SOME RESULTS ON SET-VALUED STOCHASTIC INTEGRALS WITH RESPECT TO POISSON JUMP IN AN M-TYPE 2 BANACH SPACE

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1. Introduction

Probability theory is an important tool of modeling randomness in a practical problem. But besides randomness, in the real world, there exists other kind of uncertainties such as impreciseness or vagueness. Set-valued functions are employed to model the impreciseness in applied field such as in Economics, control theory (see for example [1]). Integrals of set-valued functions have been received much attention with widespread applications, see for example [2, 7, 9, 10] etc. Recently, stochastic integrals for set-valued stochastic processes with respect to the Brownian motion and martingales have been received much attention, e.g. see [12, 13, 18, 23, 32, 37]. Correspondingly, the set-valued stochastic differential equations are studied, e.g. see [23, 25, 33, 34, 35, 36]. Michta (2011) [22] extended the integrator to a larger class: semimartingales. But the integrably boundedness of the corresponding set-valued stochastic integrals are not obtained since the semimartingales may not be of finite variation. In such cases, the set-valued stochastic integrals may not be well defined as Ogura pointed out [25].

The Poisson stochastic processes are special. They play important roles both in the random mathematics (c.f. [11, 8, 17]) and in applied fields, for example, in the financial mathematics [17]. If the characteristic measure ν of a stationary Poisson process \mathbf{p} is finite, then both of the Poisson random measure N(dsdz) (where $z \in Z$, the state space of \mathbf{p}) and the compensated Poisson random measure $\tilde{N}(dsdz)$ are of finite variation a.s. We will give some results (without giving proof since the page limitation) on the set-valued stochastic integrals with respect to the Poisson random measure N(dsdz), $\tilde{N}(dsdz)$. For the detail proof, the reader can refer to [31, 38]. For example, the stochastic integrals for set-valued \mathscr{S} -predictable (see Definition 3.2) processes with respect to N(dsdz) and $\tilde{N}(dsdz)$ are L^2 -integrably bounded. For Brownian or Martingale integrator with continuous part, the integrable boundedness are not obtained until now. Furthermore, if the σ -algebra \mathcal{F} is separable, then the integral $\{I_t(F)\}$ of convex set-valued stochastic process will not become a set-valued martingale, which is very different from single valued case. We would like to pointed out that there is a gap in the proof of Theorem 3.7 in [31] about the set-valued martingale property of set-valued stochastic integral with respect to the compensated Poisson measure, which is corrected and proven in [38].

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This paper is organized as follows: In Section 2 we give the notations and the preliminaries in the set-valued theory. Section 3 is on the definitions and results of stochastic integrals for set-valued \mathscr{S} -predictable processes with respect to N(dsdz) and $\tilde{N}(dsdz)$.

2. Preliminaries

Let (Ω, \mathcal{F}, P) be a complete probability space, $\{\mathcal{F}_t\}_{t\geq 0}$ a filtration satisfying the usual conditions, that is: \mathcal{F}_0 includes all P-null sets in \mathcal{F} , the filtration is non-decreasing and right continuous. Let $\mathcal{B}(E)$ be the Borel field of a topological space E, $(X, \|\cdot\|)$ a separable Banach space equipped with the norm $\|\cdot\|$ and $\mathbf{K}(\mathbf{X})$ (resp. $\mathbf{K_b}(\mathbf{X})$, $\mathbf{K_c}(\mathbf{X})$) the family of all nonempty closed (resp. closed bounded, closed convex) subsets of X. Let $1 \leq p < +\infty$ and $L^p(\Omega, \mathcal{F}, P; X)$ (denoted briefly by $L^p(\Omega; X)$) be the Banach space of equivalence classes of X-valued \mathcal{F} -measurable functions $f: \Omega \to X$ such that the norm

$$||f||_p = \left\{ \int_{\Omega} ||f(\omega)||^p dP \right\}^{1/p}$$

is finite. An X-valued function f is called L^p -integrable if $f \in L^p(\Omega; X)$.

A set-valued function $F: \Omega \to \mathbf{K}(X)$ is said to be *measurable* if for any open set $O \subset X$, the inverse $F^{-1}(O) := \{ \omega \in \Omega : F(\omega) \cap O \neq \emptyset \}$ belongs to \mathcal{F} . Such a function F is called a *set-valued random variable*. Let $\mathcal{M}(\Omega, \mathcal{F}, P; \mathbf{K}(X))$ be the family of all set-valued random variables, which is briefly denoted by $\mathcal{M}(\Omega; \mathbf{K}(X))$.

For any open subset $O \subset X$, set

$$Z_O := \{ E \in \mathbf{K}(X) : E \cap O \neq \emptyset \},\$$

$$\mathcal{C} := \{Z_O : O \subset X, O \text{ is open}\},\$$

and let $\sigma(\mathcal{C})$ be the σ -algebra generated by \mathcal{C} .

A set-valued function $F: \Omega \to \mathbf{K}(\mathbf{X})$ is measurable if and only if F is $\mathcal{F}/\sigma(\mathcal{C})$ -measurable. For $A, B \in 2^X$ (the power set of X), $H(A, B) \geq 0$ is defined by

$$H(A,B) := \max \{ \sup_{x \in A} \inf_{y \in B} ||x-y||, \sup_{y \in B} \inf_{x \in A} ||x-y|| \}.$$

H(A, B) for $A, B \in \mathbf{K}_b(X)$ is called the *Hausdorff metric*. It is well-known that $\mathbf{K}_b(\mathbf{X})$ equipped with the *H*-metric denoted by $((\mathbf{K}_b(X), H))$ is a complete metric space.

The following results are also well-known. (see e.g. [9], [19], [24]).

PROPOSITION 2.1. (i) For $A, B, C, D \in \mathbf{K}(\mathbf{X})$, we have

$$H(A+B,C+D) \le H(A,C) + H(B,D),$$

$$H(A \oplus B, C \oplus D) = H(A + B, C + D),$$

where $A \oplus B := cl\{a + b; a \in A, b \in B\}$.

(ii) For $A, B \in \mathbf{K}(\mathbf{X})$, $\mu \in \mathbb{R}$, we have

$$H(\mu A, \mu B) = |\mu| H(A, B).$$

For $F \in \mathcal{M}(\Omega, \mathbf{K}(X))$, the family of all L^p-integrable selections is defined by

$$S_F^p(\mathcal{F}) := \{ f \in L^p(\Omega, \mathcal{F}, P; X) : f(\omega) \in F(\omega) \ a.s. \}.$$

In the following, $S_F^p(\mathcal{F})$ is denoted briefly by S_F^p . If S_F^p is nonempty, F is said to be L^p -integrable. F is called L^p -integrably bounded if there exits a function $h \in L^p(\Omega, \mathcal{F}, P; \mathbb{R})$ such that $||x|| \leq h(\omega)$ for any x and ω with $x \in F(\omega)$. It is equivalent to that $||F||_{\mathbf{K}} \in L^p(\Omega; \mathbb{R})$, where $||F(\omega)||_{\mathbf{K}} := \sup_{a \in F(\omega)} ||a||$. The family of all measurable $\mathbf{K}(\mathbf{X})$ -valued L^p -integrably bounded functions is denoted by $L^p(\Omega, \mathcal{F}, P; \mathbf{K}(X))$. Write it for brevity as $L^p(\Omega; \mathbf{K}(X))$.

The integral (or expectation) of a set-valued random variable F was defined by Aumann in 1965 ([2]):

$$E[F] := \{ E[f] : f \in S_F^1 \}.$$

PROPOSITION 2.2. ([35]) Let $F \in \mathcal{M}(\Omega; X)$, $1 \leq p < +\infty$. Then F is L^p -integrably bounded if and only if S_F^p is nonempty and bounded in $L^p(\Omega; X)$.

Let \mathbb{R}_+ be the set of all nonnegative real numbers and $\mathcal{B}_+ := \mathcal{B}(\mathbb{R}_+)$. \mathbb{N} denotes the set of natural numbers. An X-valued stochastic process $f = \{f_t : t \geq 0\}$ (or denoted by $f = \{f(t) : t \geq 0\}$) is defined as a function $f : \mathbb{R}_+ \times \Omega \longrightarrow X$ with the \mathcal{F} -measurable section f_t , for $t \geq 0$. We say f is measurable if f is $\mathcal{B}_+ \otimes \mathcal{F}$ -measurable. The process $f = \{f_t : t \geq 0\}$ is called \mathcal{F}_t -adapted if f_t is \mathcal{F}_t -measurable for every $t \geq 0$. $f = \{f_t : t \geq 0\}$ is called predictable if it is \mathcal{P} -measurable, where \mathcal{P} is the σ -algebra generated by all left continuous and \mathcal{F}_t -adapted stochastic processes.

In a fashion similar to the X-valued stochastic process, a set-valued stochastic process $F = \{F_t : t \geq 0\}$ is defined as a set-valued function $F : \mathbb{R}_+ \times \Omega \longrightarrow \mathbf{K}(\mathbf{X})$ with \mathcal{F} -measurable section F_t for $t \geq 0$. It is called measurable if it is $\mathcal{B}_+ \otimes \mathcal{F}$ -measurable, and \mathcal{F}_t -adapted if for any fixed t, $F_t(\cdot)$ is \mathcal{F}_t -measurable. $F = \{F_t : t \geq 0\}$ is called predictable if it is \mathcal{P} -measurable.

DEFINITION 2.3. (see [9]) An integrable bounded convex set-valued \mathcal{F}_t -adapted stochastic process $\{F_t, \mathcal{F}_t : t \geq 0\}$ is called a set-valued \mathcal{F}_t -martingale if for any $0 \leq s \leq t$ it holds that $E[F_t|\mathcal{F}_s] = F_s$ in the sense of $S^1_{E[F_t|\mathcal{F}_s]}(\mathcal{F}_s) = S^1_{F_s}(\mathcal{F}_s)$.

It is called a set-valued submartingale (supermartingale) if for any $0 \le s \le t$, $E[F_t|\mathcal{F}_s] \supset F_s$ (resp. $E[F_t|\mathcal{F}_s] \subset F_s$) in the sense of $S^1_{E[F_t|\mathcal{F}_s]}(\mathcal{F}_s) \supset S^1_{F_s}(\mathcal{F}_s)$ (resp. $S^1_{E[F_t|\mathcal{F}_s]}(\mathcal{F}_s) \subset S^1_{F_s}(\mathcal{F}_s)$).

3. STOCHASTIC INTEGRALS WITH RESPECT TO POISSON POINT PROCESSES

3.1. Single Valued Stochastic Integrals w.r.t. Poisson Point Processes. Let X be a separable Banach space and Z be another separable Banach space with σ -algebra $\mathcal{B}(Z)$. A point function \mathbf{p} on Z means a mapping $\mathbf{p}: \mathbf{D_p} \to Z$, where the domain $\mathbf{D_p}$ is a countable subset of [0,T]. \mathbf{p} defines a counting measure $N_{\mathbf{p}}(dtdz)$ on $[0,T] \times Z$ (with the product σ -algebra $\mathcal{B}([0,T]) \otimes \mathcal{B}(Z)$) by

(3.1)
$$N_{\mathbf{p}}((0,t],U) := \#\{\tau \in \mathbf{D}_{\mathbf{p}} : \tau \le t, \mathbf{p}(\tau) \in U\}, \\ t \in (0,T], \ U \in \mathcal{B}(Z).$$

For 0 < s < t < T,

(3.2)
$$N_{\mathbf{p}}((s,t],U) := N_{\mathbf{p}}((0,t],U) - N_{\mathbf{p}}((0,s],U).$$

In the following, we also write $N_{\mathbf{p}}((0,t],U)$ as $N_{\mathbf{p}}(t,U)$.

A point process is obtained by randomizing the notion of point functions. If there is a continuous \mathcal{F}_t -adapted increasing process $\hat{N}_{\mathbf{p}}$ such that for $U \in \mathcal{B}(Z)$ and $t \in [0,T]$, $\tilde{N}_{\mathbf{p}}(t,U) := N_{\mathbf{p}}(t,U) - \hat{N}_{\mathbf{p}}(t,U)$ is an \mathcal{F}_t -martingale, then the random measure $\{\hat{N}_{\mathbf{p}}(t,U)\}$ is called the compensator of the point process \mathbf{p} (or $\{N_{\mathbf{p}}(t,U)\}$) and the process $\{\tilde{N}_{\mathbf{p}}(t,U)\}$ is called the compensated point process.

A point process p is called the *Poisson Point Process* if $N_{\mathbf{p}}(dtdz)$ is a Poisson random measure on $[0,T]\times Z$. A Poisson point process is stationary if and only if its intensity measure $\nu_{\mathbf{p}}(dtdz) = E[N_{\mathbf{p}}(dtdz)]$ is of the form

(3.3)
$$\nu_{\mathbf{p}}(dtdz) = dt\nu(dz)$$

for some measure $\nu(dz)$ on $(Z,\mathcal{B}(Z))$. $\nu(dz)$ is called the *characteristic measure of* **p**.

Let ν be a σ - finite measure on $(Z, \mathcal{B}(Z))$, (i.e. there exists $U_i \in \mathcal{B}(Z)$, $i \in \mathbb{N}$, pairwise disjoint such that $\nu(U_i) < \infty$ for all $i \in \mathbb{N}$ and $Z = \bigcup_{i=1}^{\infty} U_i$, $\mathbf{p} = (\mathbf{p}_t)$ be the \mathcal{F}_t -adapted stationary Poisson point process on Z with the characteristic measure ν such that the compensator $\hat{N}_{\mathbf{p}}(t,U) = E[N_{\mathbf{p}}(t,U)] = t\nu(U)$ (non-random).

The above definitions and notations of Poisson point processes come from [11] and [30]. For convenience, we will omit the subscript \mathbf{p} in the above notations.

PROPOSITION 3.1. ([31]) Assume $\nu(Z)$ is finite. Then for any $U \in \mathcal{B}(Z)$, both $\{N(t,U), t \in [0,T]\}$ and $\{\tilde{N}(t,U), t \in [0,T]\}$ are stochastic processes with finite variation a.s.

For convenience, from now on, we suppose ν is a finite measure in the measurable space $(Z, \mathcal{B}(Z))$.

DEFINITION 3.2. An X-valued mapping $f(t,z,\omega)$ defined on $[0,T]\times Z\times \Omega$ is called \mathscr{S} -predictable if the mapping $(t,z,\omega)\to f(t,z,\omega)$ is $\mathscr{S}/\mathcal{B}(X)$ -measurable, where \mathscr{S} is the smallest σ -algebra on $[0,T]\times Z\times \Omega$ with respect to which all mappings $g:[0,T]\times Z\times \Omega\to X$ satisfying (i) and (ii) below are measurable:

- (i) for each $t \in [0,T]$, the mapping $(z,\omega) \to g(t,z,\omega)$ is $\mathcal{B}(Z) \otimes \mathcal{F}_t$ -measurable;
- (ii) for each $(z, \omega) \in Z \times \Omega$, the mapping $t \to g(t, z, \omega)$ is left continuous.

REMARK 3.3. (see e.g. [30]) $\mathcal{S} = \mathcal{P} \otimes \mathcal{B}(Z)$, where \mathcal{P} denotes the σ -field on $[0, t] \times \Omega$ generated by all left continuous and \mathcal{F}_t -adapted processes.

Set

$$\mathscr{L} = \left\{ f(t,z,\omega) : f \ is \ \mathscr{S}-predictable \ and
ight. \ \left. E\left[\int_0^T \int_Z \|f(t,z,\omega)\|^2
u(dz) dt
ight] < \infty
ight\}$$

equipped with the norm

$$\|f\|_{\mathscr{L}}:=\Big(E\Big[\int_0^T\int_Z\|f(t,z,\omega)\|^2
u(dz)dt\Big]\Big)^{1/2}.$$

Let $\mathbb S$ be the subspace of those $f \in \mathscr L$ for which there exists a partition $0 = t_0 < t_1 < \cdots < t_n = T$ of of [0,T] such that

$$f(t,z,\omega) = f(0,z,\omega)\chi_{\{0\}}(t) + \sum_{i=1}^{n}\chi_{(t_{i-1},t_i]}(t)f(t_{i-1},z,\omega).$$

Let f be in S and

(3.4)
$$f(t,z,\omega) = f(0,z,\omega)\chi_{\{0\}}(t) + \sum_{i=1}^{n} \chi_{(t_{i-1},t_i]}(t)f(t_{i-1},z,\omega),$$

where $0 = t_0 < t_1 < \cdots < t_n = T$ is a partition of [0, T]. Define

(3.5)
$$J_T(f) = \int_0^{T+} \int_Z f(s-,z,\omega) N(dtdz)$$
$$:= \sum_{i=1}^n \int_Z f(t_{i-1},z,\omega) N((t_{i-1},t_i],dz),$$

and

(3.6)
$$I_{T}(f) = \int_{0}^{T+} \int_{Z} f(s-,z,\omega) \tilde{N}(dtdz)$$
$$:= \sum_{i=1}^{n} \int_{Z} f(t_{i-1},z,\omega) \tilde{N}((t_{i-1},t_{i}],dz),$$

where $\int_Z f(t_{i-1}, z, \omega) N((t_{i-1}, t_i], dz)$ and $\int_Z f(t_{i-1}, z, \omega) \tilde{N}((t_{i-1}, t_i] dz)$ are the Bochner integrals. The notation ' \int_0^{T+} ' means ' $\int_{(0,T]}$ '.

For any integer $0 \le k \le n$, let

$$M_k = \sum_{i=1}^k \int_Z f(t_{i-1},z,\omega) \tilde{N}((t_{i-1},t_i],dz)$$

then M_k is \mathcal{F}_{t_k} -measurable, $E[M_k]=0,\, E[I_T(f)]=E[M_n]=0$ and

$$E[M_{k}|\mathcal{F}_{t_{k-1}}] = E[(M_{k-1} + \int_{Z} f(t_{k-1}, z\omega)\tilde{N}((t_{k-1}, t_{k}], dz)|\mathcal{F}_{t_{k-1}}]$$

$$= M_{k-1} + E[\int_{Z} f(t_{k-1}, z, \omega)\tilde{N}((t_{k-1}, t_{k}], dz)|\mathcal{F}_{t_{k-1}}]$$

$$= M_{k-1} + \int_{Z} f(t_{k-1}, z, \omega)E[\tilde{N}((t_{k-1}, t_{k}], dz)] = M_{k-1}.$$

For any $t \in (0,T]$, define

(3.8)
$$J_{t}(f) = \int_{0}^{t+} \int_{Z} f(s-,z,\omega) N(dzds) \\ := \sum_{i=1}^{n} \int_{Z} f(t_{i-1},z,\omega) N((t_{i-1} \wedge t,t_{i} \wedge t],dz),$$

and

(3.9)
$$I_t(f) = \int_0^{t+} \int_Z f(s-,z,\omega) \tilde{N}(dzds)$$
$$:= \sum_{i=1}^n \int_Z f(t_{i-1},z,\omega) \tilde{N}((t_{i-1} \wedge t, t_i \wedge t], dz).$$

LEMMA 3.4. ([31]) For any $f \in \mathbb{S}$, both $\{I_t(f)\}$ and $\{J_t(f)\}$ are \mathcal{F}_t -adapted integrable processes. Moreover, $\{I_t(f)\}$ is an X-valued right continuous martingale. And for any $t \in (0,T]$,

(3.10)
$$E[\int_0^{t+} \int_Z f(s-,z,\omega) \tilde{N}(dsdz)] = 0,$$

$$(3.11) E[\int_0^{t+} \int_Z f(s-,z,\omega)N(dsdz)] = \int_0^{t+} \int_Z E[f(s-,z,\omega)]ds\nu(dz),$$

In order to extend the integrand from the step function which belongs to S to a more general case (belongs to \mathcal{L}), it is necessary to add some assumption in the Banach space X. Now we assume X is of M-type 2 below.

DEFINITION 3.5. ([5]) A Banach space $(X, \|\cdot\|)$ is called M-type 2 if and only if there exists a constant $C_X > 0$ such that for any X-valued martingale $\{\mathbf{M_k}\}$, it holds that

(3.12)
$$\sup_{k} E[\|\mathbf{M}_{k}\|^{2}] \leq C_{X} \sum_{k} E[\|\mathbf{M}_{k} - \mathbf{M}_{k-1}\|^{2}].$$

THEOREM 3.6. ([31]) Let X be of M-type 2 and $(Z, \mathcal{B}(Z))$ a separable Banach space with finite measure ν . Let \mathbf{p} be a stationary Poisson process with the characteristic measure ν and let f be in \mathbb{S} . Then there exists a constant C such that

(3.13)
$$E\left[\sup_{0< s \le t} \left\| \int_0^{s+} \int_Z f(\tau -, z, \omega) \tilde{N}(d\tau dz) \right\|^2 \right] \\ \le C \int_0^t \int_Z E[\|f(s, z, \omega)\|^2] ds \nu(dz),$$

and

(3.14)
$$E\left[\sup_{0 < s \le t} \left\| \int_0^{s+} \int_Z f(\tau -, z, \omega) N(d\tau dz) \right\|^2 \right] \\ \le C \int_0^t \int_Z E[\|f(s, z, \omega)\|^2] ds \nu(dz),$$

where C depends on the constant C_X in Definition 3.5.

LEMMA 3.7. ([31]) \mathbb{S} is dense in \mathscr{L} with respect to the norm $\|\cdot\|_{\mathscr{L}}$.

By Lemma 3.7, for any $f \in \mathcal{L}$, there exist a sequence $\{f^n : n \in \mathbb{N}\}$ in \mathbb{S} such that $\{f^n\}$ converges to f with respect to $\|\cdot\|_{\mathscr{L}}$ and the sequence

$$\Big\{\int_0^{t+}\int_Z f^n(s-,z,\omega)\tilde{N}(dsdz), n\in\mathbb{N}\Big\}$$

converges to a limit in L^2 -sense. We denote the limit by

$$I_t(f) = \int_0^{t+} \int_Z f(s-,z,\omega) \tilde{N}(dsdz),$$

which is called the *stochastic integral of* f with respect to the compensated Poisson random measure $\tilde{N}(dsdz)$. Similarly, we can define the *stochastic integral of* f with respect to the Poisson random measure N(dsdz), denoted by

$$J_t(f) = \int_0^{t+} \int_Z f(s-,z,\omega) N(dsdz).$$

Similarly, for any 0 < s < t < T,

$$\int_{s}^{t} \int_{Z} f(\tau-,z,\omega) \tilde{N}_{\mathbf{p}}(d\tau dz)$$

and

$$\int_s^t \int_Z f(\tau-,z,\omega) N(d\tau dz)$$

can be well defined.

REMARK 3.8. When the measure ν is finite, for any $U \in \mathcal{B}(Z)$, the processes $\{N(t,U)\}$ and $\{\tilde{N}(t,U)\}$ are both of finite variation a.s. Then the stochastic integrals coincide with the Lebesgue-Stieltjes integrals.

COROLLARY 3.9. ([31]) Let X be of M-type 2 and $(Z, \mathcal{B}(Z))$ a separable Banach space with finite measure ν . Let \mathbf{p} be a stationary Poisson process with the characteristic measure ν and let f be in \mathcal{L} . Then there exists a constant C such that

(3.15)
$$E\left[\sup_{0 < s \le t} \left\| \int_0^{s+} \int_Z f(\tau -, z, \omega) \tilde{N}(d\tau dz) \right\|^2 \right] \\ \le C \int_0^t \int_Z E[\|f(s, z, \omega)\|^2] ds \nu(dz),$$

and

(3.16)
$$E\left[\sup_{0< s \leq t} \left\| \int_{0}^{s+} \int_{Z} f(\tau -, z, \omega) N(d\tau dz) \right\|^{2}\right]$$
$$\leq C \int_{0}^{t} \int_{Z} E[\|f(s, z, \omega)\|^{2}] ds \nu(dz),$$

where C depends on the constant C_X in Definition 3.5.

COROLLARY 3.10. ([31]) For any $f \in \mathcal{L}$, both $\{I_t(f)\}$ and $\{J_t(f)\}$ are \mathcal{F}_t -adapted square-integrable processes. Moreover, $\{I_t(f)\}$ is an X-valued right continuous martingale. And for any $t \in (0,T]$,

(3.17)
$$E[\int_0^{t+} \int_Z f(s-,z,\omega) \tilde{N}(dsdz)] = 0,$$

$$(3.18) \hspace{1cm} E[\int_0^{t+} \int_Z f(s-,z,\omega) N(dsdz)] = \int_0^t \int_Z E[f(s,z,\omega)] ds \nu(dz),$$

3.2. Set-Valued Stochastic Integrals w.r.t. Poisson Point Processes. A set-valued stochastic process $F = \{F_t\} : [0,T] \times Z \times \Omega \to \mathbf{K}(X)$ is called \mathscr{S} -predictable if $F(z,t,\omega)$ is $\mathscr{S}/\sigma(\mathcal{C})$ -measurable.

Set

$$\mathcal{M} = \left\{ F(t,z,\omega) : F \ is \ \mathscr{S}-predictable \ and
ight. \ \left. E\left[\int_0^T \int_Z \|F(t,z,\omega)\|_{\mathbf{K}}^2 dt
u(dz)
ight] < \infty
ight\}$$

Given a set-valued stochastic process $\{F(t,z,\omega)\}$, the X-valued stochastic process $\{f(t,z,\omega)\}$ is called an \mathscr{S} -selection if $f(t,z,\omega) \in F(t,z,\omega)$ for all (t,z,ω) and $f \in \mathscr{S}$. By Proposition ??, for $F \in \mathscr{M}$, the \mathscr{S} -selection exists and satisfies $E\left[\int_0^T \int_Z \|f(t,z,\omega)\|^2 dt \nu(dz)\right] < \infty$ since

$$E\Big[\int_0^T \int_Z \|f(t,z,\omega)\|^2 dt \nu(dz)\Big] \leq E\Big[\int_0^T \int_Z \|F(t,z,\omega)\|_{\mathbf{K}}^2 dt \nu(dz)\Big] < \infty,$$

which means $f \in \mathcal{L}$. The family of all f which belongs to \mathcal{L} and satisfies $f(t, z, \omega) \in F(t, z, \omega)$ for a.e. (t, z, ω) is denoted by S(F), that is

$$S(F) = \{ f \in \mathcal{L} : f(t, z, \omega) \in F(t, z, \omega) \text{ for a.e. } (t, z, \omega) \}.$$

Set

$$ilde{\Gamma}_t := \{ \int_0^{t+} \int_Z f(s-,z,\omega) ilde{N}(dsdz) : (f(t))_{t \in [0,T]} \in S(F) \},$$
 $\Gamma_t := \{ \int_0^t \int_Z f(s-,z,\omega) N(dsdz) : (f(t))_{t \in [0,T]} \in S(F) \}.$

REMARK 3.11. It is easy to see for any $t \in [0, T]$, $\tilde{\Gamma}_t$ and Γ_t are the subsets of $L^2[\Omega, \mathcal{F}_t, P; X]$. Furthermore, if $\{F_t, \mathcal{F}_t : t \in [0, T]\}$ is convex, then so are $\tilde{\Gamma}_t$ and Γ_t .

Let $de\tilde{\Gamma}_t$ (resp. $de\Gamma_t$) denote the decomposable set of $\tilde{\Gamma}_t$ (resp. Γ_t) with respect to \mathcal{F}_t , $\overline{de}\tilde{\Gamma}_t$ (resp. $\overline{de}\Gamma_t$) the decomposable closed hull of $\tilde{\Gamma}_t$ (resp. Γ_t) with respect to \mathcal{F}_t , where the closure is taken in $L^1(\Omega,X)$. That is to say, for any $g\in \overline{de}\tilde{\Gamma}_t$ (resp. $\overline{de}\Gamma_t$) and any given $\epsilon>0$, there exists a finite \mathcal{F}_t -measurable partition $\{A_1,...,A_m\}$ of Ω and $(f^1(t))_{t\in[0,T]},...,(f^m(t))_{t\in[0,T]}\in S(F)$ such that

$$\begin{split} \|g - \sum_{k=1}^m \chi_{A_k} \int_0^{t+} \int_Z f^k(s-,z,\omega) \tilde{N}(dsdz) \|_{L^1} < \epsilon. \\ (resp. \ \|g - \sum_{k=1}^m \chi_{A_k} \int_0^{t+} \int_Z f^k(s-,z,\omega) N(dsdz) \|_{L^1} < \epsilon) \end{split}$$

Similar to Theorem 4.1 in [32], we have

THEOREM 3.12. Let $\{F_t, \mathcal{F}_t : t \in [0,T]\} \in \mathcal{M}$, then for any $t \in [0,T]$, $\overline{de}\Gamma_t \subset L^1(\Omega, \mathcal{F}_t, P; X)$. Moreover, there exists a set-valued random variable $J_t(F) \in \mathcal{M}(\Omega, \mathcal{F}_t, P; \mathbf{K}(X))$ such that $S^1_{J_t(F)}(\mathcal{F}_t) = \overline{de}\Gamma_t$. Similarly, there exists a set-valued random variable $I_t(F) \in \mathcal{M}(\Omega, \mathcal{F}_t, P; \mathbf{K}(X))$ such that $S^1_{I_t(F)}(\mathcal{F}_t) = \overline{de}\tilde{\Gamma}_t$. If F is convex, then so are $S^1_{I_t(F)}(\mathcal{F}_t)$ and $S^1_{J_t(F)}(\mathcal{F}_t)$.

DEFINITION 3.13. The set-valued stochastic processes $(J_t(F))_{t \in [0,T]}$ and $(I_t(F))_{t \in [0,T]}$ defined as above are called the stochastic integrals of $\{F_t, \mathcal{F}_t : t \in [0,T]\} \in \mathscr{M}$ with respect to the Poisson random measure N(ds,dz) and the compensated random measure $\tilde{N}(dsdz)$ respectively. For each t, we denote $I_t(F) = \int_0^{t+} \int_Z F(s-,z,\omega) \tilde{N}(dsdz)$, $J_t(F) = \int_0^{t+} \int_Z F(s-,z,\omega) N(dsdz)$. Similarly, for 0 < s < t, we also can define the set-valued random variable $I_{s,t}(F) = \int_s^t \int_Z F(\tau-,z,\omega) \tilde{N}(d\tau dz)$, $J_{s,t}(F) = \int_s^t \int_Z F(\tau-,z,\omega) N(d\tau dz)$.

For brevity, the integral $\int_0^{t+} \int_Z h(s-,z,\omega) \tilde{N}(dsdz)$ $(\int_0^{t+} \int_Z h(s-,z,\omega) \tilde{N}(dsdz))$ also will be denoted by $\int_0^{t+} \int_Z h_{s-} \tilde{N}(dsdz)$ $(\int_0^{t+} \int_Z h_{s-} \tilde{N}(dsdz))$ resp.), where h is an X-valued or $\mathbf{K}(\mathbf{X})$ -valued integrand.

PROPOSITION 3.14. ([38]) Assume set-valued stochastic processes $\{F_t, \mathcal{F}_t : t \in [0,T]\}$ and $\{G_t, \mathcal{F}_t : t \in [0,T]\} \in \mathcal{M}$. Then

$$J_t(F+G) = cl\{J_t(F) + J_t(G)\}$$
 a.s and $I_t(F+G) = cl\{I_t(F) + I_t(G)\}$ a.s.,

where the cl stands for the closure in X.

THEOREM 3.15. ([31]) Assume a set-valued stochastic process $\{F_t, \mathcal{F}_t : t \in [0,T]\} \in \mathcal{M}$. Then $\{J_t(F)\}$ and $\{I_t(F)\}$ are integrably bounded.

THEOREM 3.16. ([31, 38]) Let a convex set-valued stochastic process $\{F_t, \mathcal{F}_t : t \in [0, T]\} \in \mathcal{M}$, then the stochastic integral $\{I_t(F), \mathcal{F}_t : t \in [0, T]\}$ is a set-valued submartingale but not a set-valued martingale.

REMARK 3.17. With the assumption of \mathcal{F} being separable with respect to the probability measure P, Theorem 3.7 in [31] pointed out that the integral $\{I_t(F)\}$ is a set-valued martingale. But unfortunately, now we found there is a gap in the proof. In fact, $\{I_t(F)\}$ is not a set-valued martingale except for special case (the singletons). The counterexample and rigorous proof are given in [38].

THEOREM 3.18. ([38]) Assume a set-valued stochastic process $\{F_t, \mathcal{F}_t : t \in [0,T]\} \in \mathcal{M}$. Then both $\{J_t(F)\}$ and $\{I_t(F)\}$ are L^2 -integrably bounded.

THEOREM 3.19. ([31])(Castaing representation of set-valued stochastic integral) Assume $\mathcal F$ is separable with respect to the probability measure P. Then for a set-valued stochastic process $\{F_t, \mathcal F_t : t \in [0,T]\} \in \mathcal M$, there exists a sequence $\{(f_t^i)_{t \in [0,T]} : i=1,2,...\} \subset S(F)$ such that for each $t \in [0,T], z \in Z$, $F(t,z,\omega) = cl\{(f_t^i(z,\omega)) : i=1,2,...\}$ a.s., and

$$I_t(F)(\omega)=cl\{\int_0^{t+}\int_Z f^i_{s-}(z,\omega) ilde{N}(dsdz)(\omega):i=1,2,...\} \ a.s.$$

and

$$J_t(F)(\omega)=cl\{\int_0^{t+}\int_Z f^i_{s-}(z,\omega)N(dsdz)(\omega):i=1,2,...\} \ a.s.$$

THEOREM 3.20. ([38]) Assume \mathcal{F} is separable with respect to P. Let $\{F_t\}_{t\in[0,T]}$ and $\{G_t\}_{t\in[0,T]}$ be set-valued stochastic processes in \mathcal{M} . Then for all t, it follows that

$$(3.19) \qquad E\left[H\left(\int_{0}^{t+}\int_{Z}F(s-,z,\omega)N(dsdz),\int_{0}^{t+}\int_{Z}G(s-,z,\omega)N(dsdz)\right)\right] \\ \leq E\left[\int_{0}^{t+}\int_{Z}H(F(s-,z,\omega),G(s-,z,\omega))N(dsdz)\right] \\ = E\left[\int_{0}^{t}\int_{Z}H(F(s,z,\omega),G(s,z,\omega))ds\nu dz\right]$$

and

$$(3.20) \qquad E\left[H^{2}\left(\int_{0}^{t+}\int_{Z}F(s-,z,\omega)N(dsdz),\int_{0}^{t+}\int_{Z}G(s-,z,\omega)N(dsdz)\right)\right]$$

$$\leq CE\left[\int_{0}^{t+}\int_{Z}H^{2}(F(s-,z,\omega),G(s-,z,\omega))N(dsdz)\right]$$

$$= CE\left[\int_{0}^{t}\int_{Z}H^{2}(F(s,z,\omega),G(s,z,\omega))ds\nu(dz)\right]$$

where C is the constant appearing in Corollary 3.9.

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