot spots H(t) tends to one point x_{∞} as $t \to \infty$ if $A_{\phi} \neq 0$, and see that (1.3) does not hold if $A_{\phi} \in \Omega$.

Next we will explain the outline of the proofs of Theorems 2.1 and 2.2. As in stated in [11], it is difficult to know the sign of differential of the Neumann heat kernel even for the case that Ω is the exterior of a ball, and so it seems difficult to obtain Theorems 2.1 and 2.2 by using the fundamental properties of the Neumann heat kernel. We consider the following two eigenvalue problems,

(E)
$$\begin{cases} P_0 \varphi \equiv \frac{1}{\rho} \operatorname{div} (\rho \nabla \varphi) = -\lambda \varphi & \text{in } \mathbf{R}^N, \\ \varphi \in H^1(\mathbf{R}^N, \rho dy), \quad \rho(y) = \exp\left(\frac{|y|^2}{4}\right), \end{cases}$$

and

$$(2.4) -\Delta_{\mathbf{S}^{N-1}}Q = \omega Q \text{on } \mathbf{S}^{N-1},$$

such that $0 = \omega_0 < \omega_1 = N-1 < \omega_2 = 2N < \omega_3 < \cdots$, where $\Delta_{\mathbf{S}^{N-1}}$ is the Laplace-Beltrami operator on \mathbf{S}^{N-1} . Let l_k be the dimension of the eigenspace of the eigenvalue problem (2.4) corresponding to $\omega = \omega_k$ and $\{Q_{k,i}\}_{i=1}^{l_k}$ the eigenfunctions of (2.4) corresponding to $\omega = \omega_k$ such that $(Q_{k,i},Q_{k,j})_{L^2(\mathbf{S}^{N-1})} = \delta_{ij}, i,j=1,\ldots,l_k$. In particular we may take

(2.5)
$$Q_{1,i}\left(\frac{x}{|x|}\right) = c_q \frac{x_i}{|x|}, \qquad i = 1, \dots, N,$$

for some positive constant $c_q = c_q(N) > 0$. Furthermore we have the following lemma on the eigenfunctions of (E) (see [5] and [13]).

Lemma 2.1 Let $k = 0, 1, 2, \ldots$ Let $\{\lambda_{k,i}\}_{i=0}^{\infty}$ be the eigenvalues of

(E_k)
$$\begin{cases} P_k \varphi \equiv P_0 \varphi - \frac{\omega_k}{|y|^2} \varphi = -\lambda \varphi & in \ \mathbf{R}^N, \\ \varphi \text{ is a radial function in } \mathbf{R}^N, \\ \varphi \in L^2(\mathbf{R}^N, \rho dy), \end{cases}$$

such that $\lambda_{k,0} < \lambda_{k,1} < \lambda_{k,2} < \dots$ and $\varphi_{k,i}$ the eigenfunction corresponding to $\lambda_{k,i}$ such that $\|\varphi_{k,i}\|_{L^2(\Omega,\rho dx)} = 1$. Then

$$\lambda_{k,i} = \frac{N+k}{2} + i, \qquad \varphi_{k,0}(y) = c_k |y|^k \exp\left(-\frac{|y|^2}{4}\right)$$

for some constants c_k . Furthermore $\{\lambda_{k,i}\}_{k,i=0}^{\infty}$ give all eigenvalue of (E), and the eigenspace of (E) corresponding to λ are spanned by the eigenfunctions $\{\varphi_{k,i}(y)Q_{k,j}(y/|y|)\}_{j=1}^{l_k}$ with $\lambda = \lambda_{k,i}$.

In order to prove Theorems 2.1 and 2.2, we may assume, without loss of generarilty, that $\phi \in L^2(\Omega, \rho dx)$. Then, by Lemma 2.1, there exist radial functions $\{\phi_{k,j}\}_{k \in \mathbb{N} \cup \{0\}, j=1,\dots,l_k}$, such that $\phi_{k,i} \in L^2(\Omega, \rho dx)$ and

(2.6)
$$\phi = \sum_{k=0}^{\infty} \sum_{j=1}^{l_k} \phi_{k,j}(|x|) Q_{k,j}\left(\frac{x}{|x|}\right) \quad \text{in} \quad L^2(\Omega, \rho dx),$$

Furthermore let $v_{k,j}$ be the radial solution of the Cauhy-Neumann problem

$$(L_k^N) \qquad \begin{cases} \partial_t v = \mathcal{L}_k v \equiv \Delta v - \frac{\omega_k}{|x|^2} v_k & \text{in } \Omega \times (0, \infty), \\ \partial_\nu v = 0 & \text{on } \partial\Omega \times (0, \infty), \\ v(x, 0) = \phi_{k, j}(x) & \text{in } \Omega. \end{cases}$$

Then the function

$$v_{k,j}(x,t)Q_{k,j}\left(\frac{x}{|x|}\right)$$

is a solution of (1.1) with the initial data $\phi_{k,j}(x)Q_{k,j}(x/|x|)$. Furthermore we see that

$$u(x,t) = \sum_{k=0}^{\infty} \sum_{j=1}^{l_k} u_{k,j}(x,t)$$
 in $C^2(\overline{\Omega})$,

for all t > 0. Therefore we have only to study the asymptotic behavior of the radial solution of the Cauchy-Neumann problem (L_k^N) in order to study the one of the solution u of (1.1).

Let v_k be the solution of the Cauchy-Neumann problem (L_k^N) with the initial data φ , where φ is a radial function belonging to $L^2(\Omega, \rho dx)$. In order to study the asymptotic behavior of the solution v_k , we define a rescaled function w_k of the solution v_k as follows:

$$w_k(y,s) = (1+t)^{\frac{N+k}{2}} v_k(x,t), \quad y = (1+t)^{-\frac{1}{2}} x, \quad s = \log(1+t).$$

Then the function w_k satisfies

$$\begin{cases} \partial_s w_k = P_k w_k + \frac{N+k}{2} w_k & \text{in } W, \\ \partial_\nu w_k = 0 & \text{on } \partial W, \\ w_k(y,0) = \varphi(y) & \text{in } \Omega, \end{cases}$$

where

$$\Omega(s) = e^{-s/2}\Omega, \ W = \bigcup_{0 < s < \infty} (\Omega(s) \times \{s\}), \ \partial W = \bigcup_{0 < s < \infty} (\partial \Omega(s) \times \{s\}).$$

We study the asymptotic behavior of the first eigenvalue and the first eigenfunction of the operator P_k , and obtain the asymptotic behavior of the solution w_k in the space L^2 with weight ρ . Furthermore, for k=0,1,2, by using the radially symmetry of v_k , the equations (L_k^N) and (P_k^N) , and the Ascoli-Arzera theorem, we study the asymptotic behavior of v_k , $\partial_r v_k$, and $\partial_r^2 v_k$ as $t \to \infty$.

For the case k=0, we extend the domain of w_0 to \mathbf{R}^N , and apply the Ascoli-Arzera theorem to w_0 . Then, by using the results on the asymptotic behavior of w_0 in the space L^2 with weight ρ , we obtain a result on the asymptotic behavior of v_0 and $\partial_r v_0$, where r=|x|. Furthermore we obtain a result on the asymptotic behavior of $\partial_r^2 v_0$ as $t\to\infty$ by using the ones of v_0 and $\partial_r v_0$.

Proposition 2.1 Let φ be a radial function in Ω satisfying (2.1). Let v_0 be a radial solution of (L_0^N) with the initial data φ . Then

$$\lim_{t \to \infty} t^{\frac{N}{2}} v_0(x, t) = (4\pi)^{-\frac{N}{2}} \int_{\Omega} \varphi(x) dx$$

uniformly on any compact set in $\overline{\Omega}$. Furthermore, for any positive constants ϵ , there exist positive constants C, R, and T such that

$$\partial_r v_0(x,t) \le -Ct^{-\frac{N+1}{2}} \int_{\Omega} \varphi(x) dx$$

for all $x \in \Omega$ with $\epsilon(1+t)^{1/2} \le |x| \le R(1+t)^{1/2}$ and all $t \ge T$.

Proposition 2.2 Let φ be a radial function in Ω satisfying (2.1). Let v_0 be a radial solution of (L_0^N) with the initial data φ . Then there exist positive constant R and T such that

$$\partial_{\tau} v_0(x,t) \le -\frac{1}{4} (4\pi)^{-\frac{N}{2}} t^{-\frac{N+2}{2}} (|x| - L) \int_{\Omega} \varphi(x) dx$$

for all $x \in \Omega$ with $|x| \le L + R(1+t)^{1/2}$ and $t \ge T$, where r = |x|. Furthermore, for any R > L,

$$\begin{split} &\partial_r v_0(x,t) \\ &= -\frac{1}{2} (4\pi)^{-\frac{N}{2}} (1+o(1)) |x| (1-L^N|x|^{-N}) t^{-\frac{N+2}{2}} \int_{\Omega} \varphi(x) dx, \\ &\partial_r^2 v_0(x,t) \\ &= -\frac{1}{2} (4\pi)^{-\frac{N}{2}} (1+o(1)) (1+(N-1)L^N r^{-N}) t^{-\frac{N+2}{2}} \int_{\Omega} \varphi(x) dx \end{split}$$

as $t \to \infty$, uniformly on $\Omega \cap B(0,R)$.

On the other hand, for the case k = 1, the inequality

$$\sup_{s>1} \|\nabla_y^2 w_1(\cdot, s)\|_{C(\Omega(s))} < \infty$$

does not necessarily holds, and w(y,s) tends to 0 uniformly for all y with $|y| \leq Re^{-s/2}$ with any R > L. So it is not useful to apply the Ascoli-Arzera theorem to w_1 for the aim at studying the asymptotic behavior of w_1 and $\partial_r w_1$ in the domain $\{y \in \Omega(s) : |y| \leq Re^{-s/2}\}$, as $s \to \infty$. To overcome this difficulty, we may apply the Ascoli-Arzera theorem w_1 in the any annulus $D(\epsilon, R) = \{y \in \mathbf{R}^N : \epsilon \leq |y| \leq R\}$ with $0 < \epsilon < R$, and obtain the asymptotic behavior of w_1 in the annulus $D(\epsilon, R)$. Furthermore, by using the equation (L_1) effectively, we study the asymptotic behavior of v_1 , $\partial_r v_1$ and $\partial_r^2 v_1$ as $t \to \infty$, and obtain the following proposition.

Proposition 2.3 Let φ be a radial function in Ω satisfying (2.1). Let v_1 be a radial solution of (L_1^N) with the initial data φ . Put

$$U_L^N(r) = c_1 r \left(1 + \frac{L^N}{N-1} r^{-N} \right), \quad a_{\varphi}^N = \int_{\Omega} \varphi(x) U_L^N(|x|) dx.$$

Then there exists a positive constant C such that

$$\|\nabla v_1(x,t)\|_{L^{\infty}(\Omega)} \le C_1(|a_{\varphi}^N| + o(1))t^{-\frac{N+2}{2}}$$

for sufficiently large t. Furthermore, for any R > L,

$$\begin{array}{rcl} v_1(x,t) & = & (a_{\varphi}^N + o(1))U_L^N t^{-\frac{N+2}{2}}, \\ \partial_r v_1(x,t) & = & c_1(a_{\varphi}^N + o(1))\left(1 - L^N r^{-N}\right)t^{-\frac{N+2}{2}}, \\ \partial_r^2 v_1(x,t) & = & c_1(a_{\varphi}^N + o(1))NL^N r^{-(N+1)}t^{-\frac{N+2}{2}}, \end{array}$$

as $t \to \infty$, uniformly on $\Omega \cap B(0,R)$.

Similarly we study the asymptotic behavior of v_2 , $\partial_r v_2$ and $\partial_r^2 v_2$ as $t \to \infty$, and obtain the following proposition.

Proposition 2.4 Let φ be a radial function in Ω satisfying (2.1). Let v_2 be a radial solution of (L_2^N) with the initial data φ . Then there exists a positive constant C_1 such that

$$\|v_2(\cdot,t)\|_{L^{\infty}(\Omega)} \le C_1 t^{-\frac{N+2}{2}},$$

 $\|\partial_{\tau} v_2(\cdot,t)\|_{L^{\infty}(\Omega)} \le C_1 t^{-\frac{N+3}{2}},$

for sufficiently large t. Furthermore, for any R > L, there exists a constant C_2 such that

$$|\partial_r^2 v_2(x,t)| \le C_2 t^{-\frac{N+3}{2}}$$

for all $x \in \Omega$ with $|x| \leq R$ and all sufficiently large t.

By Propositions 2.1–2.4, we may obtain the asymptotic behavior of the solutions $u_{k,j}$, $k = 0, 1, 2, j = 1, ..., l_k$. Finally, by (2.6), we put

(2.7)
$$\phi_3 = \phi - \sum_{k=0}^{2} \sum_{j=1}^{l_k} \phi_{k,j}(|x|) Q_{k,j}\left(\frac{x}{|x|}\right),$$

and study the solution of (1.1) with the initial data ϕ_3 . Then we have

Proposition 2.5 Assume (2.1). Let ϕ_3 be a function defined by (2.6) and (2.7). Let u_3 be a function of (1.1) with the initial data ϕ_3 . Then there exists a constant C such that

$$\|\nabla_x^k u_3(\cdot,t)\|_{L^{\infty}(\Omega)} \le Ct^{-\frac{N+3}{2}}, \quad k=0,1,2,$$

for all sufficiently large t.

By Propositions 2.1–2.5, we obtain the asymptotic behavior of u, $\nabla_x u$, and $\nabla_x^2 u$ as $t \to \infty$, and may obtain Theorems 2.1 and 2.2.

3 On the Cauchy-Neumann Problem (1.2)

In this section we assume that

(3.1)
$$\phi \in L^2(\Omega, \rho dx), \quad m_{\phi} > 0,$$

where $\rho(x) = \exp(|x|^2/4)$ and

$$m_{\phi} = \begin{cases} \int_{\Omega} \phi(x) \left(1 - \frac{L^{N-2}}{|x|^{N-2}} \right) dx & \text{if } N \ge 3, \\ \int_{\Omega} \phi(x) \log \frac{|x|}{L} dx & \text{if } N \ge 2. \end{cases}$$

We first give the following results on the asymptotic behavior of the solution u of (1.2), which imply that the hot spots H(t) run away from the boundary $\partial\Omega$ as $t\to\infty$.

Theorem 3.1 (See Theorem 1.1 in [9].)

Let u be a solution of the Cauchy-Dirichlet problem (1.2) under the condition (3.1) and $N \geq 3$. Then

(3.2)
$$\lim_{t \to \infty} \int_{\Omega} u(x, t) dx = m_{\phi} > 0$$

and

(3.3)
$$\lim_{t \to \infty} t^{\frac{N}{2}} u(x,t) = (4\pi)^{-\frac{N}{2}} m_{\phi} \left(1 - \frac{L^{N-2}}{|x|^{N-2}} \right)$$

uniformly for all x on any compact set in $\overline{\Omega}$.

Theorem 3.2 (See Theorem 1.2 in [9].)

Let u be a solution of the Cauchy-Dirichlet problem (1.2) under the condition (3.1) and N=2. Then there exists a constant C such that

(3.4)
$$||u(\cdot,t)||_{L^1(\Omega)} \le C(\log t)^{-1} ||\phi||_{L^2(\Omega,\rho dx)}$$

for all $t \geq 1$. Furthermore

(3.5)
$$\lim_{t \to \infty} (\log t) \int_{\Omega} u(x, t) dx = 2m_{\phi}$$

and

(3.6)
$$\lim_{t \to \infty} t(\log t)^2 u(x,t) = \frac{1}{\pi} m_{\phi} \log \frac{|x|}{L}$$

uniformly for all x on any compact set in $\overline{\Omega}$.

Remark 3.1 Collet, Martínes, and Martín [4] used the probability method to prove the asymptotic behavior of the Dirichlet heat kernel G = G(x, y, t) on the exterior domain of a compact set as $t \to \infty$. In particular, for the exterior domain $\mathbb{R}^N \setminus \overline{B(0, L)}$, they obtained that

$$(3.7) \quad \lim_{t \to \infty} t^{\frac{N}{2}} G(x, y, t) = (4\pi)^{-\frac{N}{2}} \left(1 - \frac{L^{N-2}}{|x|^{N-2}} \right) \left(1 - \frac{L^{N-2}}{|y|^{N-2}} \right) \text{ if } N \ge 3,$$

(3.8)
$$\lim_{t \to \infty} t(\log t)^2 G(x, y, t) = \frac{1}{\pi} \log \frac{|x|}{L} \log \frac{|y|}{L}$$
 if $N = 2$,

for all $x, y \in \Omega$ (see also [6]). By (3.3) and (3.6), we may obtain (3.7) and (3.8), and the proof of this paper is complete different from the one of [4]. Furthermore we remark that Herraiz [7] applied the comparison method to the Cauchy-Dirichlet problem (1.2) in the exterior domain of a compact set, and obtained the similar results to Theorems 3.1 and 3.2 for nonnegative initial data ϕ .

Next we give a result on the rate for the hot spots H(t) to run away from the boundary Ω as $t \to \infty$.

Theorem 3.3 (See Theorem 1.3 in [9].)

Let u be a solution of the Cauchy-Dirichlet problem (1.2) under the condition (3.1). Put

$$\zeta(t) = 2(N-2)L^{N-2}t$$
 if $N \ge 3$, $\zeta(t) = 2t(\log t)^{-1}$ if $N = 2$.

Then
$$\lim_{t \to \infty} \sup_{x \in H(t)} \left| \zeta(t)^{-1} |x|^N - 1 \right| = 0.$$

Furthermore there exists a positive constant T such that, if $x \in H(t)$ and $t \geq T$, then

$$(3.10) H(t) \cap l_x = \{x\},$$

where $l_x = \{kx/|x| : k > 0\}.$

Next we give a sufficient condition for the hot spots H(t) to consist of one point x(t) after a finite time. Furthermore we give the limit of x(t)/|x(t)| as $t \to \infty$.

Theorem 3.4 (See Theorem 1.4 in [9].)

Let u be a solution of the Cauchy-Dirichlet problem (1.2) under the condition (3.1). Assume that

$$A_{\phi}^{D} \equiv \int_{\Omega} x \phi(x) \left(1 - \frac{L^{N}}{|x|^{N}} \right) dx \neq 0.$$

Then there exist a positive constant T and a smooth curve $x=x(t)\in C^{\infty}([T,\infty):\Omega)$ such that $H(t)=\{x(t)\}$ for all $t\geq T$ and

(3.11)
$$\lim_{t \to \infty} \frac{x(t)}{|x(t)|} = \frac{A_{\phi}^D}{|A_{\phi}^D|}.$$

Therefore, by Theorems 3.3 and 3.4, we see that, under the assumptions (3.1) and $A_{\phi}^{D} \neq 0$, the set of hot spots H(t) consists of one points x(t) after a finite time, and

$$\lim_{t \to \infty} \zeta(t)^{-1/N} |x(t)| = 1, \qquad \lim_{t \to \infty} x(t) / |x(t)| = A_{\phi}^{D} / |A_{\phi}^{D}|.$$

Next we explain the outline of the proofs of Theorems 3.1–3.3. In the similar way to the Cauchy-Neumann problem (1.1), we have only to study the asymptotic behavior of the radial solutions v_k of the Cauchy-Dirichlet problem

$$(L_k^D) \qquad \begin{cases} \partial_t v = \mathcal{L}_k v \equiv \Delta v - \frac{\omega_k}{|x|^2} v_k & \text{in } \Omega \times (0, \infty), \\ v = 0 & \text{on } \partial\Omega \times (0, \infty), \\ v(x, 0) = \varphi(x) & \text{in } \Omega, \end{cases}$$

where φ is a radial function belonging to $L^2(\Omega, \rho dx)$ and $k = 0, 1, 2 \dots$ Furthermore, by the same argument with in the Cauchy-Neumann problem (1.1), we introduce a rescaled function w_k of v_k , and study the asymptotic behavior of the rescaled functions w_k as $s \to \infty$. For the case $N \geq 3$, we study the asymptotic behavior of $w_0 = w_0(y, s)$ in the space L^2 with weight ρ , and obtain the one of $v_0 = v_0(x, t)$ for all $x \in \Omega$ with $|x| \sim t^{1/2}$ as $t \to \infty$. Furthermore, by using the radially symmetry of v_0 and v_0 , we obtain the asymptotic behavior of v_0 , v_0 , v_0 , v_0 , v_0 , v_0 , and v_0 for all v_0 with v_0 as v_0 , we obtain the asymptotic behavior of v_0 , v_0 , v_0 , v_0 , v_0 , and v_0 for all v_0 with v_0 as v_0 ,

Proposition 3.1 Let φ be a radial function in Ω satisfying (2.1). Let v_0 be a radial solution of (L_0^D) with the initial data φ and $N \geq 3$. Put

$$U_L^{D,0}(r) = c_0 \left(1 - \frac{L^{N-2}}{r^{N-2}} \right), \quad a_{\varphi}^{D,0} = \int_{\Omega} \varphi(x) U_L^{D,0}(|x|) dx.$$

Then there hold that

$$\begin{split} v_0^\star(r,t) &= t^{-\frac{N}{2}}(a_\varphi^{D,0}+o(1))U_L^0(r) + \frac{N}{2}t^{-\frac{N+2}{2}}(a_0+o(1))O(r^2) \\ &\quad + O(t^{-\frac{N+4}{2}})O(r^4), \\ (\partial_r v_0^\star)(r,t) &= t^{-\frac{N}{2}}(a_\varphi^{D,0}+o(1))\partial_r U_L^0(r) \\ &\quad - \frac{Nc_0}{4}rt^{-\frac{N+2}{2}}(a_\varphi^{D,0}+o(1))(1+O(r^{-1})) + O(t^{-\frac{N+4}{2}})O(r^3), \\ (\partial_r^2 v_0^\star)(r,t) &= t^{-\frac{N}{2}}(a_\varphi^{D,0}+o(1))\partial_r^2 U_L^0(r) - U_L^0(r)\frac{N}{2}t^{-\frac{N+2}{2}}(a_\varphi^{D,0}+o(1)) \\ &\quad + O(t^{-\frac{N+4}{2}})O(r^2), \\ (\partial_t v_0^\star)(r,t) &= -\frac{N}{2}t^{-\frac{N+2}{2}}(a_\varphi^{D,0}+o(1))U_L^0(r) + O(t^{-\frac{N+4}{2}})O(r^2) \end{split}$$

for all $r \geq L$ and $t \geq 1$.

For the case N=2, the behavior of v_0 is different from the one for the case $N\geq 3$. By the similar way to in the case $N\geq 3$, we first obtain $\max_{x\in\partial\Omega}|\partial_r v_0(x,t)|=O(t^{-1}(\log t)^{-1})$ as $t\to\infty$. This gives that $\|v_0(\cdot,t)\|_{L^1(\Omega)}=O((\log t)^{-1})$ as $t\to\infty$. By using the similar argument to in the case $N\geq 3$ again, we have $\max_{x\in\partial\Omega}|\partial_r v_0(x,t)|=O(t^{-1}(\log t)^{-2})$ as $t\to\infty$, and obtain the following proposition.

Proposition 3.2 Let φ be a radial function in Ω satisfying (2.1). Let v_0 be a radial solution of (L_0^D) with the initial data φ and N=2. Put

$$\tilde{a}_{\varphi}^{D,0} = 4c_0^2 \int_{\Omega} \varphi(x) \log \frac{|x|}{L} dx.$$

Then there exists a function $\zeta_1 = \zeta_1(t)$ and $\zeta_2(t)$ with

$$\lim_{t \to \infty} t(\log t)^2 \zeta_1(t) = \tilde{a}_{\varphi}^{D,0}, \qquad \lim_{t \to \infty} t^2 (\log t)^2 \zeta_2(t) = \tilde{a}_{\varphi}^{D,0},$$

such that

$$v_{0}(r,t) = \zeta_{1}(t) \log \frac{r}{L} + O(r^{2} \log r) \zeta_{1}(t) + O(r^{4}) O(t^{-3} (\log t)^{-1}),$$

$$(\partial_{r} v_{0})(r,t) = \frac{\zeta_{1}(t)}{r} - \zeta_{1}(t) r \log r (1 + o(1)) + O(r^{3}) O(t^{-3} (\log t)^{-1}),$$

$$(\partial_{r}^{2} v_{0})(r,t) = -\frac{\zeta_{1}(t)}{r^{2}} - U_{L}^{0}(r) \zeta_{1}(t) + O(r^{2}) O(t^{-3} (\log t)^{-1}),$$

$$(\partial_{t} v_{0})(r,t) = -\left(\log \frac{r}{L}\right) \zeta_{2}(t) + O(r^{2}) O(t^{-3} (\log t)^{-1})$$

for all $r \geq L$ and $t \geq 2$.

Furthermore, by the similar argument to the problem (1.1), we obtain the asymptotic behavior of the solutions v_1 and v_2 .

Proposition 3.3 Let φ be a radial function in Ω satisfying (2.1). Let v_1 be a radial solution of (L_1^D) with the initial data φ and $N \geq 2$. Put

$$U_L^{D,1}(r) = c_1 r \left(1 - \frac{L^N}{r^N}\right), \quad a_{\varphi}^{D,1} = \int_{\Omega} \varphi(x) U_L^{D,1}(|x|) dx.$$

Then there hold that

$$\begin{split} v_1^*(r,t) &= t^{-\frac{N+2}{2}}(a_\varphi^{D,1}+o(1))U_L^1(r)+O(r^2)O(t^{-\frac{N+3}{2}}),\\ \partial_r v_1^*(r,t) &= t^{-\frac{N+2}{2}}(a_\varphi^{D,1}+o(1))\partial_r U_L^1(r)+O(r)O(t^{-\frac{N+3}{2}}),\\ \partial_r^2 v_1^*(r,t) &= t^{-\frac{N+2}{2}}(a_\varphi^{D,1}+o(1))\partial_r^2 U_L^1(r)+O(t^{-\frac{N+3}{2}}) \end{split}$$

for all $r \ge L$ and t > 1.

Proposition 3.4 Let φ be a radial function in Ω satisfying (2.1). Let v_2 be a radial solution of (L_2^D) with the initial data φ and $N \geq 2$. Then there hold that

$$\begin{array}{rcl} v_2^{\star}(r,t) & = & O(t^{-\frac{N+4}{2}}\log t)U_L^{D,2}(r) + O(t^{-\frac{N+4}{2}})O(r^2\log r), \\ \partial_r v_2^{\star}(r,t) & = & O(t^{-\frac{N+4}{2}}\log t)\partial_r U_L^{D,2}(r) + O(t^{-\frac{N+4}{2}})r\log\frac{r}{L}, \\ \partial_r^2 v_2^{\star}(r,t) & = & O(t^{-\frac{N+4}{2}}\log t)\partial_r^2 U_L^{D,2}(r) + O(t^{-\frac{N+4}{2}})\log\frac{r}{L}, \end{array}$$

for all $r \geq L$ and t > 1, where

$$U_L^{D,2}(r) = c_2 r^2 \left(1 - \frac{L^{N+2}}{r^{N+2}} \right).$$

Therefore, by the similar argument to the problem (1.1) and Propositions 3.1--3.4, we may prove Theorems 3.1--3.3. In order to prove Theorem 3.4, we study the asymptotic behavior of x/|x| for all $x \in H(t)$ and all sufficiently large t, by using the asymptotic behavior of v_0 and v_1 . Furthermore we compare the hot spots H(t) with the radial solution of (1.2) with the initial data $\varphi \in L^2(\Omega, \rho dx)$ with $m_{\varphi} = m_{\phi}$. Then we may prove that, if t is sufficiently large, then the matrix $\{-\partial_{x_i}\partial_{x_j}u(x,t)\}_{i,j=1}^N$ is positive definite for all points near the hot spots H(t), and complete the proof Theorem 3.4.

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